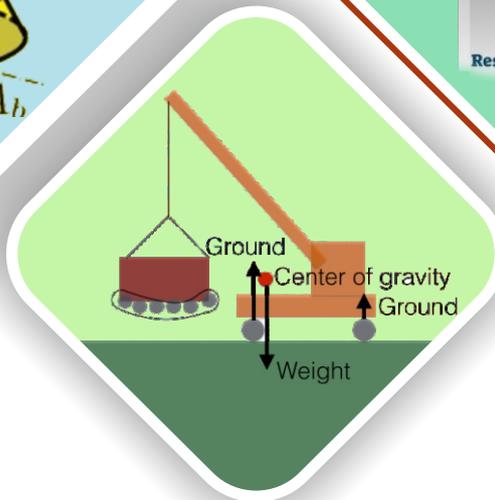
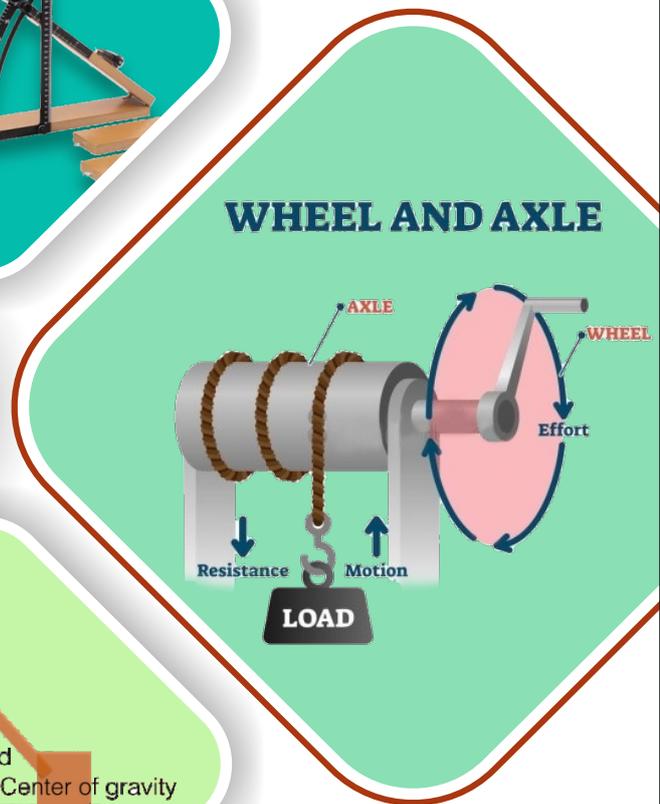
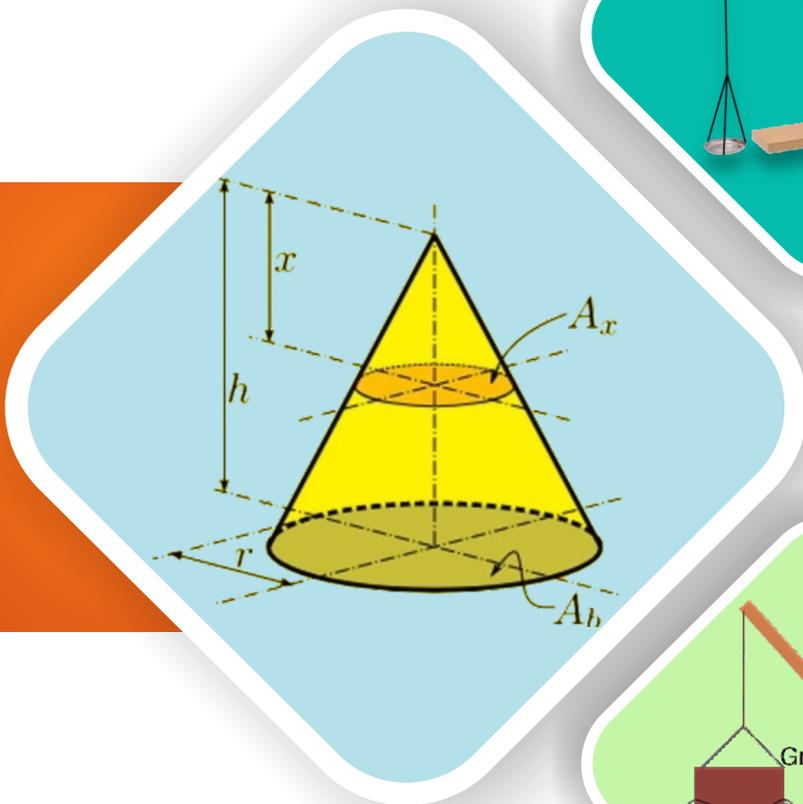


SCHEME : K

Name : _____
Roll No. : _____ Year : 20__ 20__
Exam Seat No. : _____

LABORATORY MANUAL FOR ENGINEERING MECHANICS (312312)



CE/CH/ME ENGINEERING GROUP



**MAHARASHTRA STATE BOARD OF
TECHNICAL EDUCATION, MUMBAI
(Autonomous) (ISO 9001: 2015) (ISO/IEC 27001:2013)**

VISION:

To ensure that the Diploma level Technical Education constantly matches the latest requirements of Technology and industry and includes the all-round personal development of students including social concerns and to become globally competitive, technology led organization.

MISSION:

To provide high quality technical and managerial manpower, information and consultancy services to the industry and community to enable the industry and community to face the challenging technological & environmental challenges.

QUALITY POLICY:

We, at MSBTE are committed to offer the best in class academic services to the students and institutes to enhance the delight of industry and society. This will be achieved through continual improvement in management practices adopted in the process of curriculum design, development, implementation, evaluation and monitoring system along with adequate faculty development programmes.

CORE VALUES:

MSBTE believes in the following:

- Skill development in line with industry requirements
- Industry readiness and improved employability of Diploma holders
- Synergistic relationship with industry
- Collective and Cooperative development of all stake holders
- Technological interventions in societal development
- Access to uniform quality technical education

**A Laboratory Manual
For
Engineering Mechanics**

(312312)

SEMESER-II

“K-SCHEME”

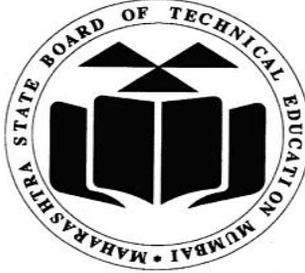
(AE/AL/CE/CH/CR/CS/LE/ME/MK/PG)



**Maharashtra State
Board of Technical Education, Mumbai.
(Autonomous) (ISO: 9001: 2015) (ISO/IEC 27001:2013)**



Maharashtra State Board of Technical Education, Mumbai
(Autonomous) (ISO: 9001: 2015) (ISO/IEC 27001:2013)
4th Floor, Government Polytechnic Building, 49, Kherwadi,
Bandra (East), Mumbai – 400051,
(Printed On _____, 2024)



**Maharashtra State
Board of Technical Education, Mumbai.**

Certificate

This is to certify that Mr. / Ms.

Roll No.....of Second semester of Diploma in

.....of

institute,.....

.....(Code:.....)has completed

the term work satisfactorily in course **Engineering Mechanics(312312)** for the

academic year 20..... to 20..... as prescribed in Curriculum.

Place:

Enrollment No:

Date:

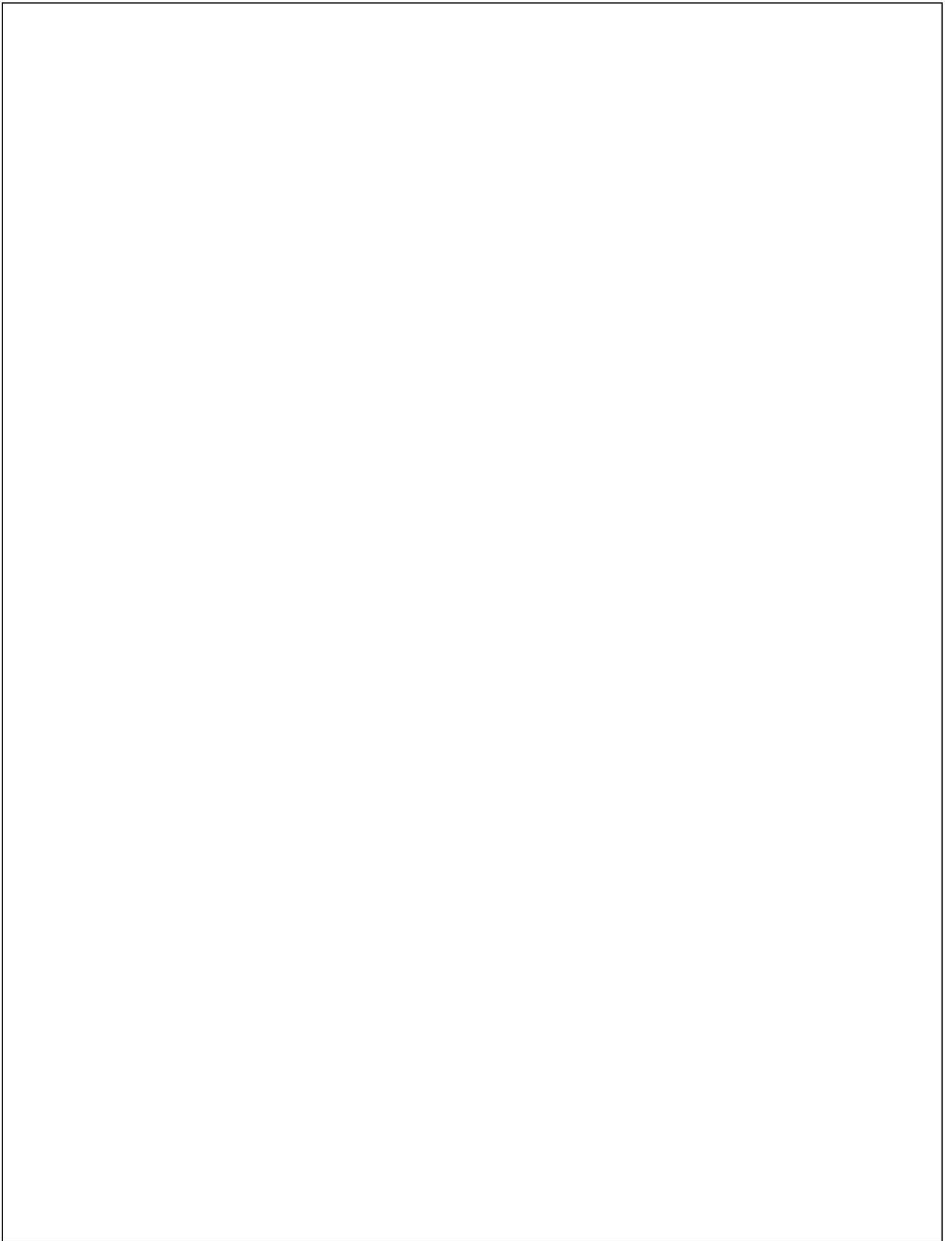
Exam. Seat No:

Subject teacher

Head of the Department

Principal





PREFACE

The development of the critically important industry-relevant abilities and skills is the main goal of any engineering laboratory or field work in the technical education system. In light of this, MSBTE developed the most recent "K" Scheme curricula for engineering diploma programs, emphasizing outcome-based learning. As a result, a sizable portion of the program is dedicated to practical work. This demonstrates how crucial laboratory work is in helping teachers, instructors, and students understand that every minute of lab time must be used efficiently to create these outcomes rather than wasting it on unnecessary activities. Every practical has thus been created to operate as a "vehicle" to help each student acquire this industry-identified capability in order to ensure the effective implementation of this outcome-based curriculum. The "chalk and duster" practice in the classroom is a challenging way to build practical skills. As a result, the development team of the "K" scheme laboratory manual focused on the intended results when creating the practicals, as opposed to the customary approach of performing practicals to "verify the theory".

This lab manual is intended to support all parties involved, particularly the students, instructors, and teachers, in helping the students achieve the pre-established goals. It is required of every student to read through the relevant practical process in its entirety and comprehend the bare minimum of theoretical background related to the practical at least one day in advance of the practical. As a crucial starting point for carrying out the practical, each exercise in this handbook starts with establishing the competency, industry-relevant skills, course outcomes, and practical results. After that, the students will learn about the abilities they will acquire through the process outlined there and the safety measures that must be followed, which will enable them to use in addressing real-world situations in their professional life. This manual also offers guidance to educators on how to manage resources so that students follow protocols and safety measures methodically and meet learning objectives. This allows teachers and instructors to effectively support student-centered lab activities through each practical exercise.

Machines play an important role in many aspects of our lives, making many tasks easier and more efficient. For example, machines are used in lift, crane. In same way globally we come across different types of structure created for different purpose and function. While designing the machine or structure analysis of forces and stresses is an important and prerequisite step. Correct analysis is possible only when one knows the types and effect of force acting on the structure. This course provides the scope to understand fundamental concepts of law of machines and their application to different engineering problems. This course is designed to provide basic understanding about different types of forces, moments and their effects on structural elements, which will analyses different structural systems.

Although best possible care has been taken to check for errors (if any) in this laboratory manual, perfection may elude us as this is the first edition of this manual. Any errors and suggestions for improvement are solicited and highly welcome.

Programme outcome (POs) to be achieved through Practical

PO 1. Basic & Discipline specific knowledge: Apply knowledge of basic mathematics, sciences and engineering fundamentals and engineering specialization to solve the engineering problems.

PO 2 Problem Analysis: Identify and analyze well defined engineering problems using codified standard methods.

PO 3. Design /Development Solutions: Design solutions for well-defined technical problems and assist with the design of systems components or processes to meet specified needs.

PO 4. Engineering tools experimentation and testing: Apply modern engineering tools and appropriate technique to conduct standard tests and measurements.

PO 5. Engineering practices for society sustainability and environment: Apply appropriate technology in context of society, sustainability, environment and ethical practices.

PO 6. Project Management: Use engineering management principles individually, as a team member or a leader to manage projects and effectively communicate about well-defined engineering activities.

PO 7. Lifelong learning: Ability to analyze individual needs and engage in updating in context of technological changes.

Practical Course outcome matrix:

- CO1 - Select the suitable machine under given loading condition.
- CO2 - Analyze the given force system to calculate resultant force.
- CO3 - Determine unknown force(s) of given load combinations in the given situation.
- CO4 - Apply the laws of friction in the given situation.
- CO5 - Determine the centroid/centre of gravity of the given structural elements of having specific shape and size.

Pr. No.	Title of the Practical	Mapped Course Outcome				
		CO 01	CO 02	CO 03	CO 04	CO 05
01	Collect the photographic information of Indian Knowledge System (IKS) given in various units	√	√	--	--	√
02	*Determine mechanical advantage and velocity ratio of differential axle and wheel for different load and efforts.	√	--	--	--	--
03	Determine mechanical advantage and velocity ratio of worm and worm wheel for different load and efforts.	√	--	--	--	--
04	Determine mechanical advantage and velocity ratio of single purchase crab winch for different load and efforts.	√	--	--	--	--
05	Determine mechanical advantage and velocity ratio of double purchase crab winch for different load and efforts	√	--	--	--	--
06	*Determine mechanical advantage and velocity ratio of simple screw jack for different load and efforts.	√	--	--	--	--
07	Determine mechanical advantage and velocity ratio of Weston's differential pulley block for different load and efforts.	√	--	--	--	--
08	Determine mechanical advantage and velocity ratio of geared pulley block for different load and efforts.	√	--	--	--	--
09	Determine mechanical advantage and velocity ratio of two sheave pulley block for different load and efforts.	√	--	--	--	--
10	Determine mechanical advantage and velocity ratio of three sheave pulley block for different load and efforts.	√	--	--	--	--
11	*Verify law of polygon of forces using Universal force table for given forces.	--	√	--	--	--
12	*Verify law of moment of forces using law of moment apparatus for given forces.	--	√	--	--	--
13	Verify Varignon's theorem of moments of forces using law of moment apparatus for given forces.	--	√	--	--	--
14	Determine graphically the resultant force of given concurrent force system.	--	√	--	--	--
15	Determine graphically the resultant force of given parallel force system	--	√	--	--	--
16	*Verify the Lami's theorem using Universal force table apparatus for given forces.	--	--	√	--	--
17	*Determine support reactions of simply supported beam using parallel force or beam reaction apparatus for given	--	--	√	--	--

	vertical forces.					
18	*Determine coefficient of friction using friction apparatus for given block on horizontal plane.	--	--	--	√	--
19	Determine coefficient of friction using friction apparatus for given block on inclined plane.	--	--	--	√	--
20	*Verify centroid of plane figure of given dimensions by making simple paper model.	--	--	--	--	√

List of Relevant Skills

On the successful completion of the course the students will acquire the required industry relevant skills and they will be able to:

1. Select the suitable machine under given loading condition.
2. Apply the principles of engineering mechanics to find resultant of concurrent, parallel forces acting on structure.
3. Apply the principles of Lami's theorem to find tension in string in three coplanar, concurrent forces.
4. Find support reactions of beam which further use for analysis of beam.
5. Apply the principles of friction in various conditions for useful purpose.
6. Find the centroid and centre of gravity of various components in engineering systems.

Guidelines to teachers

1. Teacher should provide the guideline with demonstration of practical to the students with all features.
2. Teacher shall explain prior concepts to the students before starting of each practical.
3. Involve students in performance of each practical.
4. Teacher should ensure that the respective skills and competencies are developed in the students after the completion of the practical exercise.
5. Teachers should give opportunity to students for hands on experience after the demonstration.
6. Teacher is expected to share the skills and competencies to be developed in the students.
7. Teacher may provide additional knowledge and skills to the students even though not covered in the manual but are expected the students by the industry.
8. Finally give practical assignment and assess the performance of students based on task assigned to check whether it is as per the instructions.

Instructions to Students

1. Organize the work in the group and make record all programs.
2. Students shall develop maintenance skill as expected by industries.
3. Student shall attempt to develop related hand-on skills and gain confidence.
4. Student shall develop the habits of evolving more ideas, innovations, skills etc. those included in scope of manual
5. Student shall refer technical magazines.
6. Student should develop habit to submit the practical's on date and time.
7. Student should well prepare while submitting write-up of exercise.
8. Attach /paste separate papers wherever necessary.

INDEX

List of Practical's and Formative Assessment sheet.

Pr. No.	Title of the Practical	Page No.	Date of performance	Date of Submission	Assessment marks	Dated sign of teacher	Remarks (if any)
01	Collect the photographic information of Indian Knowledge System (IKS) given in various units						
02	*Determine mechanical advantage and velocity ratio of differential axle and wheel for different load and efforts.						
03	Determine mechanical advantage and velocity ratio of worm and worm wheel for different load and efforts.						
04	Determine mechanical advantage and velocity ratio of single purchase crab winch for different load and efforts.						
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08	Determine mechanical advantage and velocity ratio of geared pulley block for different load and efforts.						
09	Determine mechanical advantage and velocity ratio of two sheave pulley block for different load and efforts.						
10	Determine mechanical advantage and velocity ratio of three sheave pulley block for different load and efforts.						

11	*Verify law of polygon of forces using Universal force table for given forces.						
12	*Verify law of moment of forces using law of moment apparatus for given forces.						
13	Verify Varignon's theorem of moments of forces using law of moment apparatus for given forces.						
14	Determine graphically the resultant force of given concurrent force system.						
15	Determine graphically the resultant force of given parallel force system						
16	*Verify the Lamis theorem using Universal force table apparatus for given forces.						
17	*Determine support reactions of simply supported beam using parallel force or beam reaction apparatus for given vertical forces.						
18	*Determine coefficient of friction using friction apparatus for given block on horizontal plane.						
19	Determine coefficient of friction using friction apparatus for given block on inclined plane.						
20	*Verify centroid of plane figure of given dimensions by making simple paper model.						

Total marks :			
Total marks (obtained):			
Average marks (out of 25):			
Sign of Subject Teacher:			

Practical No. 1: Collect the photographic information of Indian Knowledge System (IKS) given in various units

I. Practical Significance

Indian Knowledge Systems (IKS) will actively engage for spreading the traditional knowledge in the field of Engineering & Technology.

II. Industry / Employer Expected outcomes

Apply the principles of engineering mechanics to analyze, design and automation the prototypes and equipment's of various industries.

III Course Level Learning Outcome(s)

CO1 Select the suitable machine under given loading condition.

CO2 Analyze the given force system to calculate resultant force.

CO5 Determine the centroid/center of gravity of gravity of the given structural elements of having specific shape and size.

IV Laboratory Learning Outcome(s)

LLO 1.1 Verify law of machine under the given condition.

LLO 1.2 Verify law of moment of forces.

LLO 1.3 Understand the centroid of structural component.

V Relevant Affective Domain related Outcome (s)

Follow safety practices

VI Relevant Theoretical Background

The Indian Knowledge Systems comprise of Jnan, Vignan, and Jeevan Darshan that have evolved out of experience, observation, experimentation, and rigorous analysis. This tradition of validating and putting into practice has impacted our education, arts, administration, law, justice, health, manufacturing, and commerce.

VII Required Recourses/Apparatus/Equipment with specifications

Sr. No.	Particulars	Specifications	Quantity	Remarks (If Any)
1.				
2.				
3.				
4.				

VIII Precautions to be followed

.....

IX Procedure

1. Study the IKS system.
2. Identify various IKS given in various units
3. Student will collect the photographic information of given IKS.

X Observations and Calculations

Identify different IKS in the various units and collect its photographic information.

XI Observations Table

Sr. No.	Unit Name/Instrument Name	Related Photographic Information
1.	Unit - I Simple Lifting Machine Hand axe as wedge	
2.	Unit - I Simple Lifting Machine Lever in battle, Inclined Plane for loading	
3.	Unit - I Simple Lifting Machine Pulleys to lift water in irrigation	
4.	Unit - II Analysis of Forces Weighing scale in Mohenjodaro, Harappa	
5.	Unit - V Centroid and Centre of Gravity Archery arrowheads in Ramayana	

6.	Unit - V Centroid and Centre of Gravity Arch in archaeological structures such as Mahal, Gol Gumbaz	
----	---	--

XII Results

.....

XIII Interpretation of results

.....

XIV Conclusions and Recommendations

.....

XV Practical Related Questions

Note: Below given are few sample questions for reference. Teachers must design more such questions so as to ensure the achievement of identified CO. Write answers of minimum three questions.

1. What is IKS?
2. Explain Hand axe as wedge
3. Discuss about Pulleys to lift water in irrigation
4. Explain weighing scale in Mohenjodaro, Harappa
5. Describe arch in archaeological structures such as Mahal, Gol Gumbaz

SPACE TO WRITE ANSWERS

.....

XVII Suggested Assessment Scheme

Performance Indicators		Weightage (%)
Process related: 15 Marks		60 %
1	Collect the basic information of Indian knowledge system.	20 %
2	Identify the IKS in Engineering Mechanics	20 %
3	Working in team.	20 %
Product related: 10 Marks		40 %
1	Collect the photographic information regarding IKS.	20 %
2	Answer to the practical related questions.	10 %
3	Submission of report in time.	10 %
Total: 25 Marks		100 %

List of Student team members.

1.
2.
3.
4.

Marks Obtained			Dated sign of Teacher
Process Related(15)	Product Related(10)	Total(25)	

Practical No. 2: Determine mechanical advantage and velocity ratio of differential axle and wheel for different load and efforts.

I. Practical Significance

There is often a need to lift loads and different lifting machines are used depending on the type of load, intensity of the load and other site conditions. Differential axle and wheel machines are used to lift smaller loads in confined spaces. After conducting this experiment, a graduate engineer will be able to assess the suitability of the differential axle and wheel based on the given load lifting situation.

II. Industry / Employer Expected Outcomes

Apply the principles of engineering mechanics to analyze, design and automation the prototypes and equipment's of various industries.

III. Course Level Learning Outcome(s)

CO1 Select the suitable machine under given loading condition.

IV. Laboratory Learning Outcome(s)

Verify law of machine under the given condition.

V. Relevant Affective Domain related Outcome (s)

- a. Follow safety practices and precautions
- b. Demonstrate working as a leader/ a team member.
- c. Maintain tools and equipment.

VI. Relevant Theoretical Background

Differential axle and wheel: It is different from simple axle and wheel machine because of its axle configuration. Instead of prismatic single axle in simple wheel and axle, step down axles is used in differential axle and wheel. This machine has a better mechanical advantage as compared to single axle and wheel. Two axles of different diameters are coaxially fitted with the spindle, with which a wheel is also coaxially attached. The effort is applied through a wrapped string wound around this wheel.

Another string is wound over two axles and carries load with the help of movable pulley. The rope on the wheel and smaller axle are wound in the same direction, whereas that on the larger axle is in opposite direction. When an effort is applied through the wheel, the rope on the wheel and smaller axle gets unwound but gets wound on the larger axle, thus lifting the load.

$$\begin{aligned} \text{Velocity Ratio} &= \frac{\text{Distance Traveled by Effort}}{\text{Distance Traveled by Load}} \\ &= \frac{\pi D}{\frac{\pi(d_1 - d_2)}{2}} = \frac{2D}{(d_1 - d_2)} \end{aligned}$$

Where,

D = Diameter of effort wheel
 d_1 = Diameter of larger axle
 d_2 = Diameter of smaller axle

VII. Actual Circuit diagram used in laboratory with equipment specifications

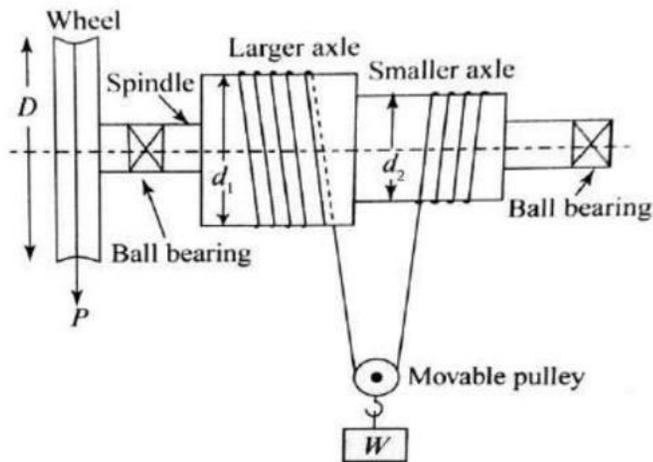


Fig: Differential Axle and Wheel

VIII. Required Recourses/Apparatus/Equipment with specifications

Sr. No.	Broad Specifications	Quantity	Remarks(If Any)
1	Differential Axle and Wheel	Differential Axle and wheel (wall mounted unit) with wheel of 40 cm diameter and axles are in steps of 20 cm and 10 cm reducing diameter	01 for Group of 4 to 5 students.

IX. Precautions to be followed

1. The reading must be taken and noted down carefully.
2. The load and effort should move slowly.
3. Effort must be applied gradually.
4. Any overlapping of the string must be avoided.
5. There should be no knot in the string.
6. Only light weights must be used during the course of experiment.

X. Procedure

1. Observe the machine carefully and identify the various components of machine.
2. Set the machine and check the reversibility of machine.
3. Calculate friction in the machine at zero load.
4. Apply the load starting with smaller magnitude.
5. Apply the effort for each corresponding load.
6. Record the observations of load and effort in observation table.

7. Take at least five readings.
8. Determine M.A., V.R., Efficiency, Ideal effort and Effort lost in friction,
9. Plot graphs viz. load against effort and load against efficiency.

XI. Observations and Calculations

$$VR = \frac{2D}{(d_1 - d_2)} =$$

1. $D = \dots\dots\dots mm$

2. $d_1 = \dots\dots\dots mm$

3. $d_2 = \dots\dots\dots mm$

XII. Observations Table

Sr. No.	Load W (N)	Effort P (N)	M.A.	Velocity Ratio	Efficiency η (%)	Ideal Effort P_i (N)	Effort Lost in Friction P_f (N)
1							
2							
3							
4							
5							

XIII. Sample Calculations

$$M.A. = \frac{\text{Load}}{\text{Effort}} = \frac{W}{P} =$$

$$\text{Efficiency}(\eta) = \frac{M.A.}{V.R.} \times 100\% =$$

$$P_i = \frac{W}{V.R.} =$$

$$P_f = P - P_i =$$

Law of machine is $P = mW + C$

Where,

$$m = \text{Slope} = \frac{P_2 - P_1}{W_2 - W_1} =$$

$C = Y$ intercept (i.e. Machine Friction) = _____N

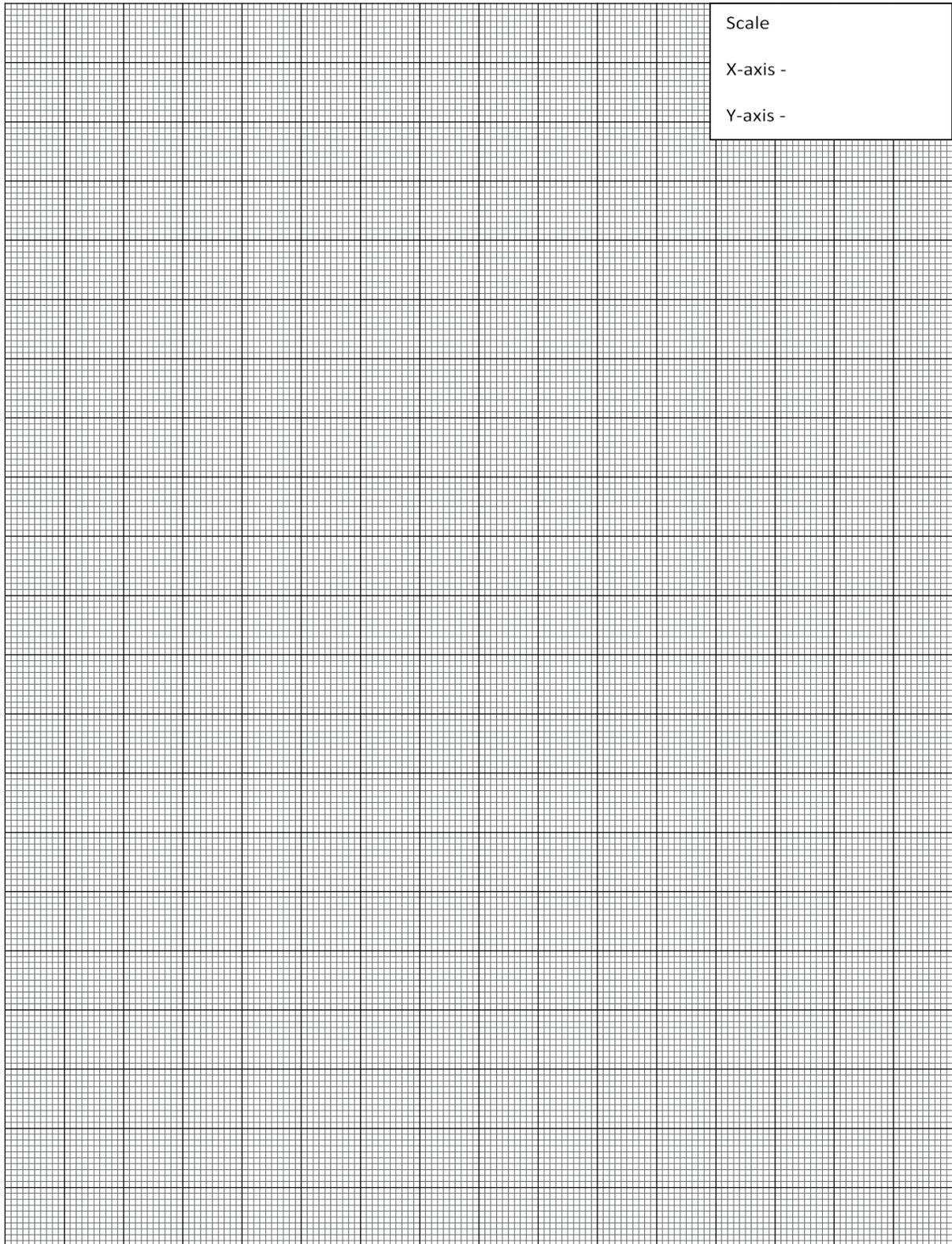
XIX. Suggested Assessment Scheme

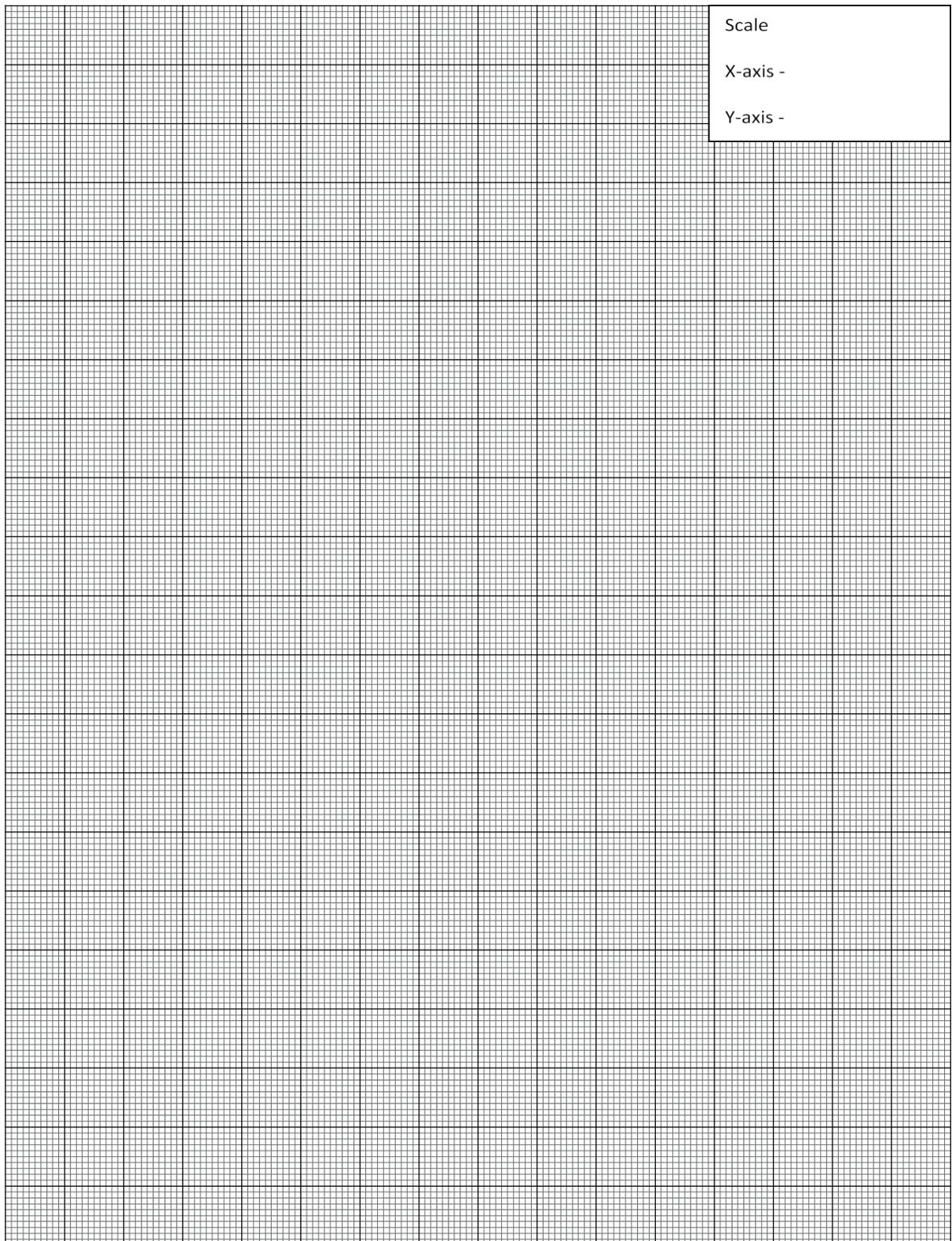
Performance Indicators		Weightage (%)
Process related: 15 Marks		60 %
1	Handling of the machine.	5 %
2	Determination of V. R. of machine.	10 %
3	Applying load and determine effort of machine.	20 %
4	Identify the type of machine i.e. reversible or self-locking.	10 %
5	Calculation of parameters concerned.	10 %
6	Working in team.	5 %
Product related: 10 Marks		40 %
1	Error estimation.	5 %
2	Interpretation of result and graph.	10 %
3	Conclusion and Recommendation.	10 %
4	Answer to the practical related questions.	10 %
5	Submission of report in time.	5 %
Total: 25 Marks		100 %

List of Student team members.

1.
2.
3.
4.

Marks Obtained			Dated sign of Teacher
Process Related(15)	Product Related(10)	Total(25)	





Practical No. 3: Determine mechanical advantage and velocity ratio of worm and worm wheel for different load and effort.**I. Practical Significance**

There is often a need to lift loads and different lifting machines are used depending on the type of load, intensity of the load and other site conditions. Worm and worm wheel machines are used for lifting heavy loads in confined spaces. After carrying out this experiment, a qualified engineer can assess the suitability of worms and worm wheels depending on the given lifting situation.

II. Industry / Employer Expected outcomes

Apply the principles of engineering mechanics to analyze, design and automation the prototypes and equipment's of various industries

III Course Level Learning Outcome(s)

CO1 Select the suitable machine under given loading condition.

IV Laboratory Learning Outcome(s)

Verify law of machine under the given condition.

V Relevant Affective Domain related Outcome (s)

- Follow safety practices and precautions
- Demonstrate working as a leader/ a team member.
- Maintain tools and equipment.

VI Relevant Theoretical Background

Worm and Worm Wheel: A worm is square-threaded screw and worm wheel is a toothed wheel. In this machine, a worm and worm wheel are geared together maintaining their axes at right angles to each other. An effort wheel or pulley is attached to the worm coaxially so that effort can be applied through a rope wound over the pulley. A load is securely mounted coaxially on worm wheel and load is connected with a separate rope wound around the load drum. For single rotation of effort wheel, effort traverses a distance= πD . For an n- threaded worm, worm pushes the worm wheel through one tooth during single rotation of effort wheel. If the total number of teeth in a worm wheel is T push of one tooth means the load drum traverses through (n/T) rotations. Thus, when the radius of load drum is r, distance moved by the load= $2 \pi r \times (n/T)$.

Therefore, the velocity ratio,
$$VR = \frac{\pi D}{2\pi r \left(\frac{n}{T}\right)} = \frac{DT}{2nr}$$

Where,

- D = Diameter of effort wheel
r = Radius of pulley
T = No. of teeth on the worm wheel

n = No. of thread on worm wheel.

VII Actual Circuit diagram used in laboratory with equipment specifications

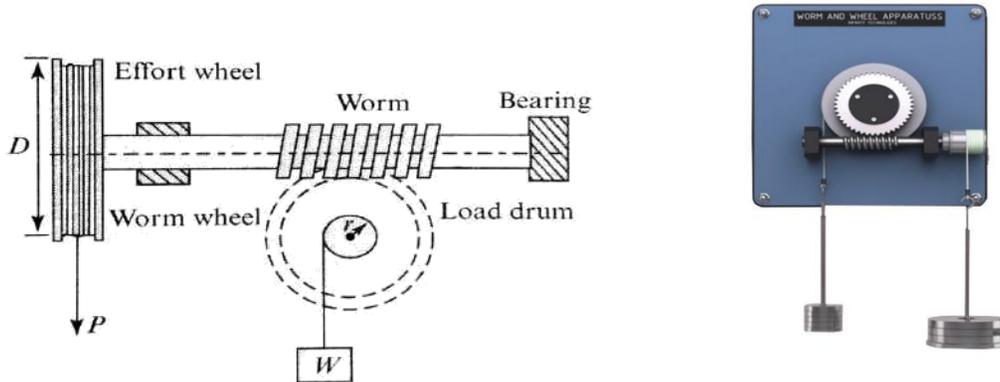


Fig: Worm and Worm Wheel

VIII Required Recourses/Apparatus/Equipment with specifications

Sr. No.	Particulars	Broad Specifications	Quantity	Remarks (If Any)
1.	Worm and Worm Wheel	Worm and worm wheel (wall Mounted Unit threaded spindle, load drum, effort wheel; with necessary slotted weights, hanger and thread).	01 for Group of 4 to 5 students.	

IX Precautions to be followed

1. The reading must be taken and noted down carefully.
2. The load and effort should move slowly.
3. Effort must be applied gradually.
4. Any overlapping of the string must be avoided.
5. There should be no knot in the string.
6. Only light weights must be used during the course of experiment.
7. Lubricate the screw before starting the experiment.

X Procedure

1. Observe the machine carefully and identify the various components of machine.
2. Set the machine and check the reversibility of machine.
3. Apply the load-on-load drum starting with smaller magnitude.
4. Apply the effort to the effort wheel for each corresponding load.
5. Record the observations of load and effort in observation table. Take at least five readings.
6. Measure the radius of the load drum and the radius of effort wheel.
7. Determine M.A., V.R., Efficiency, Ideal effort and Effort lost in friction,

8. Plot graphs viz. load against effort and load against efficiency.

XI Observations and Calculations

$$V. R. = \frac{DT}{2nr} =$$

1. D = mm
2. r = mm
3. T = No.
4. n = No.

XII Observations Table

Sr. No.	Load W (N)	Effort P (N)	M.A.	Velocity Ratio	Efficiency η (%)	Ideal Effort P_i (N)	Effort Lost in Friction P_f (N)
1							
2							
3							
4							
5							

XIII Sample Calculations

$$M.A. = \frac{\text{Load}}{\text{Effort}} = \frac{W}{P} =$$

$$\text{Efficiency}(\eta) = \frac{M.A.}{V.R.} \times 100\% =$$

$$P_i = \frac{W}{V.R.} =$$

$$P_f = P - P_i =$$

Law of machine is $P = mW + C$

Where,

$$m = \text{Slope} = \frac{P_2 - P_1}{W_2 - W_1} =$$

C = Y intercept (i.e. Machine Friction) = _____ N

XIV Results

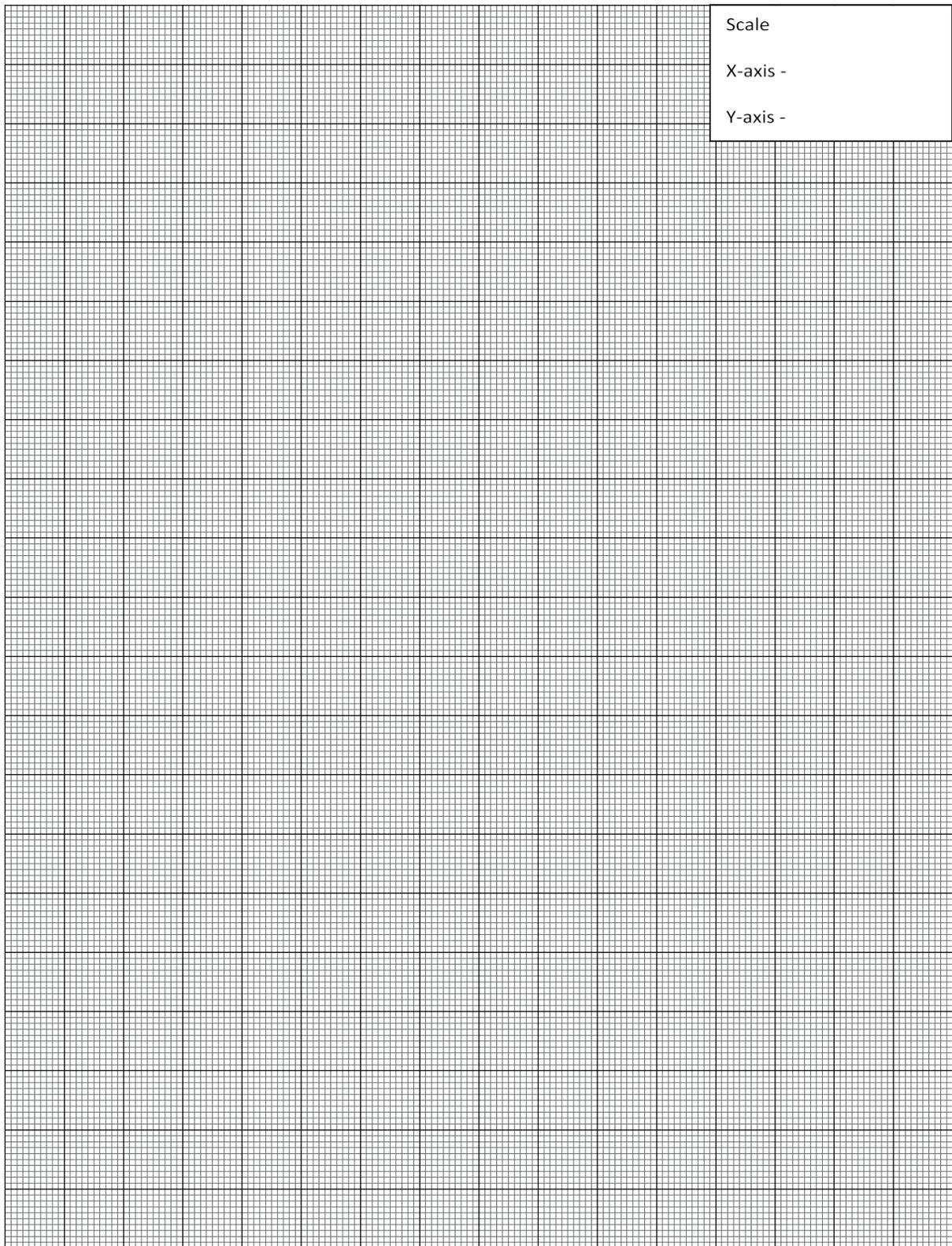
XIX Suggested Assessment Scheme

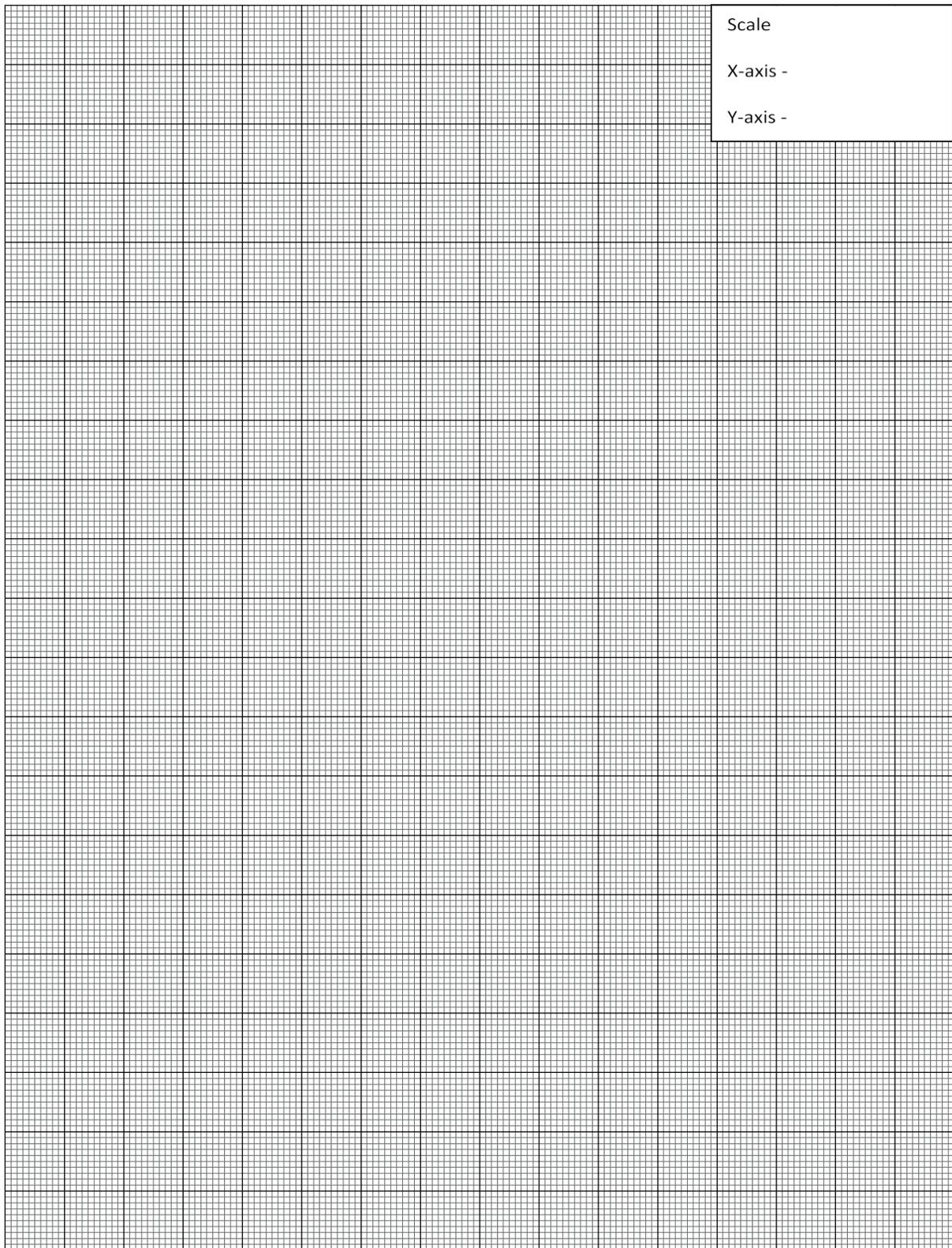
Performance Indicators		Weightage (%)
Process related: 15 Marks		60 %
1	Handling of the machine.	5 %
2	Determination of V. R. of machine.	10 %
3	Applying load and determine effort of machine.	20 %
4	Identify the type of machine i.e. reversible or self-locking.	10 %
5	Calculation of parameters concerned.	10 %
6	Working in team.	5 %
Product related: 10 Marks		40 %
1	Error estimation.	5 %
2	Interpretation of result and graph.	10 %
3	Conclusion and Recommendation.	10 %
4	Answer to the practical related questions.	10 %
5	Submission of report in time.	5 %
Total: 25 Marks		100 %

List of Student team members.

1.
2.
3.
4.

Marks Obtained			Dated sign of Teacher
Process Related(15)	Product Related(10)	Total(25)	





Practical No. 4: Determine mechanical advantage and velocity ratio of single purchase crab winch for different load and effort.

I. Practical Significance

There is often a need to lift loads and different lifting machines are used depending on the type of load, intensity of the load and other site conditions. The single purchase crab machine is used for lifting heavy loads in confined spaces. After carrying out this experiment, a qualified engineer can decide on the suitability of a single purchase crab based on the given lifting situation.

II. Industry / Employer Expected Outcomes

Apply the principles of engineering mechanics to analyze, design and automation the prototypes and equipment's of various industries

III Course Level Learning Outcome(s)

CO1 Select the suitable machine under given loading condition.

IV Laboratory Learning Outcome(s)

Verify law of machine under the given condition.

V Relevant Affective Domain related Outcome (s)

- a. Follow safety practices and precautions
- b. Demonstrate working as a leader/ a team member.
- c. Maintain tools and equipment.

VI Relevant Theoretical Background

Single Purchase Crab: Crab and winch are machines used for hoisting heavy loads applying smaller amount of effort. These machines use gear systems in order to augment velocity ratio. Depending on the number of gear assemblies, crab and winch systems can be classified into two types single and double purchase crab.

In single purchase crab, one set of gears, one pinion of teeth T_1 and one spur wheel of teeth T_2 are deployed. The pinion is fixed coaxially with the effort axle and effort pulley. Generally, a rope is wound around the effort wheel of diameter D through effort is applied. Effort then moves the pinion and thereby the spur wheel gets rotated. As the spur wheel is mounted coaxially with the load drum of diameter d , the load drum will get rotated. A strong rope is attached with load drum, at the end of Which load is connected. Thus, the load is lifted by the rotation of the effort wheel. For a single rotation of effort wheel, distance travelled by effort = πD . For single rotation of pinion, spur wheel and thereby the load drum rotate= T_1/T_2 times. So, displacement of load = $\pi d \times (T_1 / T_2)$

$$\text{Hence, Velocity Ratio} = \frac{D \times T_2}{d \times T_1} =$$

Where,

D = Diameter of effort wheel

d = Diameter of load drum

T_1 = No. of teeth on the pinion wheel

T_2 = No. of thread on spur wheel.

VII Actual Circuit diagram used in laboratory with equipment specifications

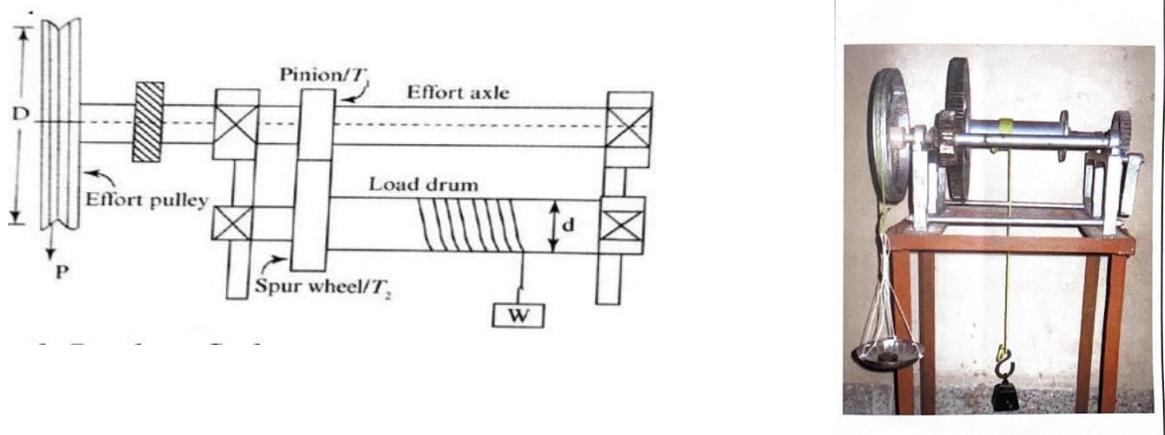


Fig: Single Purchase Crab

VIII Required Recourses/Apparatus/Equipment with specifications

Sr. No.	Particulars	Broad Specifications	Quantity	Remarks (If Any)
1.	Single Purchase Crab	Single Purchase Crab winch (Table mounted heavy Cast iron body. The effort wheel is of C.I. material of 25 cm diameter mounted on a shaft of about 40mm dia. On the same shaft a geared wheel of 15 cm diameter.	01 for Group of 4 to 5 students.	

IX Precautions to be followed

1. Effort should not be pulled suddenly.
2. Friction in pulley should be less.
3. String should not be extensible and weightless.
4. Any overlapping of the string should be avoided.
5. Lubricate the screw before starting the experiment.
6. Trapping should be done after adding the weight in the effort hanger.

X Procedure

1. Observe the machine carefully and identify the various components of machine.
2. Set the machine and check the reversibility of machine. Also calculate friction in ma-

chine at zero load

3. Apply the load starting with smaller magnitude.
4. Apply the effort for each corresponding load.
5. Record the observations of load and effort in observation table. Take at least five readings.
6. Measure the radius of effort wheel and load drum. Count number of teeth on pinion-gear and spur wheel.
7. Determine M.A., V.R., Efficiency, Ideal effort and Effort lost in friction for given Single Purchase Crab.
8. Plot graphs load against effort and load against efficiency.

XI Observations and Calculations

$$V. R. = \frac{D \times T2}{d \times T1} =$$

1. D = mm
2. d = mm
3. T1 = No.
4. T2 = No.

XII Observations Table

Sr. No.	Load W (N)	Effort P (N)	M.A.	Velocity Ratio	Efficiency η (%)	Ideal Effort Pi (N)	Effort Lost in Friction Pf (N)
1							
2							
3							
4							
5							

XIII Sample Calculations

$$M.A. = \frac{\text{Load}}{\text{Effort}} = \frac{W}{P} =$$

$$\text{Efficiency}(\eta) = \frac{M.A.}{V.R.} \times 100\% =$$

$$P_i = \frac{W}{V.R.} =$$

$$P_f = P - P_i =$$

Law of machine is $P = mW + C$

Where,

$$m = \text{Slope} = \frac{P_2 - P_1}{W_2 - W_1} =$$

$C = Y$ intercept (i.e. Machine Friction) = _____ N

XIV Results

1. The law of machine is $P = (\dots\dots\dots) W + (\dots\dots\dots) N$
2. The average efficiency of machine is = %

XV Interpretation of results

Machine is

Friction loss is (i.e. $Y - \text{intercept} = \dots\dots\dots$) reduced by the machine.

The graph between load and effort is a straight line which indicates.....

The graph between load and efficiency is a curve which indicates.....

XVI Conclusions and Recommendations

.....

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.....

.....

XVII Practical Related Questions

Note: Below given are few sample questions for reference. Teachers must design more such questions so as to ensure the achievement of identified CO. Write answers of minimum three questions.

1. Why pinion wheel is smaller than spur wheel. Give reason.
2. Write two field applications of single purchase crab.
3. Weather the given machine is reversible or not? Give reason.
4. State any two field conditions where this machine can be used.
5. Name the types of gear teeth used for the machine in your laboratory.

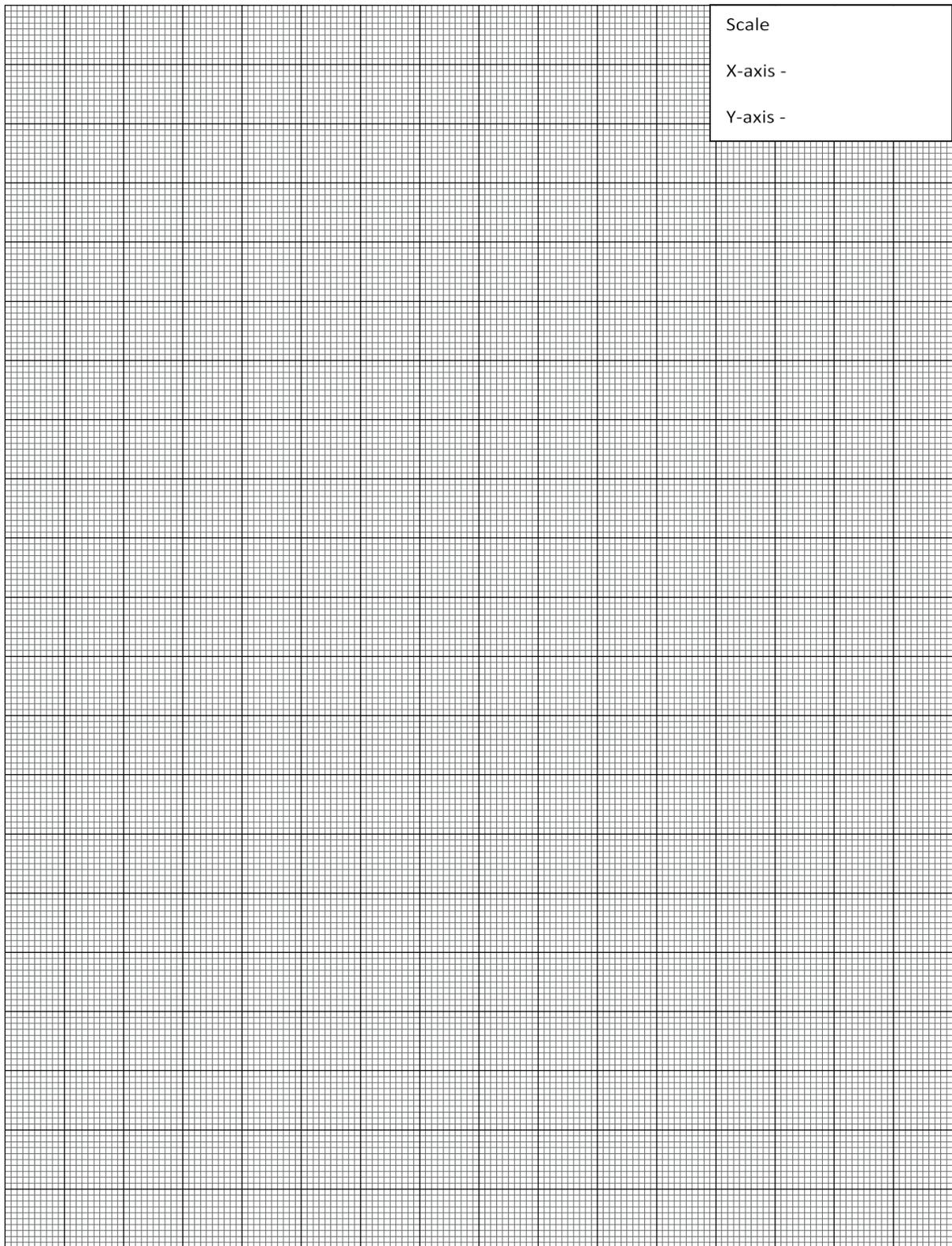
XIX Suggested Assessment Scheme

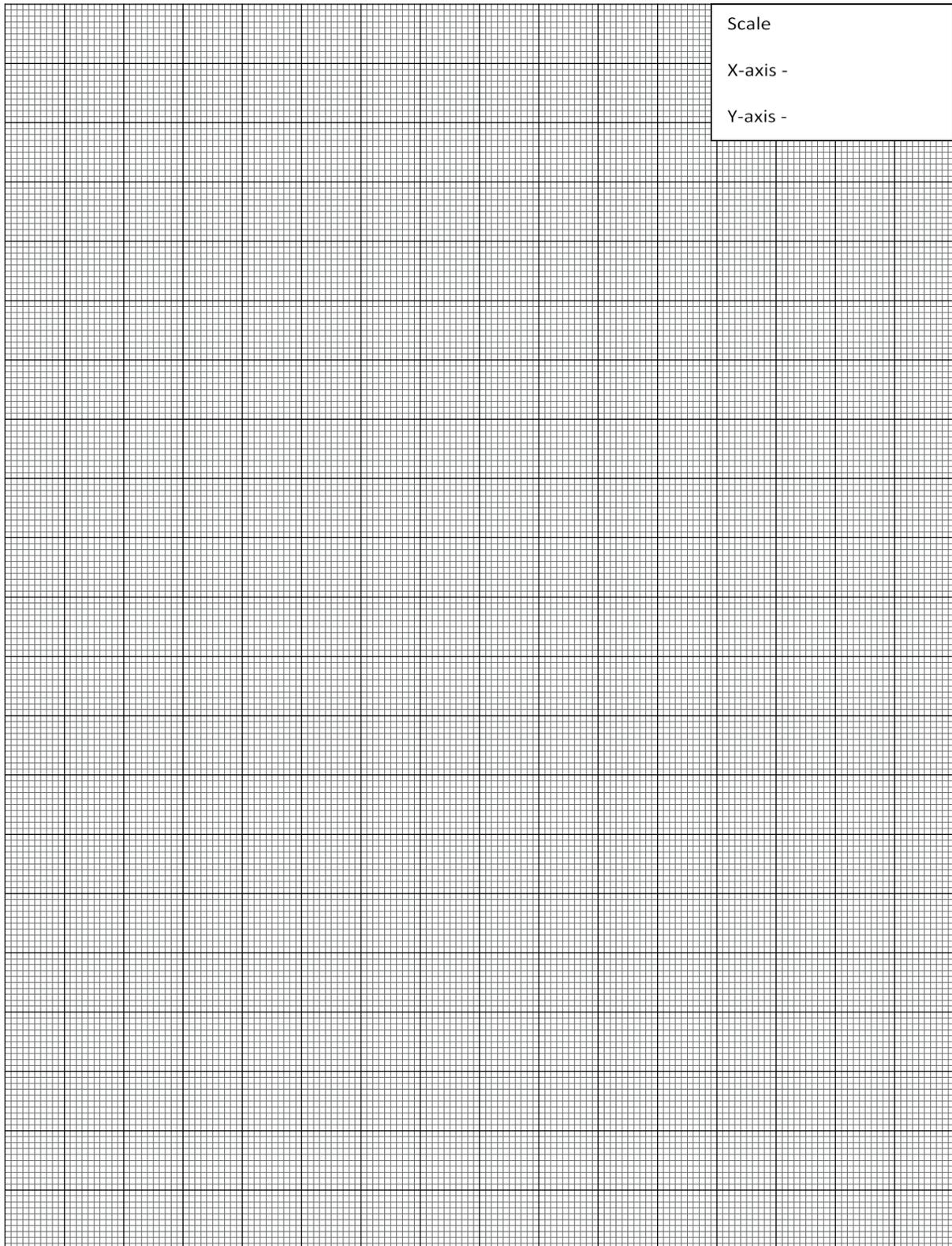
Performance Indicators		Weightage (%)
Process related: 15 Marks		60 %
1	Handling of the machine.	5 %
2	Determination of V. R. of machine.	10 %
3	Applying load and determine effort of machine.	20 %
4	Identify the type of machine i.e. reversible or self-locking.	10 %
5	Calculation of parameters concerned.	10 %
6	Working in team.	5 %
Product related: 10 Marks		40 %
1	Error estimation.	5 %
2	Interpretation of result and graph.	10 %
3	Conclusion and Recommendation.	10 %
4	Answer to the practical related questions.	10 %
5	Submission of report in time.	5 %
Total: 25 Marks		100 %

List of Student team members.

1.
2.
3.
4.

Marks Obtained			Dated sign of Teacher
Process Related(15)	Product Related(10)	Total(25)	





Practical No. 5: Determine mechanical advantage and velocity ratio of double purchase crab winch for different load and effort.

I. Practical Significance

There is often a need to lift loads and different lifting machines are used depending on the type of load, intensity of the load and other site conditions. The Double Purchase Crab machine is used for lifting heavy loads in confined spaces. According to per. Through this experiment, a qualified engineer can decide on the suitability of a double purchase crab based on the given lifting situation.

II. Industry / Employer Expected Outcomes

Apply the principles of engineering mechanics to analyze, design and automation the prototypes and equipment's of various industries

III Course Level Learning Outcome(s)

CO1 Select the suitable machine under given loading condition.

IV Laboratory Learning Outcome(s)

Verify law of machine under the given condition.

V Relevant Affective Domain related Outcome (s)

- a. Follow safety practices and precautions
- b. Demonstrate working as a leader/ a team member.
- c. Maintain tools and equipment.

VI Relevant Theoretical Background

Double Purchase Crab: Crab and winch are machines used for hoisting heavy loads applying smaller amount of effort. These machines use gear systems in order to augment velocity ratio. Depending on the number of gear assemblies, crab and winch systems can be classified into two types single and double purchase crab.

In double purchase crab machine, two sets of gear assemblies are used. One additional axle, called an intermediate axle, is deployed. The pinion of teeth T1, mounted on effort wheel axle meshes with spur wheel of teeth T2, mounted on the intermediate axel.

Similarly, the pinion of teeth T3, on intermediate axle meshes with spur wheel of teeth T4, mounted on the load drum. A rope is wound around the effort wheel of diameter D through effort is applied and load is attached to another rope wound around the load drum. Effort then moves the pinion and thereby the spur wheel gets rotated. As the spur wheel is mounted intermediate axle it gets rotated. As intermediate axle rotates the load drum of diameter d, will get rotated. A strong rope is attached with load drum, at the end of which load is connected. Thus, the load is lifted by the rotation of the effort wheel.

For a single rotation of the effort wheel, distance travelled by effort= πD . For single rotation of pinion, on effort axle, spur wheel on intermediate axle rotates= T_1/T_2 times. Now the pinion on the intermediate axle also rotates= T_1/T_2 times. So, the spur wheel of the load drum rotates= $(T_1/T_2) \times (T_3/T_4)$ times. Thus, the displacement of load = $\pi d \times (T_1/T_2) \times (T_3/T_4)$

$$\text{Hence, Velocity Ratio} = \frac{\pi D}{\pi d \left(\frac{T_1}{T_2}\right) \left(\frac{T_3}{T_4}\right)} = \frac{D \times T_2 \times T_4}{d \times T_1 \times T_3}$$

Where,

- D = Diameter of effort wheel
- d = Diameter of load drum
- T1 and T3 = No. of teeth on the pinion wheel
- T2 and T4 = No. of thread on spur wheel.

VII Actual Circuit diagram used in laboratory with equipment specifications

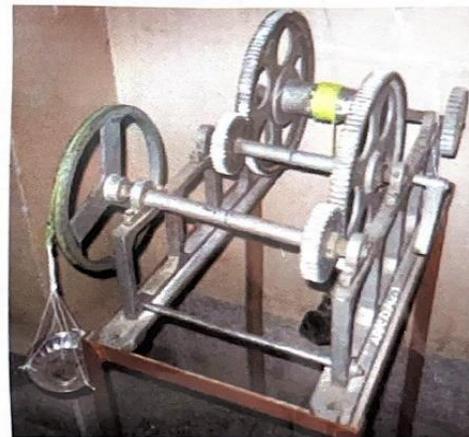
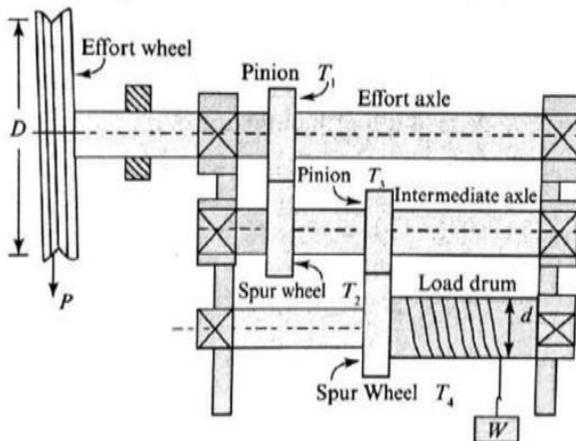


Fig: Double Purchase Crab

VIII Required Recourses/Apparatus/Equipment with specification

Sr. No.	Particulars	Broad Specifications	Quantity	Remarks (If Any)
1.	Double Purchase Crab	Double Purchase Crab winch (Having assembly same as single purchase crab but with double set gearing arrangement)	01 for Group of 4 to 5 students.	

IX Precautions to be followed

1. Effort should not be pulled suddenly.
2. Friction in pulley should be less.
3. String should not be extensible and weightless.

4. Any overlapping of the string should be avoided.
5. Lubricate the screw before starting the experiment.
6. Trapping should be done after adding the weight in the effort hanger.

X Procedure

1. Observe the machine carefully and identify the various components of machine.
2. Set the machine and check the reversibility of machine.
3. Calculate friction in the machine based on zero load.
4. Apply the load starting with smaller magnitude.
5. Apply the effort for each corresponding load.
6. Record the observations of load and effort in observation table. Take at least five readings.
7. Measure the radius of effort wheel and load drum. Count number of teeth on pinion gear and spur wheels.
8. Determine M.A., V.R., Efficiency, Ideal effort and Effort lost in friction for given Double purchase Crab.
9. Plot graphs viz. load against effort and load against efficiency

XI Observations and Calculations

$$\text{Velocity Ratio} = \frac{\pi D}{\pi d \left(\frac{T_1}{T_2} \right) \left(\frac{T_3}{T_4} \right)} = \frac{D \times T_2 \times T_4}{d \times T_1 \times T_3}$$

1. D = mm
2. d = mm
3. T1 = No.
4. T2 = No.
5. T3 = No.
6. T4 = No.

XII Observations Table

Sr. No.	Load W (N)	Effort P (N)	M.A.	Velocity Ratio	Efficiency η (%)	Ideal Effort Pi (N)	Effort Lost in Friction Pf (N)
1							
2							
3							
4							
5							

XIII Sample Calculations

$$M. A. = \frac{\text{Load}}{\text{Effort}} = \frac{W}{P} =$$

$$\text{Efficiency } (\eta) = \frac{M.A.}{V.R.} \times 100\% =$$

$$M.A. = \frac{\text{Load}}{\text{Effort}} = \frac{W}{P} =$$

$$\text{Efficiency}(\eta) = \frac{M.A.}{V.R.} \times 100\% =$$

$$P_i = \frac{W}{V.R.} =$$

$$P_f = P - P_i =$$

Law of machine is $P = mW + C$

Where,

$$m = \text{Slope} = \frac{P_2 - P_1}{W_2 - W_1} =$$

$C = Y$ intercept (i.e. Machine Friction) = _____ N

XIV Results

1. The law of machine is $P = (\dots\dots\dots) W + (\dots\dots\dots) N$
2. The average efficiency of machine is = %

XV Interpretation of results

Machine is

Friction loss is (i.e. $Y -$ intercept =) reduced by the machine.

The graph between load and effort is a straight line which indicates.....

The graph between load and efficiency is a curve which indicates.....

XVI Conclusions and Recommendations

.....

XVII Practical Related Questions

Note: Below given are few sample questions for reference. Teachers must design more such questions so as to ensure the achievement of identified CO. Write answers of minimum three questions.

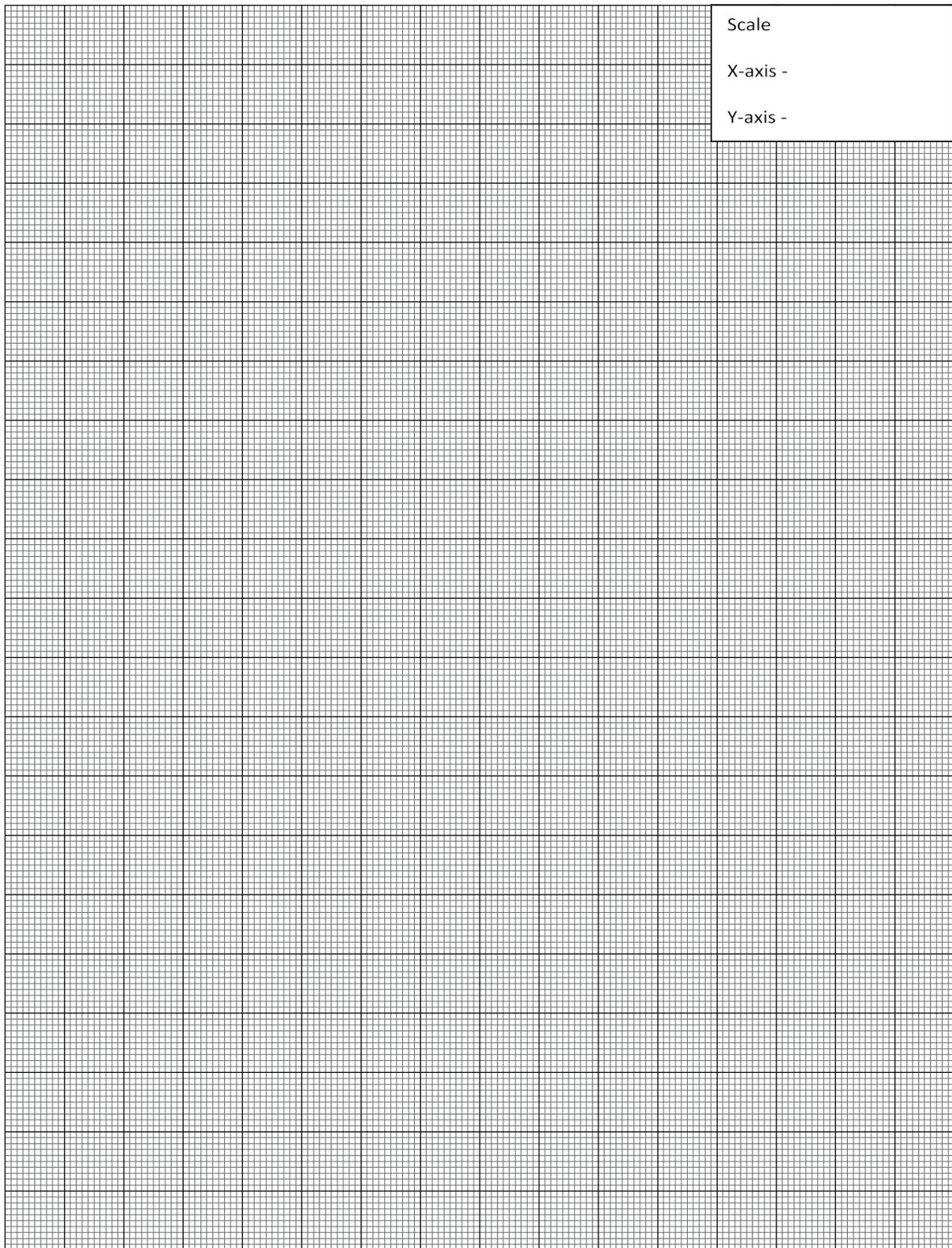
XIX Suggested Assessment Scheme

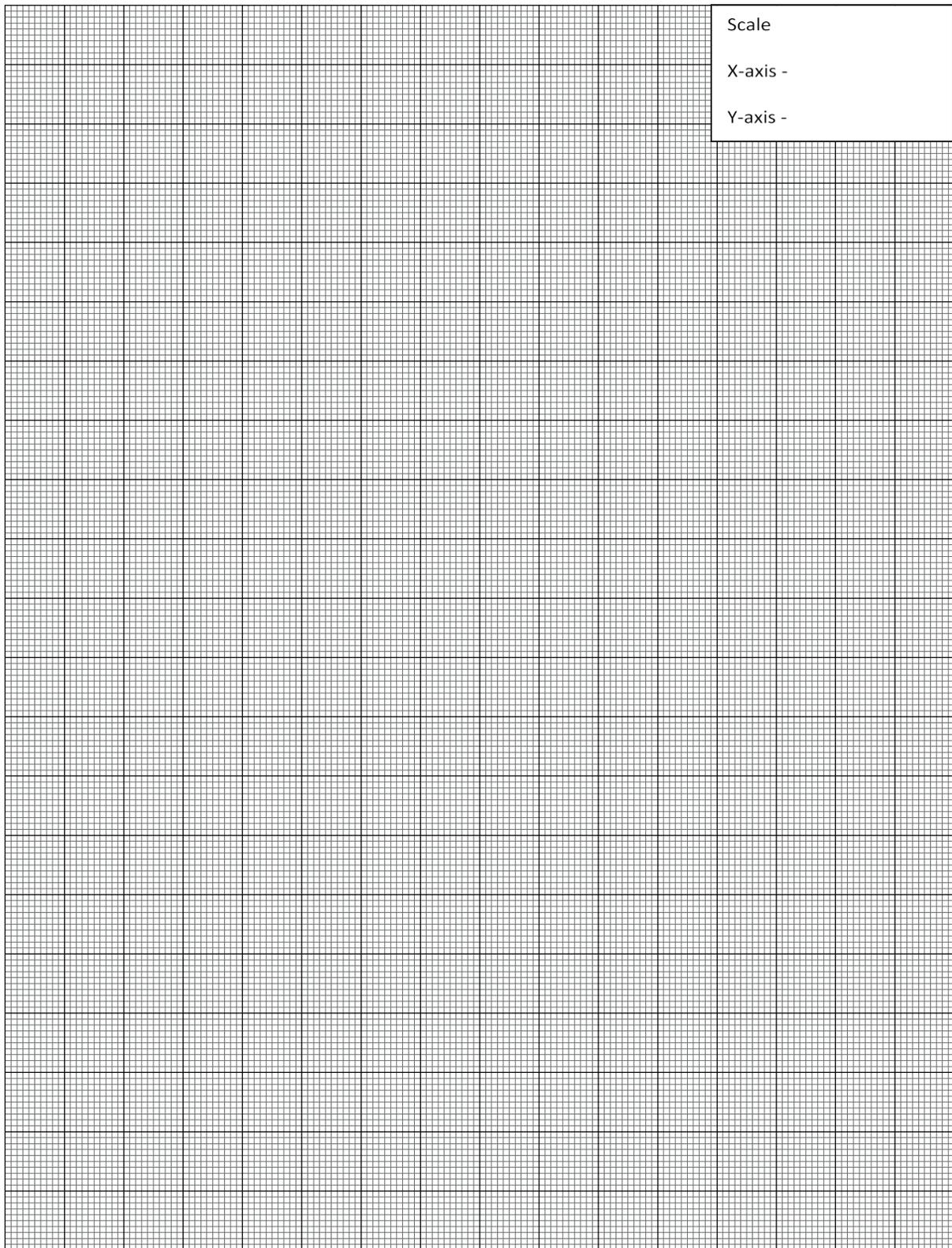
Performance Indicators		Weightage (%)
Process related: 15 Marks		60 %
1	Handling of the machine.	5 %
2	Determination of V. R. of machine.	10 %
3	Applying load and determine effort of machine.	20 %
4	Identify the type of machine i.e. reversible or self-locking.	10 %
5	Calculation of parameters concerned.	10 %
6	Working in team.	5 %
Product related: 10 Marks		40 %
1	Error estimation.	5 %
2	Interpretation of result and graph.	10 %
3	Conclusion and Recommendation.	10 %
4	Answer to the practical related questions.	10 %
5	Submission of report in time.	5 %
Total: 25 Marks		100 %

List of Student team members.

1.
2.
3.
4.

Marks Obtained			Dated sign of Teacher
Process Related(15)	Product Related(10)	Total(25)	





Practical No. 6: Determine mechanical advantage and velocity ratio of simple screw jack for different load and effort.

I. Practical Significance

There is often a need to lift loads and different lifting machines are used depending on the type of load, intensity of the load and other site conditions. A simple screw jack is used to lift heavy loads in confined spaces. After carrying out this experiment, a qualified engineer is able to assess the suitability of a screw jack based on the given load lifting situation.

II. Industry / Employer Expected outcomes

Apply the principles of engineering mechanics to analyze, design and automation the prototypes and equipment's of various industries

III Course Level Learning Outcome(s)

CO1 Select the suitable machine under given loading condition.

IV Laboratory Learning Outcome(s)

Verify law of machine under the given condition.

V Relevant Affective Domain related Outcome (s)

- a. Follow safety practices and precautions
- b. Demonstrate working as a leader/ a team member.
- c. Maintain tools and equipment.

VI Relevant Theoretical Background

Simple Screw Jack: A screw jack is a simple device which is used to lift heavy loads such as large vehicles. It mainly consists of three parts. A nut attached to a pedestal or stand, a large screw fitted within the nut and lever attached to the head of the screw.

The weight which is to be lifted is placed on either on the head of the screw or on the platform attached to the screw. Sometimes a wheel is fixed at top and effort is applied tangentially to the circumference of the wheel. A screw thread is cut just like an inclined plane. The distance which the screw advances in one turn is called lead distance and distance measured between two consecutive threads is called pitch distance. The screw jack works on the principle similar to that of an inclined plane.

$$\text{Velocity Ratio} = \frac{\text{Distance travelled by effort}}{\text{Distance travelled by load}}$$

$$VR = \frac{2\pi R}{p}$$

Where,

R = Length of arm or Radius of wheel

p = Pitch of the screw

VII Actual Circuit diagram used in laboratory with equipment specifications

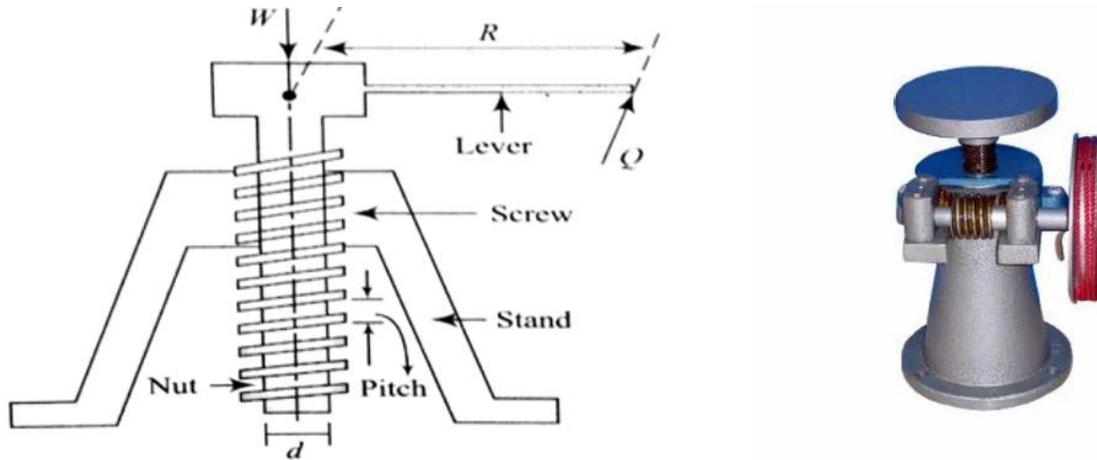


Fig: Simple Screw Jack

VIII Required Recourses/Apparatus/Equipment with specifications

Sr. No.	Particulars	Broad Specifications	Quantity	Remarks (If Any)
1.	Simple Screw Jack	Table mounted Metallic body, screw with a pitch of 5 mm carrying a double flanged turn table of 20 cm diameter.	01 for Group of 4 to 5 students.	

IX Precautions to be followed

1. Effort must be applied gradually

X Procedure

1. Observe the machine carefully and identify the various components of machine.
2. Set the machine and check the reversibility of machine
3. Calculate friction in the machine at zero load.
4. Apply the load starting with smaller magnitude.
5. Apply the effort for each corresponding load.
6. Record the observations of load and effort in observation table. Take at least five readings.
7. Determine M.A., V.R., Efficiency, Ideal effort and Effort lost in friction for given screw jack.
8. Plot graphs load against effort and load against efficiency.

XI Observations and Calculations

$$VR = \frac{2\pi R}{p}$$

1. R = mm

2. $p = \dots\dots\dots$ mm

XII Observations Table

Sr. No.	Load W (N)	Effort P (N)	M.A.	Velocity Ratio	Efficiency η (%)	Ideal Effort P_i (N)	Effort Lost in Friction P_f (N)
1							
2							
3							
4							
5							

XIII Sample Calculations

$$\text{M.A.} = \frac{\text{Load}}{\text{Effort}} = \frac{W}{P} =$$

$$\text{Efficiency}(\eta) = \frac{\text{M.A.}}{\text{V.R.}} \times 100\% =$$

$$P_i = \frac{W}{\text{V.R.}} =$$

$$P_f = P - P_i =$$

$$\text{Law of machine is } P = mW + C$$

Where,

$$m = \text{Slope} = \frac{P_2 - P_1}{W_2 - W_1} =$$

$$C = \text{Y intercept (i.e. Machine Friction)} = \text{-----} \text{N}$$

XIV Results

- The law of machine is $P = (\dots\dots\dots) W + (\dots\dots\dots) N$
- The average efficiency of machine is = $\dots\dots\dots$ %

XV Interpretation of results

Machine is $\dots\dots\dots$

Friction loss is (i.e. Y – intercept = $\dots\dots\dots$) reduced by $\dots\dots\dots$ the machine.

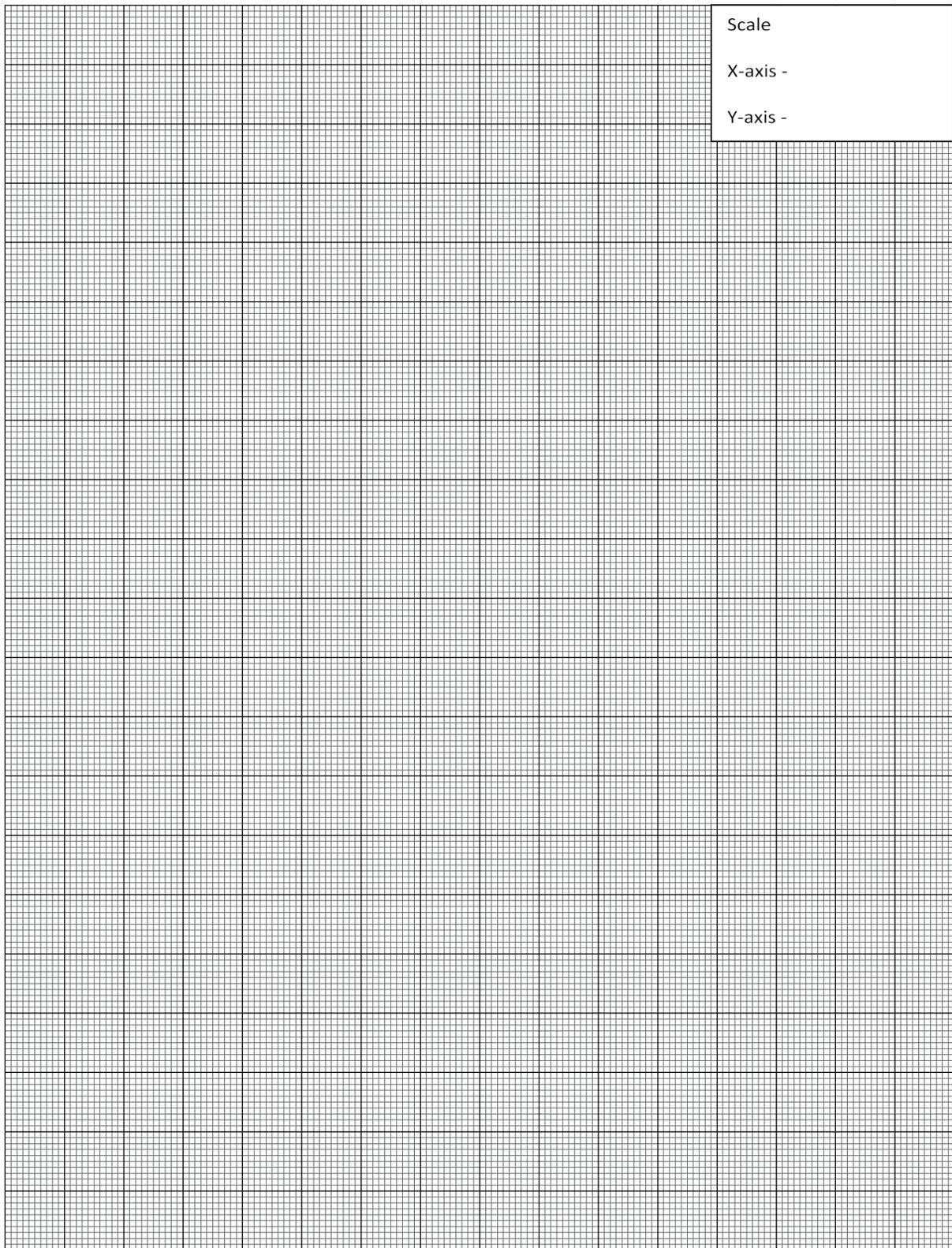
XIX Suggested Assessment Scheme

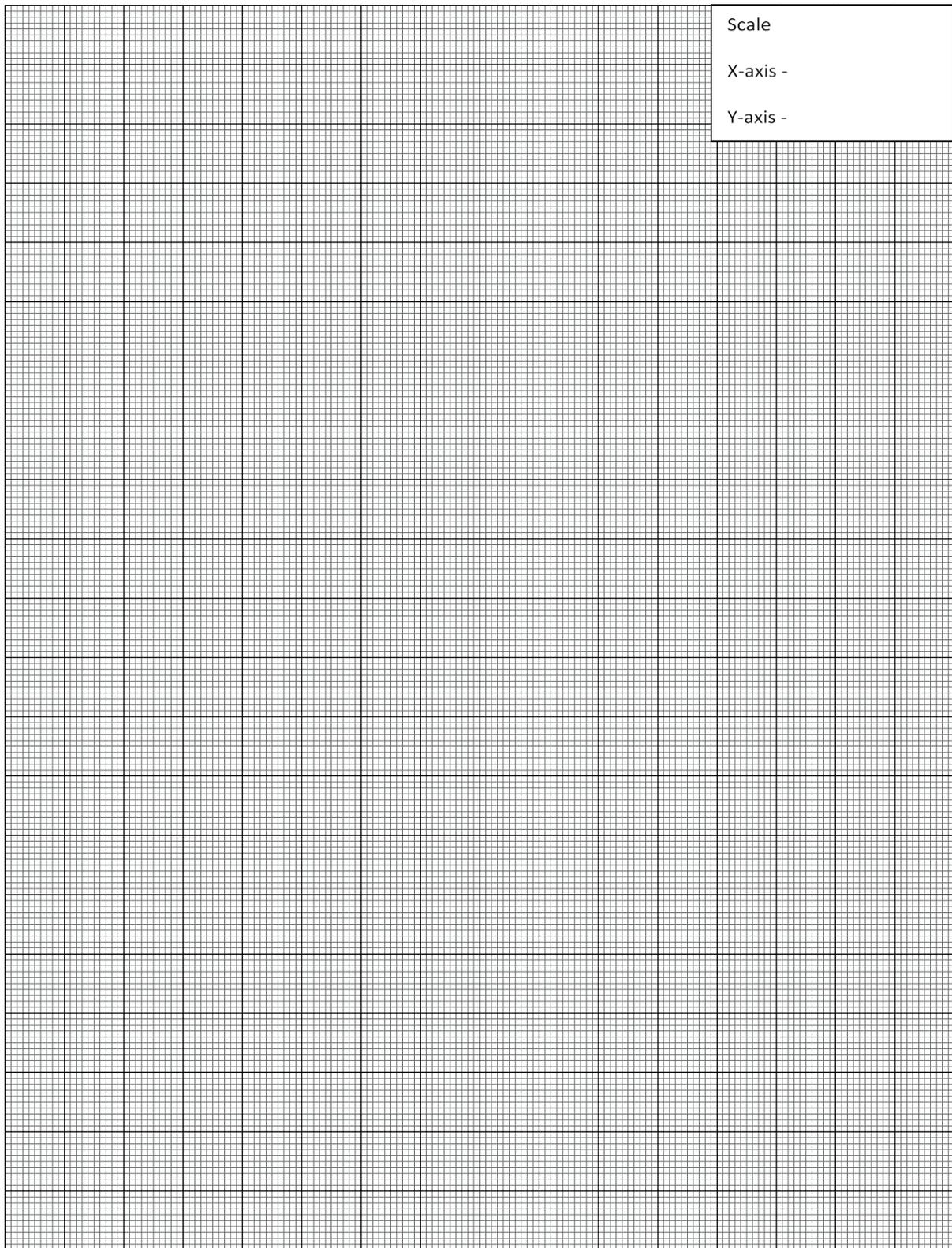
Performance Indicators		Weightage (%)
Process related: 15 Marks		60 %
1	Handling of the machine.	5 %
2	Determination of V. R. of machine.	10 %
3	Applying load and determine effort of machine.	20 %
4	Identify the type of machine i.e. reversible or self-locking.	10 %
5	Calculation of parameters concerned.	10 %
6	Working in team.	5 %
Product related: 10 Marks		40 %
1	Error estimation.	5 %
2	Interpretation of result and graph.	10 %
3	Conclusion and Recommendation.	10 %
4	Answer to the practical related questions.	10 %
5	Submission of report in time.	5 %
Total: 25 Marks		100 %

List of Student team members.

1.
2.
3.
4.

Marks Obtained			Dated sign of Teacher
Process Related(15)	Product Related(10)	Total(25)	





Practical No. 7: Determine mechanical advantage and velocity ratio of Weston's differential pulley block for different load and efforts.

I. Practical Significance

There is often a need to lift loads and different lifting machines are used depending on the type of load, intensity of the load and other site conditions. Weston's differential pulley block is used for lifting heavy loads in confined spaces. After conducting this experiment, a graduate engineer can evaluate the suitability of the Weston differential pulley block based on the given load lifting situation.

II. Industry / Employer Expected Outcomes

Apply the principles of engineering mechanics to analyze, design and automation the prototypes and equipment's of various industries

III Course Level Learning Outcome(s)

CO1 Select the suitable machine under given loading condition.

IV Laboratory Learning Outcome(s)

Verify law of machine under the given condition.

V Relevant Affective Domain related Outcome (s)

- a. Follow safety practices and precautions
- b. Demonstrate working as a leader/ a team member.
- c. Maintain tools and equipment.

VI Relevant Theoretical Background

Weston's Differential Pulley Block: This differential pulley block was invented by Thomas Aldridge Weston from king's Norton, England, in 1854. Hence, this simple machine is also called as Weston's differential pulley block. This is a special type of pulley system, which is normally used to hoist very large masses to small distance, for example, the pulley system is used for manually lifting car engines. This system consists of two fixed pulleys of unequal radii, which are coaxially attached to each other and can rotate together and are fixed to the support, a single pulley hanging at the bottom and holding load and an endless rope wrapped around the pulleys. In order to avoid slipping, generally rope is substituted by a chain and connected to pulleys by sprockets (i.e. tooth or cogs on pulleys). The displacement of the effort in one revolution of upper pulley block = πD . This is also equal to length of the chain pulled over the large pulley. Since the smaller pulley also turns with the larger one, therefore length of the chain released by the smaller pulley = πd . Net shortening of the chain = $\pi D - \pi d = \pi (D-d)$. This shortening of chain will be equally divided between the portion of the chain, supporting the load. Therefore, the distance the load moves up by a distance $\pi (D-d)/2$.

$$\text{Velocity Ratio} = \frac{\text{Distance travelled by effort}}{\text{Distance travelled by load}}$$

$$VR = \frac{2D}{D - d} = \frac{2T_1}{T_1 - T_2}$$

Where,

D = Diameter of pulley P1

d = Diameter of pulley P2

T1 = No. of teeth or cogs of pulley P1

T2 = No. of teeth or cogs on pulley P2

VII Actual Circuit diagram used in laboratory with equipment specifications

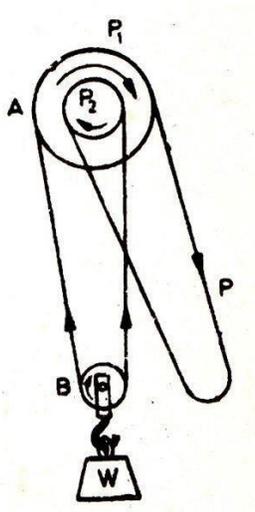


Fig: Weston's Differential Pulley Block

VIII Required Recourses/Apparatus/Equipment with specifications

Sr. No.	Particulars	Broad Specifications	Quantity	Remarks (If Any)
1.	Weston's Differential Pulley Block	Weston's Differential pulley block (consisting of two pulleys; one bigger and other smaller)	01 for Group of 4 to 5 students.	

IX Precautions to be followed

1. Effort must be applied gradually

X Procedure

1. Observe the machine carefully and identify the various components of machine.
2. Set the machine and check the reversibility of it.
3. Calculate friction in the given machine at zero load.
4. Apply the load starting with smaller magnitude.
5. Apply the effort for each corresponding load.
6. Record the observations of load and effort in observation table. Take at least five readings.
7. Measure the radius or number of cogs of larger and smaller pulley.
8. Determine M.A., V.R., Efficiency, Ideal effort and Effort lost in friction for given Weston's differential pulley block.
9. Plot graphs viz. load against effort and load against efficiency.

XI Observations and Calculations

$$VR = \frac{2D}{D-d} = \frac{2T_1}{T_1 - T_2}$$

1. $T_1 = \dots\dots\dots$ No.
2. $T_2 = \dots\dots\dots$ No.

XII Observations Table

Sr. No.	Load W (N)	Effort P (N)	M.A.	Velocity Ratio	Efficiency η (%)	Ideal Effort P_i (N)	Effort Lost in Friction P_f (N)
1							
2							
3							
4							
5							

XIII Sample Calculations

$$M.A. = \frac{\text{Load}}{\text{Effort}} = \frac{W}{P} =$$

$$\text{Efficiency}(\eta) = \frac{M.A.}{V.R.} \times 100\% =$$

$$P_i = \frac{W}{V.R.} =$$

$$P_f = P - P_i =$$

Law of machine is $P = mW + C$

Where,

$$m = \text{Slope} = \frac{P_2 - P_1}{W_2 - W_1} =$$

$C = Y$ intercept (i.e. Machine Friction) = _____ N

XIV Results

1. The law of machine is $P = (\dots\dots\dots) W + (\dots\dots\dots) N$
2. The average efficiency of machine is = %

XV Interpretation of results

Machine is

Friction loss is (i.e. $Y - \text{intercept} = \dots\dots\dots$) reduced by the machine.

The graph between load and effort is a straight line which indicates.....

The graph between load and efficiency is a curve which indicates.....

XVI Conclusions and Recommendations

.....

.....

.....

XVII Practical Related Questions

Note: Below given are few sample questions for reference. Teachers must design more such questions so as to ensure the achievement of identified CO. Write answers of minimum three questions.

1. Calculate the maximum MA and maximum efficiency.
2. State the given machine is reversible or not. Give reason.
3. Why effort is required for zero load?
4. Write use of snatch block in working of machine.
5. State the two situations in field where differential pulley block is used.

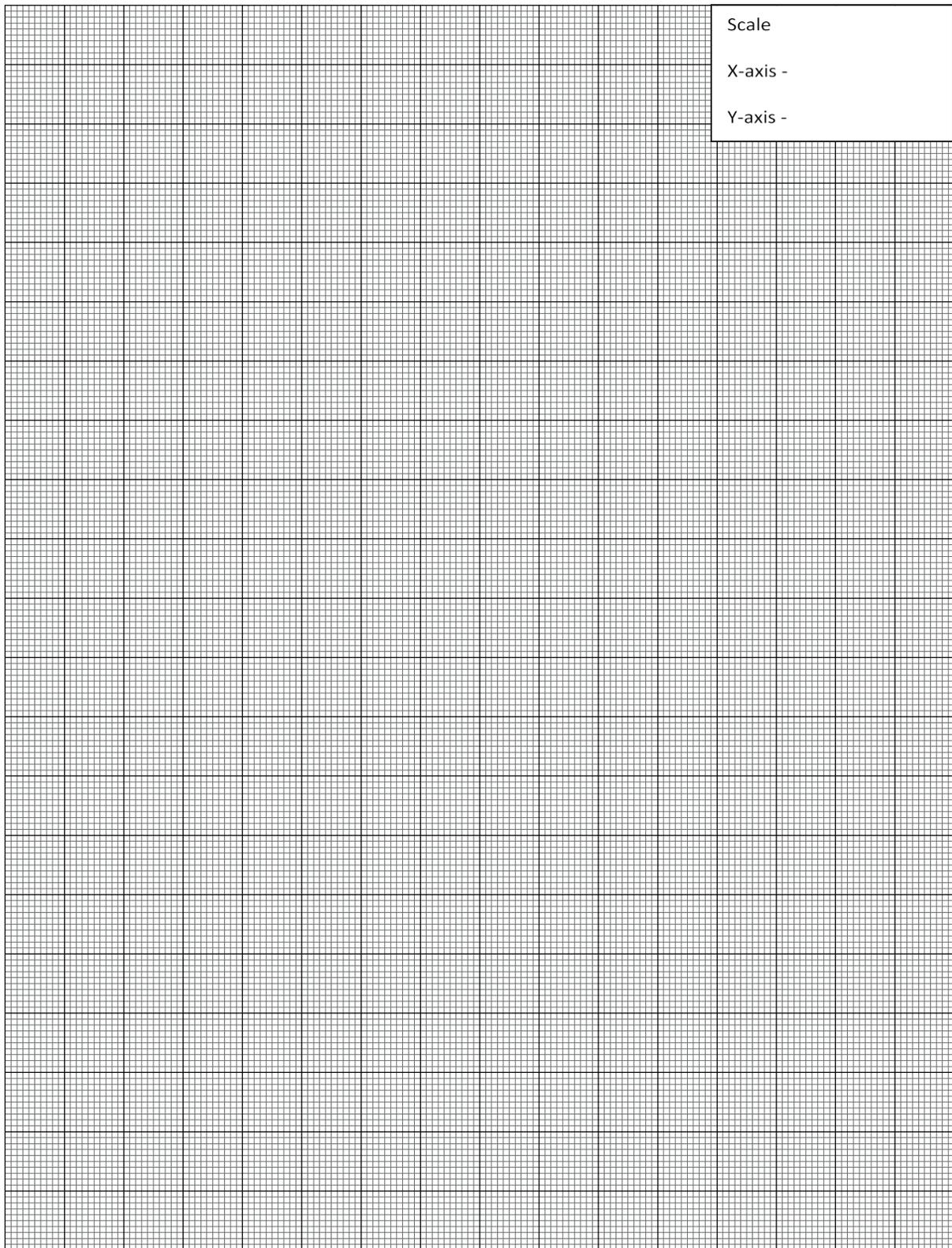
XIX Suggested Assessment Scheme

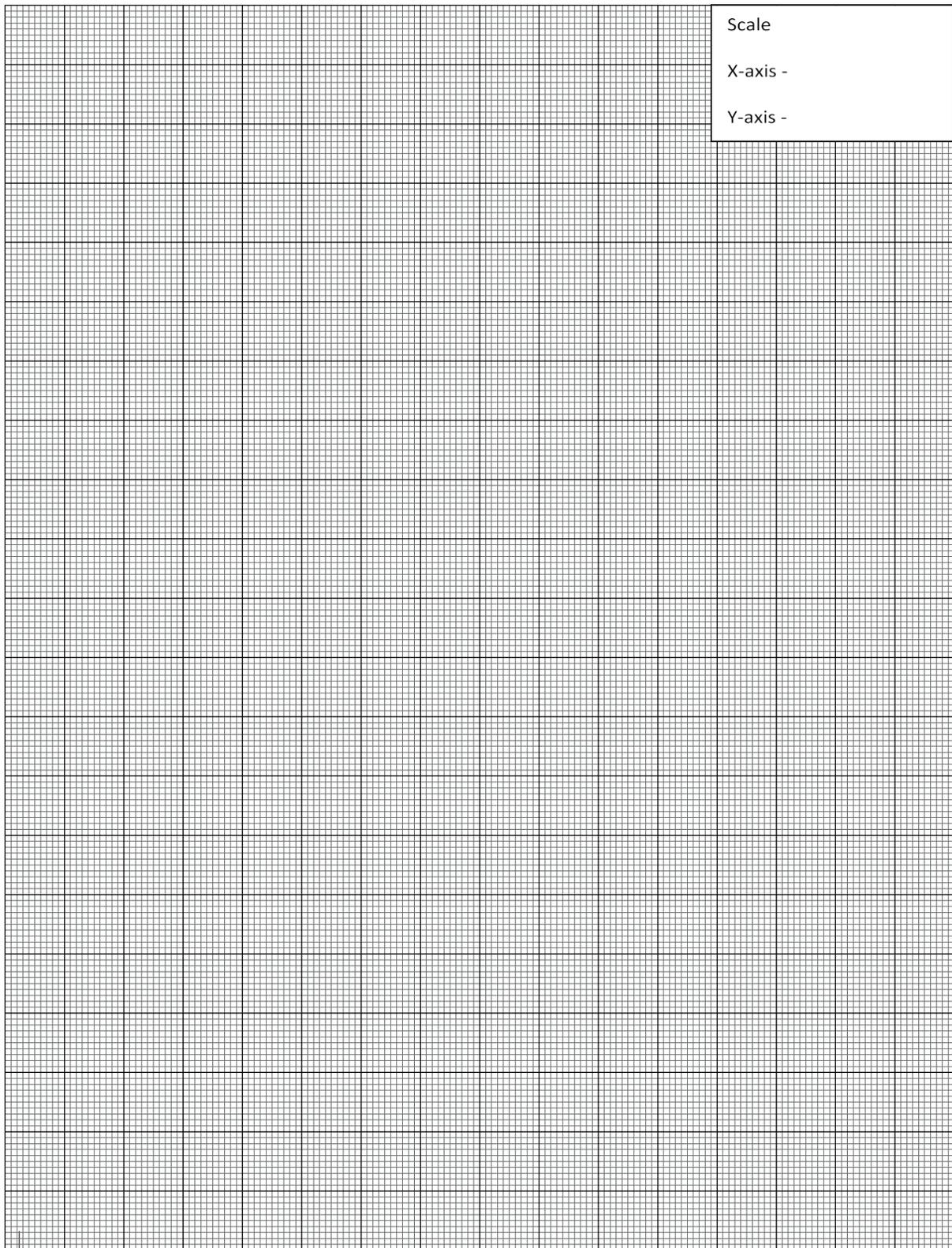
Performance Indicators		Weightage (%)
Process related: 15 Marks		60 %
1	Handling of the machine.	5 %
2	Determination of V. R. of machine.	10 %
3	Applying load and determine effort of machine.	20 %
4	Identify the type of machine i.e. reversible or self-locking.	10 %
5	Calculation of parameters concerned.	10 %
6	Working in team.	5 %
Product related: 10 Marks		40 %
1	Error estimation.	5 %
2	Interpretation of result and graph.	10 %
3	Conclusion and Recommendation.	10 %
4	Answer to the practical related questions.	10 %
5	Submission of report in time.	5 %
Total: 25 Marks		100 %

List of Student team members.

1.
2.
3.
4.

Marks Obtained			Dated sign of Teacher
Process Related(15)	Product Related(10)	Total(25)	





Practical No. 8: Determine mechanical advantage and velocity ratio of geared pulley block for different load and efforts.

I. Practical Significance

There is often a need to lift loads and different lifting machines are used depending on the type of load, intensity of the load and other site conditions. The gear pulley is used for lifting heavy loads in confined spaces. After conducting this experiment, a graduate engineer can assess the suitability of the Geard pulley based on the given load lifting situation.

II. Industry / Employer Expected outcomes

Apply the principles of engineering mechanics to analyze, design and automation the prototypes and equipment's of various industries.

III Course Level Learning Outcome(s)

CO1 Select the suitable machine under given loading condition.

IV Laboratory Learning Outcome(s)

Verify law of machine under the given condition.

V Relevant Affective Domain related Outcome (s)

- a. Follow safety practices and precautions
- b. Demonstrate working as a leader/ a team member.
- c. Maintain tools and equipment.

VI Relevant Theoretical Background

Worm Gear Pulley Block: In a gear pulley block, an axle is coaxially attached to an effort wheel having T_1 number teeth. A pinion having teeth T_2 and a ratchet and clutch are attached coaxially on the axle. A pawl presses against this ratchet and clutch with the help of a spring. The pinion is geared with a spur wheel having teeth T_3 . On the same axle as spur wheel a load drum having teeth T_4 is keyed on its circumference. An endless rope or chain is wound over effort wheel with which the effort is applied. The motion is transmitted from effort wheel to load drum through pinion and spur wheel. A separate rope is wound around half the perimeter of load drum. One end of it is fixed to the frame and other end holds the load. When the load is hoisted, the ratchet passes under the pawl. On the removal of effort, the pawl prevents the load from falling down. Hence, it is self-locking arrangement. In single rotation of effort wheel, effort moves through a distance proportional to T_1 . At the same time, the spur wheel and the load drum rotate by (T_2/T_1) of a rotation. In single rotation of load drum, the load is lifted through distance proportional to 4. So far, a single rotation of effort wheel, the load is lifted by a distance $(T_2/T_3) \times T_4$.

Hence,

$$\text{Velocity Ratio} = \frac{\text{Distance travelled by effort}}{\text{Distance travelled by load}}$$

$$VR = \frac{T_1}{\frac{T_2}{T_3} - T_4} = \frac{T_1 \times T_3}{T_2 \times T_4}$$

Where,

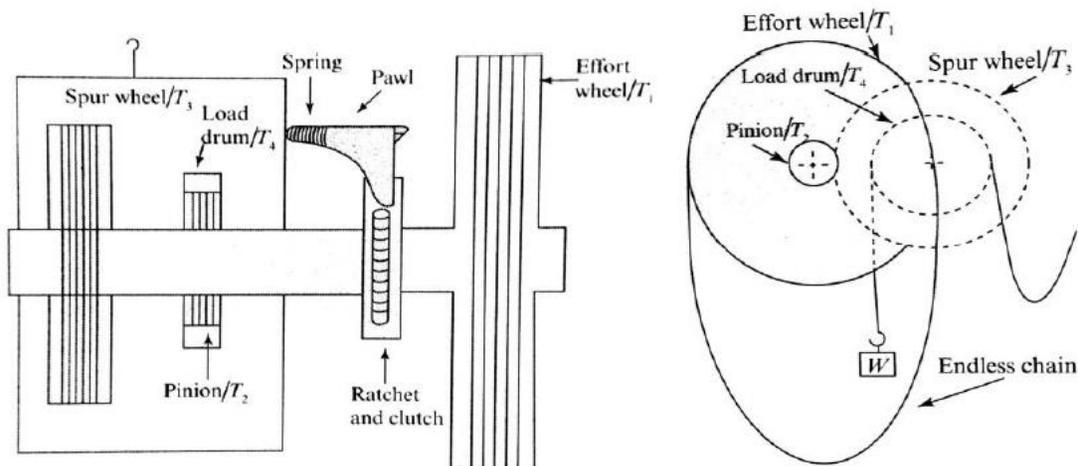
T1 = No. of teeth or cogs on effort wheel

T2 = No. of teeth or cogs on pinion wheel

T3 = No. of teeth or cogs on spur wheel

T4 = No. of teeth or cogs on load drum

VII Actual Circuit diagram used in laboratory with equipment specifications



Gear arrangement working of gear pulley block

Figure: Worm Gear Pulley Block

VIII Required Recourses/Apparatus/Equipment with specifications

Sr. No.	Particulars	Broad Specifications	Quantity	Remarks (If Any)
1.	Worm Gear Pulley Block.	Worm gear pulley block consists of a metallic (preferably steel) cogged wheel of about 20 cm along with a protruded load drum of 10 cm diameter to suspend the weights of 10 kg, 20 kg and 50 kg weights.	01 for Group of 4 to 5 students.	

IX Precautions to be followed

1. Effort must be applied gradually

X Procedure

1. Observe the machine carefully and identify the various components of machine.
2. Set the machine and check the reversibility of it.
3. Calculate friction in the given machine at zero load.
4. Apply the load starting with smaller magnitude.
5. Apply the effort for each corresponding load.
6. Record the observations of load and effort in observation table. Take at least five read-ings.
7. Measure the radius or number of cogs of larger and smaller pulley.
8. Determine M.A., V.R., Efficiency, Ideal effort and Effort lost in friction for given Weston's differential pulley block.
9. Plot graphs load against effort and load against efficiency.

XI Observations and Calculations

$$VR = \frac{T1}{\frac{T2}{T3} - T4} = \frac{T1 \times T3}{T2 \times T4}$$

1. T1 = No.
2. T2 = No.
3. T3 = No.
4. T4 = No.

XII Observations Table

Sr. No.	Load W (N)	Effort P (N)	M.A.	Velocity Ratio	Efficiency η (%)	Ideal Effort P_i (N)	Effort Lost in Friction P_f (N)
1							
2							
3							
4							
5							

XIII Sample Calculations

$$M.A. = \frac{\text{Load}}{\text{Effort}} = \frac{W}{P} =$$

$$\text{Efficiency}(\eta) = \frac{M.A.}{V.R.} \times 100\% =$$

$$P_i = \frac{W}{V.R.} =$$

$$P_f = P - P_i =$$

$$\text{Law of machine is } P = mW + C$$

Where,

$$m = \text{Slope} = \frac{P_2 - P_1}{W_2 - W_1} =$$

$$C = \text{Y intercept (i.e. Machine Friction)} = \text{_____ N}$$

XIV Results

1. The law of machine is $P = (\dots\dots\dots) W + (\dots\dots\dots) N$
2. The average efficiency of machine is = $\dots\dots\dots$ %

XV Interpretation of results

Machine is $\dots\dots\dots$

Friction loss is (i.e. Y – intercept = $\dots\dots\dots$) reduced by $\dots\dots\dots$ the machine.

The graph between load and effort is a straight line which indicates $\dots\dots\dots$

The graph between load and efficiency is a curve which indicates $\dots\dots\dots$

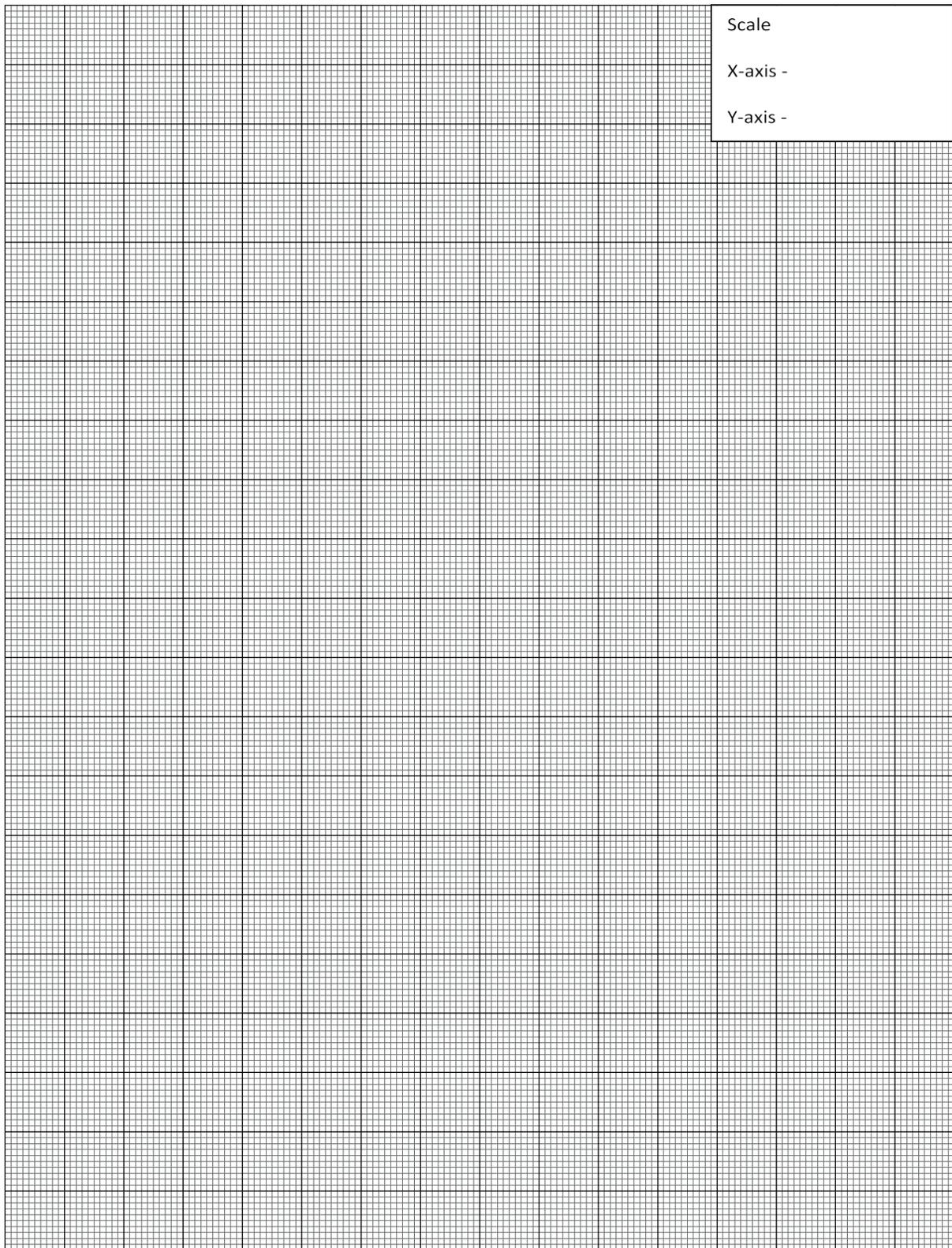
XIX Suggested Assessment Scheme

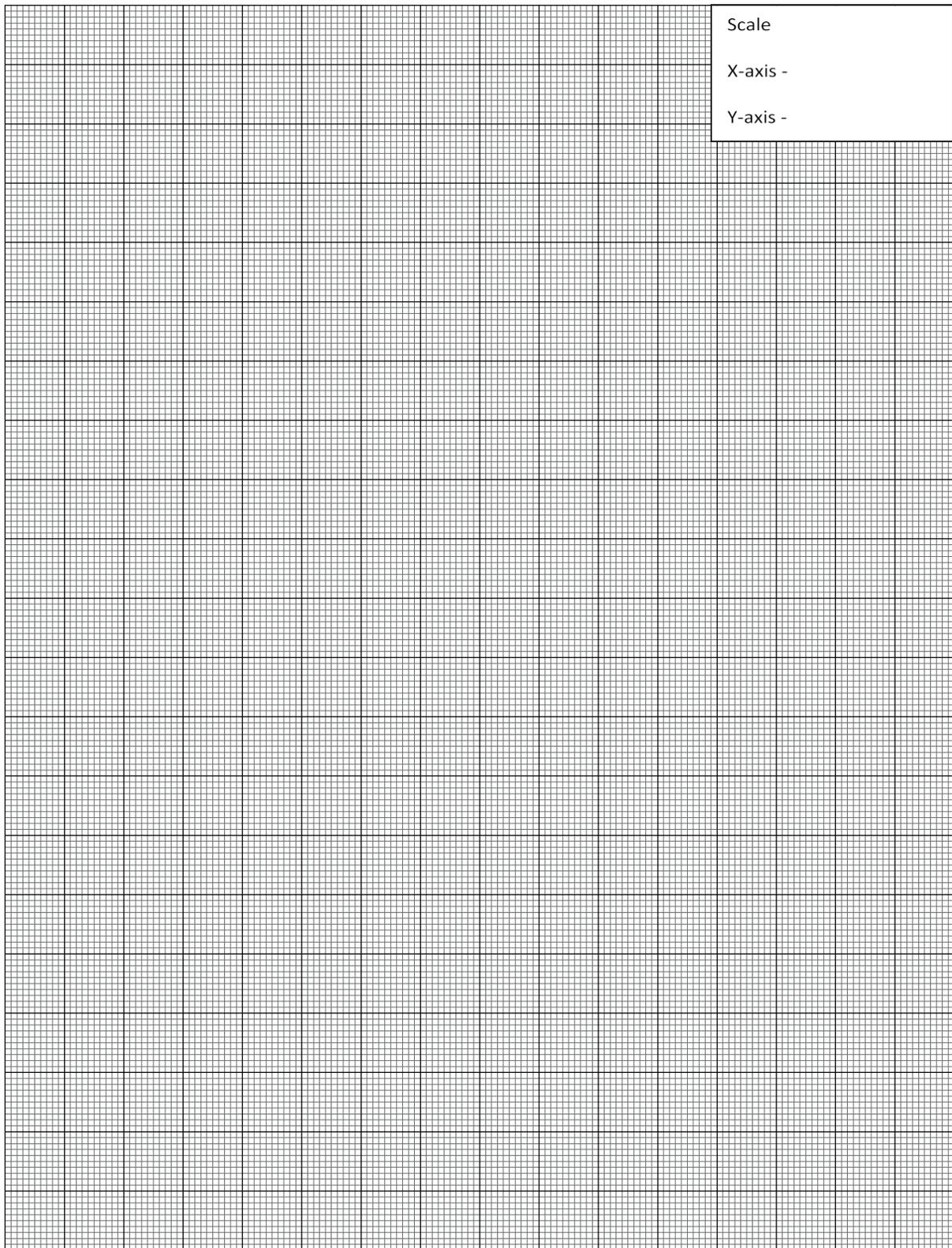
Performance Indicators		Weightage (%)
Process related: 15 Marks		60 %
1	Handling of the machine.	5 %
2	Determination of V. R. of machine.	10 %
3	Applying load and determine effort of machine.	20 %
4	Identify the type of machine i.e. reversible or self-locking.	10 %
5	Calculation of parameters concerned.	10 %
6	Working in team.	5 %
Product related: 10 Marks		40 %
1	Error estimation.	5 %
2	Interpretation of result and graph.	10 %
3	Conclusion and Recommendation.	10 %
4	Answer to the practical related questions.	10 %
5	Submission of report in time.	5 %
Total: 25 Marks		100 %

List of Student team members.

1.
2.
3.
4.

Marks Obtained			Dated sign of Teacher
Process Related(15)	Product Related(10)	Total(25)	





Practical No. 9: Determine mechanical advantage and velocity ratio of two sheave pulley block for different load and efforts.**I. Practical Significance**

There is often a need to lift loads and different lifting machines are used depending on the type of load, intensity of the load and other site conditions. Two sheave pulley blocks are used for lifting heavy loads in confined spaces. After conducting this experiment, a graduate engineer will be able to assess the suitability of a two-sheave pulley based on the given load lifting situation.

II. Industry / Employer Expected Outcomes

Apply the principles of engineering mechanics to analyze, design and automation the prototypes and equipment's of various industries

III Course Level Learning Outcome(s)

CO1 Select the suitable machine under given loading condition.

IV Laboratory Learning Outcome(s)

Verify law of machine under the given condition.

V Relevant Affective Domain related Outcome (s)

- Follow safety practices and precautions
- Demonstrate working as a leader/ a team member.
- Maintain tools and equipment.

VI Relevant Theoretical Background

Two Sheave pully block: It also consists of upper block and lower block each having the pulleys in their sheave; therefore, total number of pulley are four. Upper block is fixed that of lower block is moveable. As the load W is equally shared by the four parts of the rope; tension (T) in each rope is W/P for an ideal machine $M.A. = V.R.$

Hence,

$$\text{Velocity Ratio} = \frac{\text{Distance travelled by effort}}{\text{Distance travelled by load}}$$

$$VR = \frac{W}{\frac{W}{4}} = 4$$

$$\therefore V.R. = 2 \times \text{Number of sheaves}$$

Where,

W = Load

P = Effort

VII Actual Circuit diagram used in laboratory with equipment specifications

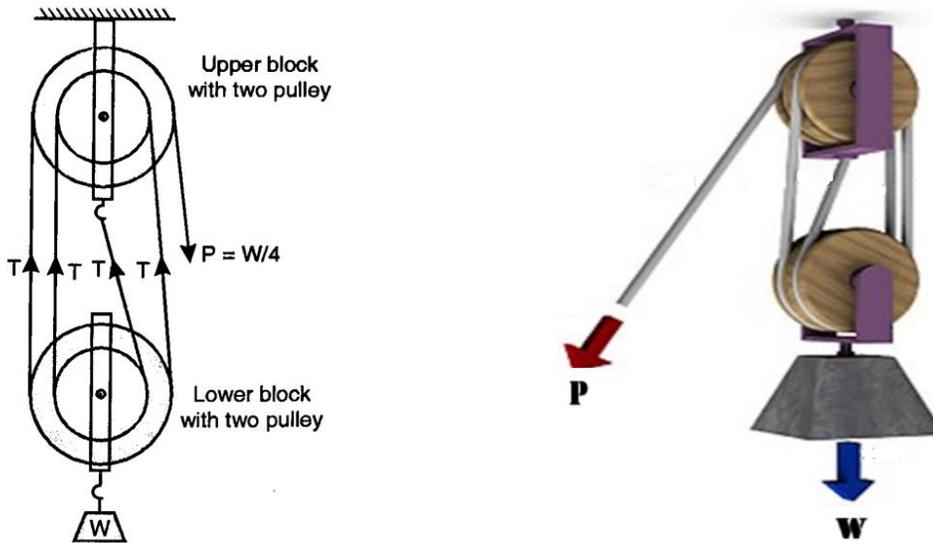


Fig. Two Sheaves Pulley Block

VIII Required Recourses/Apparatus/Equipment with specifications

Sr. No.	Particulars	Broad Specifications	Quantity	Remarks (If Any)
1.	Two sheaves pulley block	Two sheave pulley block consists of a metallic (preferably steel) cogged wheel of about 20 cm along with a protruded load drum of 10 cm diameter to suspend the weights of 10 kg, 20 kg and 50 kg weights.	01 for Group of 4 to 5 students.	

IX Precautions to be followed

1. Effort must be applied gradually

X Procedure

1. Observe the machine carefully and identify the various components of machine.
2. Set the machine and check the reversibility of it.
3. Calculate friction in the given machine at zero load.
4. Apply the load starting with smaller magnitude.
5. Apply the effort for each corresponding load.
6. Record the observations of load and effort in observation table. Take at least five readings.
7. Measure the radius or number of cogs of larger and smaller pulley.

8. Determine M.A., V.R., Efficiency, Ideal effort and Effort lost in friction for given pulley block.
9. Plot graphs load against effort and load against efficiency.

XI Observations and Calculations

$$VR = \frac{W}{\frac{W}{4}} = 4$$

XII Observations Table

Sr. No.	Load W (N)	Effort P (N)	M.A.	Velocity Ratio	Efficiency η (%)	Ideal Effort P_i (N)	Effort Lost in Friction P_f (N)
1							
2							
3							
4							
5							

XIII Sample Calculations

$$M.A. = \frac{\text{Load}}{\text{Effort}} = \frac{W}{P} =$$

$$\text{Efficiency}(\eta) = \frac{M.A.}{V.R.} \times 100\% =$$

$$P_i = \frac{W}{V.R.} =$$

$$P_f = P - P_i =$$

$$\text{Law of machine is } P = mW + C$$

Where,

$$m = \text{Slope} = \frac{P_2 - P_1}{W_2 - W_1} =$$

$$C = \text{Y intercept (i.e. Machine Friction)} = \text{_____N}$$

Sr. No.	Link	Description
1.	https://www.engineersrail.com/simple-lifting-machine/	Introduction of simple lifting machine
2.	https://www.youtube.com/watch?v=kNypk8GReqM	Law of machine and types of machines useful in industry.
3.	https://en.wikipedia.org/wiki/Block_and_tackle	Two sheave Pulley Block image
4.	http://nitttrc.edu.in/nptel/courses/video/112106286/L01.html	Introduction to engineering mechanics

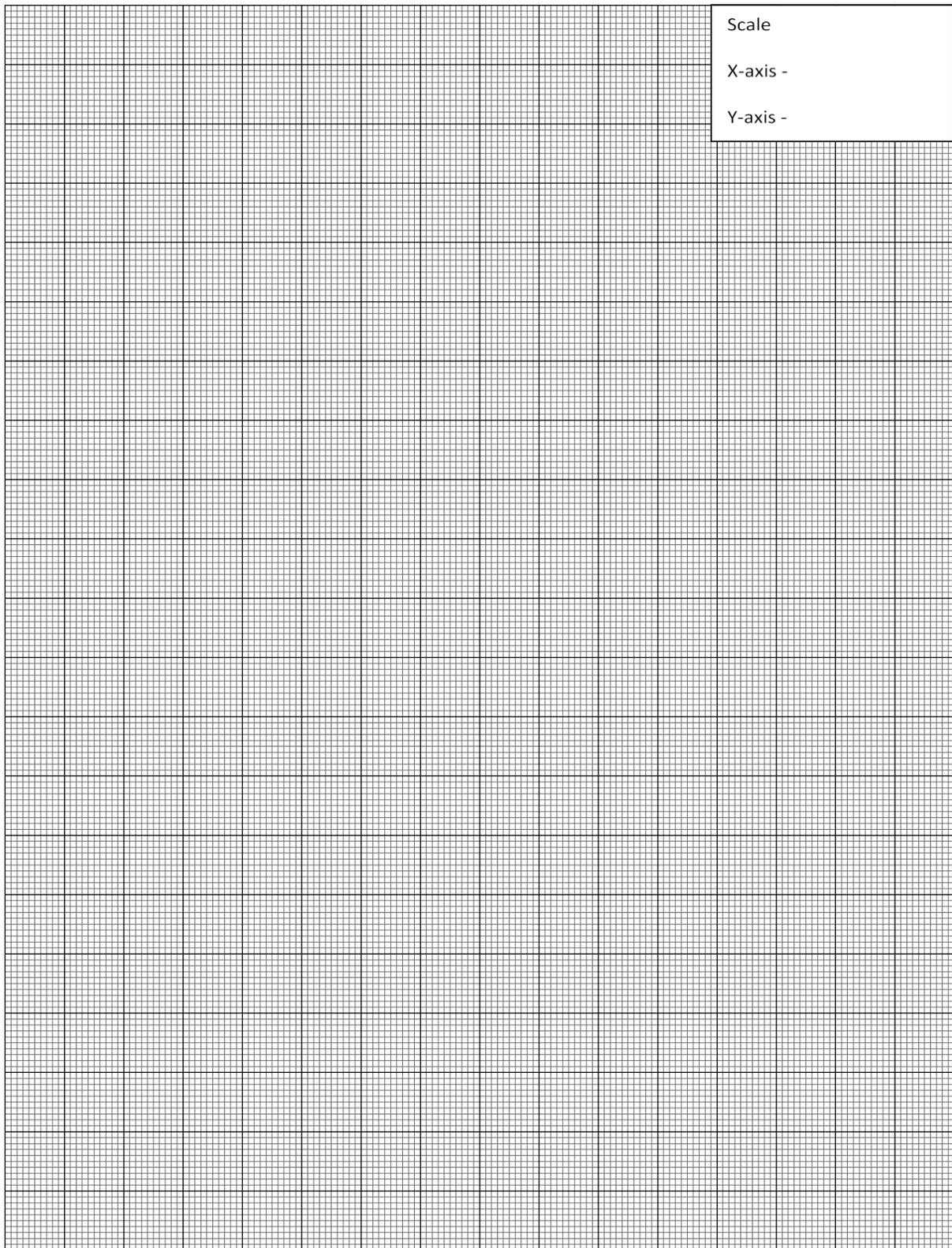
XIX Suggested Assessment Scheme

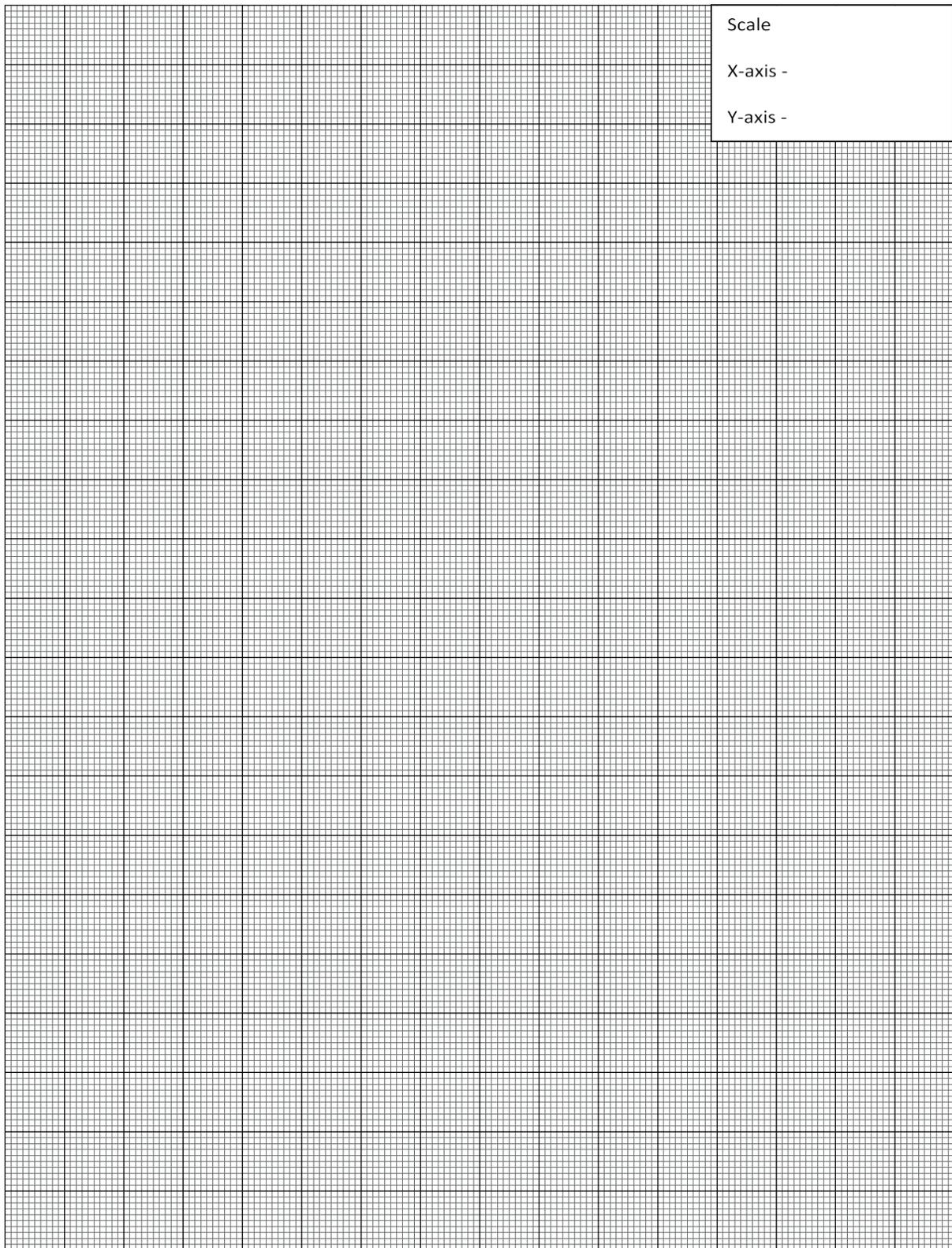
Performance Indicators		Weightage (%)
Process related: 15 Marks		60 %
1	Handling of the machine.	5 %
2	Determination of V. R. of machine.	10 %
3	Applying load and determine effort of machine.	20 %
4	Identify the type of machine i.e. reversible or self-locking.	10 %
5	Calculation of parameters concerned.	10 %
6	Working in team.	5 %
Product related: 10 Marks		40 %
1	Error estimation.	5 %
2	Interpretation of result and graph.	10 %
3	Conclusion and Recommendation.	10 %
4	Answer to the practical related questions.	10 %
5	Submission of report in time.	5 %
Total: 25 Marks		100 %

List of Student team members.

1.
2.
3.
4.

Marks Obtained			Dated sign of Teacher
Process Related(15)	Product Related(10)	Total(25)	





Practical No. 10: Determine mechanical advantage and velocity ratio of three sheave pulley block for different load and efforts.

I. Practical Significance

There is often a need to lift loads and different lifting machines are used depending on the type of load, intensity of the load and other site conditions. Three sheave pulley blocks are used for lifting heavy loads in confined spaces. After conducting this experiment, a graduate engineer will be able to assess the suitability of a three-sheave pulley based on the given load lifting situation.

II. Industry / Employer Expected Outcomes

Apply the principles of engineering mechanics to analyze, design and automation the prototypes and equipment's of various industries

III Course Level Learning Outcome(s)

CO1 Select the suitable machine under given loading condition.

IV Laboratory Learning Outcome(s)

Verify law of machine under the given condition.

V Relevant Affective Domain related Outcome (s)

- a. Follow safety practices and precautions
- b. Demonstrate working as a leader/ a team member.
- c. Maintain tools and equipment.

VI Relevant Theoretical Background

Three Sheave pulley block: It also consists of upper block and lower block each having the pulleys in their sheave; therefore, total number of pulley are six. Upper block is fixed that of lower block is moveable. As the load W is equally shared by the four parts of the rope; tension (T) in each rope is W/P for an ideal machine $M.A. = V.R.$

Hence,

$$\text{Velocity Ratio} = \frac{\text{Distance travelled by effort}}{\text{Distance travelled by load}}$$

$$VR = \frac{W}{\frac{W}{6}} = 6$$

$$\therefore V.R. = 2 \times \text{Number of sheaves}$$

Where,

$W = \text{Load}$

$P = \text{Effort}$

VII Actual Circuit diagram used in laboratory with equipment specifications

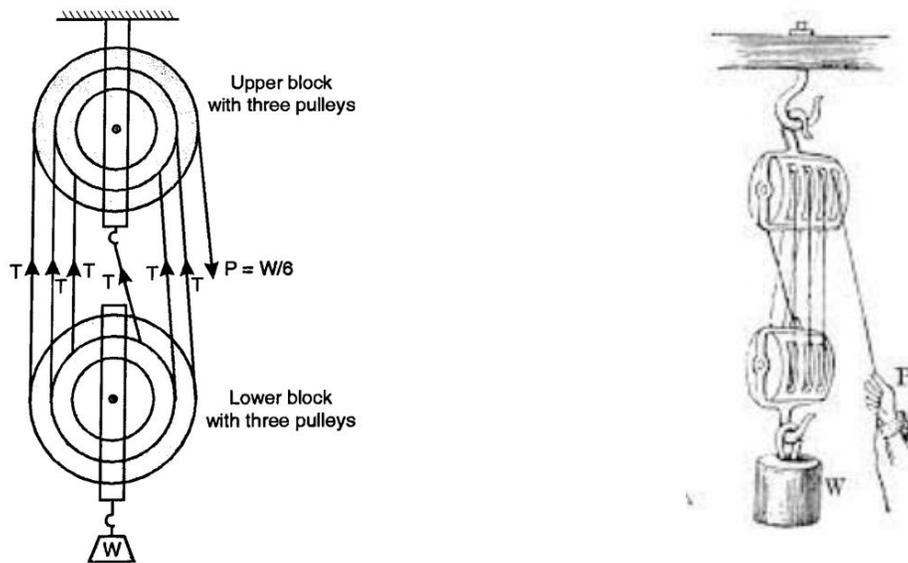


Fig. Three Sheaves Pulley Block

VIII Required Recourses/Apparatus/Equipment with specifications

Sr. No.	Particulars	Broad Specifications	Quantity	Remarks (If Any)
1.	Three sheaves pulley block	Three sheave pulley block consists of a metallic (preferably steel) cogged wheel of about 20 cm along with a protruded load drum of 10 cm diameter to suspend the weights of 10 kg, 20 kg and 50 kg weights.	01 for Group of 4 to 5 students.	

IX Precautions to be followed

1. Effort must be applied gradually

X Procedure

1. Observe the machine carefully and identify the various components of machine.
2. Set the machine and check the reversibility of it.
3. Calculate friction in the given machine at zero load.
4. Apply the load starting with smaller magnitude.
5. Apply the effort for each corresponding load.
6. Record the observations of load and effort in observation table. Take at least five readings.
7. Measure the radius or number of cogs of larger and smaller pulley.

8. Determine M.A., V.R., Efficiency, Ideal effort and Effort lost in friction for given pulley block.
9. Plot graphs load against effort and load against efficiency.

XI Observations and Calculations

$$VR = \frac{W}{\frac{W}{6}} = 6$$

XII Observations Table

Sr. No.	Load W (N)	Effort P (N)	M.A.	Velocity Ratio	Efficiency η (%)	Ideal Effort Pi (N)	Effort Lost in Friction Pf (N)
1							
2							
3							
4							
5							

XIII Sample Calculations

$$M.A. = \frac{\text{Load}}{\text{Effort}} = \frac{W}{P} =$$

$$\text{Efficiency}(\eta) = \frac{M.A.}{V.R.} \times 100\% =$$

$$P_i = \frac{W}{V.R.} =$$

$$P_f = P - P_i =$$

Law of machine is $P = mW + C$

Where,

$$m = \text{Slope} = \frac{P_2 - P_1}{W_2 - W_1} =$$

$C = Y$ intercept (i.e. Machine Friction) = _____N

XIV Results

1. The law of machine is $P = (\dots\dots\dots) W + (\dots\dots\dots) N$
2. The average efficiency of machine is = %

XV Interpretation of results

Machine is

Friction loss is (i.e. Y – intercept =) reduced by the machine.

The graph between load and effort is a straight line which indicates.....

The graph between load and efficiency is a curve which indicates.....

XVI Conclusions and Recommendations

.....

.....

.....

.....

XVII Practical Related Questions

Note: Below given are few sample questions for reference. Teachers must design more such questions so as to ensure the achievement of identified CO. Write answers of minimum three questions.

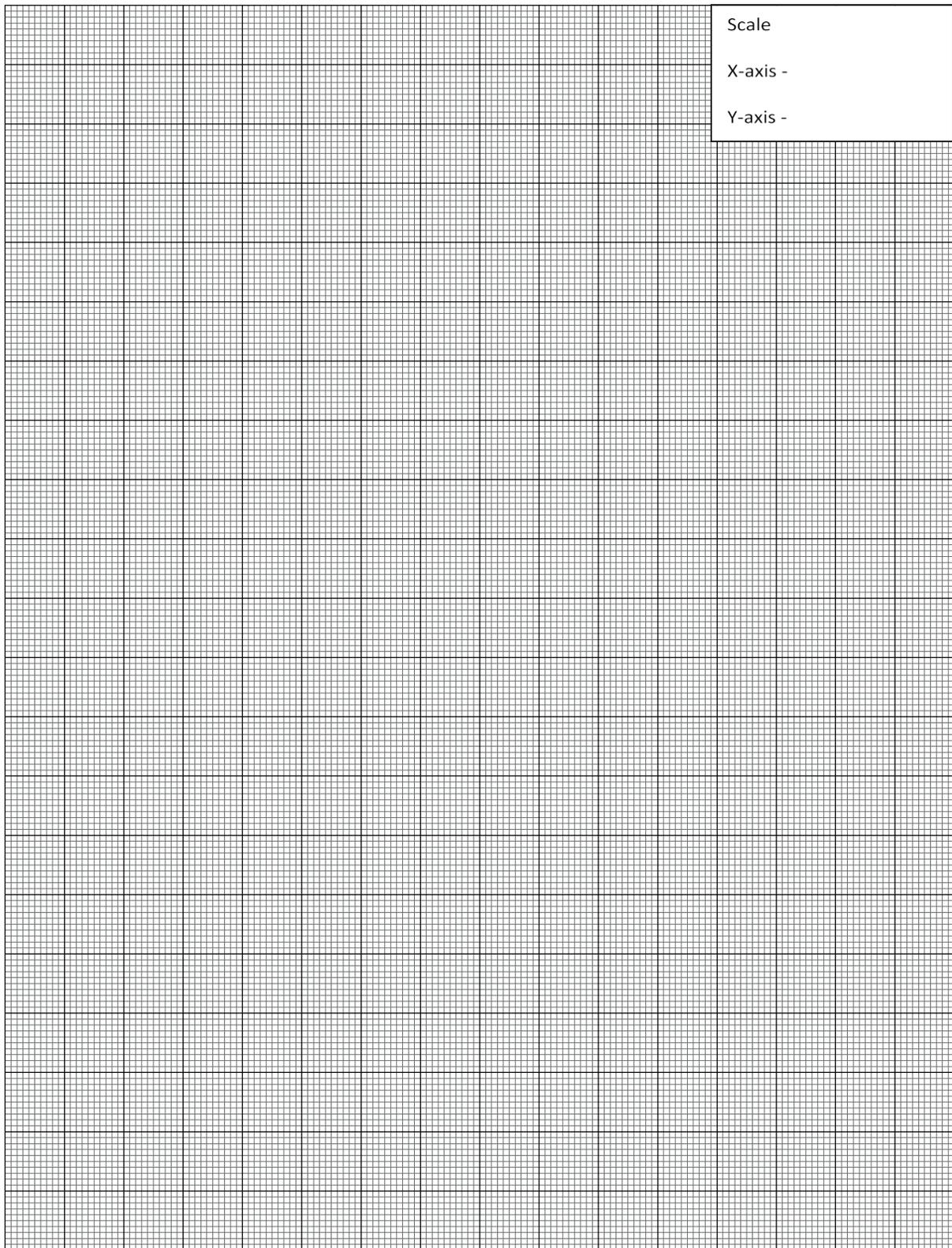
XIX Suggested Assessment Scheme

Performance Indicators		Weightage (%)
Process related: 15 Marks		60 %
1	Handling of the machine.	5 %
2	Determination of V. R. of machine.	10 %
3	Applying load and determine effort of machine.	20 %
4	Identify the type of machine i.e. reversible or self-locking.	10 %
5	Calculation of parameters concerned.	10 %
6	Working in team.	5 %
Product related: 10 Marks		40 %
1	Error estimation.	5 %
2	Interpretation of result and graph.	10 %
3	Conclusion and Recommendation.	10 %
4	Answer to the practical related questions.	10 %
5	Submission of report in time.	5 %
Total: 25 Marks		100 %

List of Student team members.

1.
2.
3.
4.

Marks Obtained			Dated sign of Teacher
Process Related(15)	Product Related(10)	Total(25)	



Practical No.11: Verify law of polygon of forces using Universal force table for given forces.

I. Practical significance

Many times there is a need to determine the resultant force. Depending upon the type of force system resultant can be determined by applying law of polygon of forces. After performing this experiment students will be able to find the resultant of three or more forces by graphically using law of polygon.

II. Industry / Employer Expected Outcome(s)

Apply the principles of engineering mechanics to find resultant of concurrent forces acting on structure (analytically and graphically).

III. Course Level Learning Outcome(s)

CO2 - Analyze the given force system to calculate resultant force

IV. Laboratory Learning Outcome(s)

Analyze the resultant force of given force system.

V. Relevant Affective Domain related Outcome(s)

- Follow safety practices.
- Demonstrate working as a leader/a team member.
- Maintain tools and equipment.

VI. Relevant Theoretical Background

The law states that “If a number of forces acting simultaneously on a particle, be represented in magnitude and direction, by sides of a polygon taken in order, then the resultant of all these forces is represented in magnitude and direction by closing side of polygon taken in opposite direction.”

This experiment is used to study the forces acting on a particle with the help of Universal force table as shown in figure.

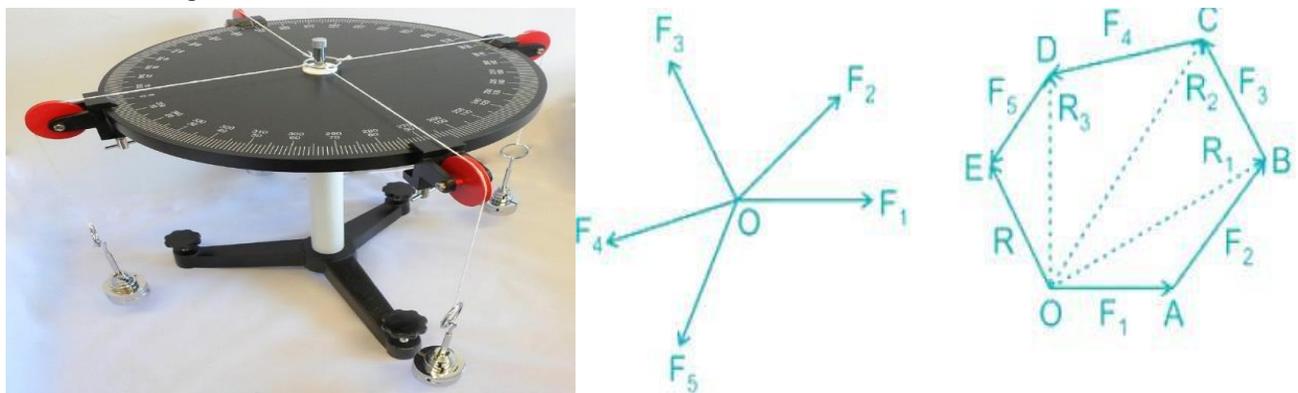


Fig.-Universal Force table

VII. Required Resources/apparatus/equipment with specifications

Sr.No	Particulars	Specification	Quantity	Remark
1	Universal Force Table	It Consists of circular 40cm dia. Aluminium disc, graduated into 360degrees with all accessories	01 for Group of 4 to 5 students	
2	Slotted weights	50gms and 100gms	Three sets of 5 weight each	
3	Cotton String			

VIII. Precautions to be followed

1. All the pulleys should be free from friction.
2. Pivot and ring must be concentric with each other.
3. Angles should be measured carefully.

IX. Procedure

1. Place the universal force table on plane surface. Make the circular disc in horizontal position with the help of foot screws and also check position with spirit level.
2. Attach five pulleys at such position that angle between any two is not very acute angle.
3. Pass the thread on these pulleys as shown in fig & attach the pan to each thread.
4. Put some weights on each pan (or hang slotted weights with each thread) and adjust the weights such that the ring is exactly in the centre under the effect of all this forces.
5. Note the sum of slotted weights in each hanger and weight of hanger and consider it as one force F1 and next forces F2, F3, F4, F5 in order. Also note down angle between them.
6. Repeat the step 5 by changing any one or two pulleys position and take three set of observation and Select a suitable scale & draw a polygon taking the forces in order.
7. Since all forces are in equilibrium the polygon shall be closed one.
8. If the polygon is not closed one calculate the closing error by analytical and graphical method.

X. Observation table

Obs. No.	Magnitude of Forces in (N) (Weight in hanger +Weight of hanger)					Angles between two forces in(degree)					
	F1	F2	F3	F4	F5 (From graph)	θ_1	θ_2	θ_3	θ_4	θ_5	θ_5 From graph
1											
2											
3											

Sr. No.	Link	Description
1.	https://youtu.be/vUCDoIRZrxM?si=uPjz6sF6uSyO19Of	Law of Parallelogram of forces.
2.	https://youtu.be/qYhhWHIikLY?si=OvTv02X9NYIV1xOd	Application of Lamis theorem
3.	https://www.youtube.com/watch?v=Fudcc0JoXdo	Force System
4.	https://www.youtube.com/watch?v=ljDIIMvx-eg	Equilibrium of Rigid bodies

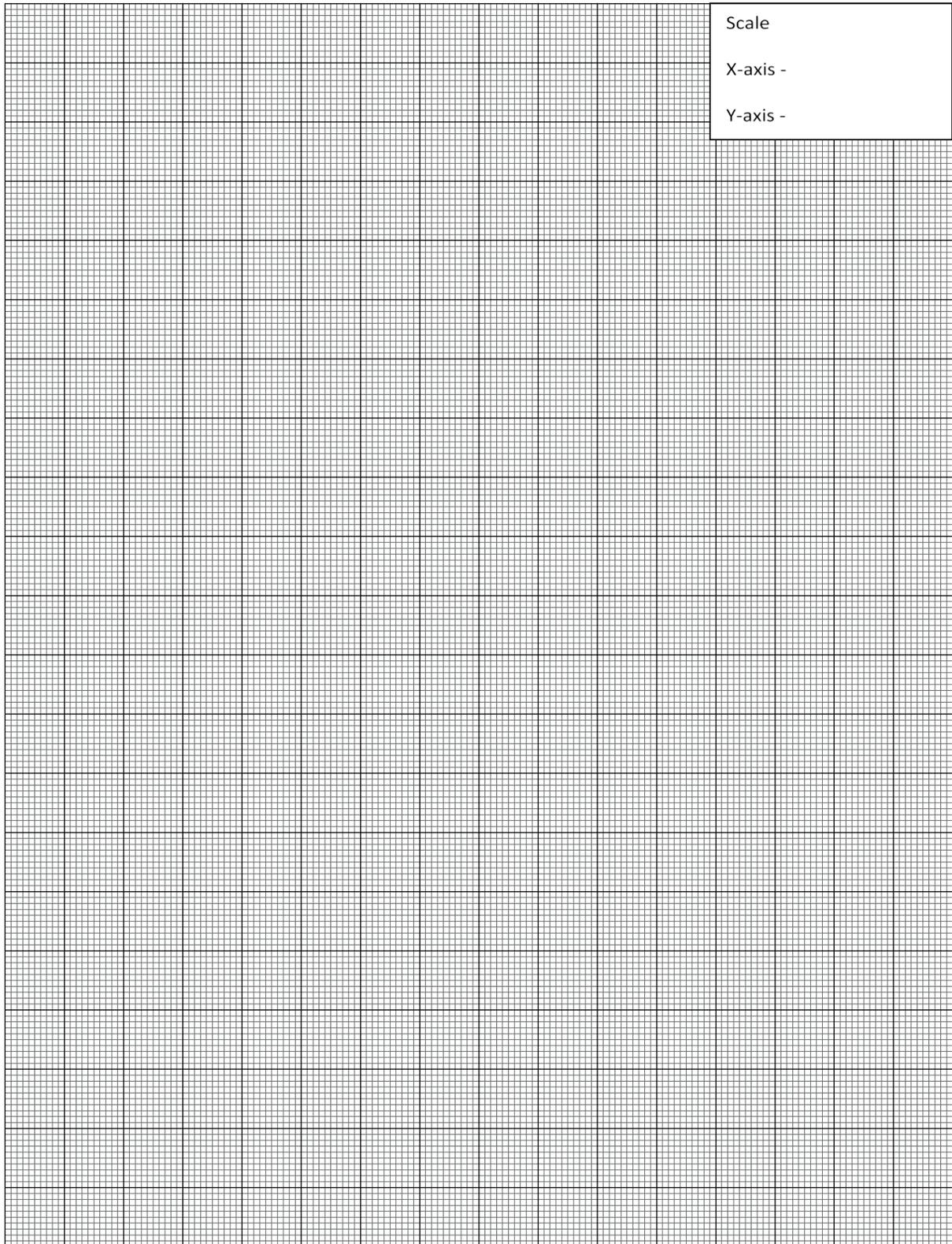
XVI. Suggested Assessment Scheme

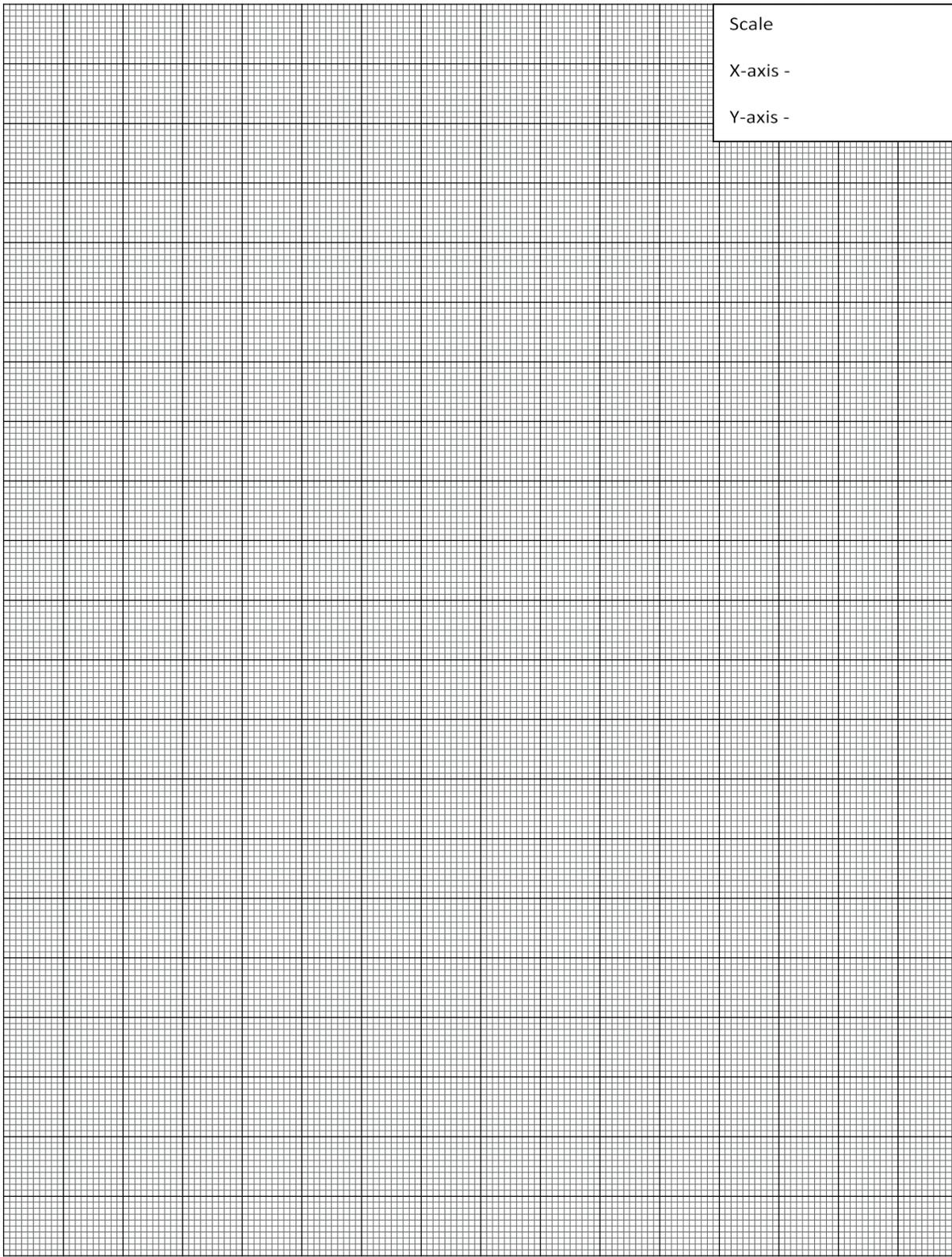
Performance Indicators		Weightage (%)
Process related: 15 Marks		60 %
1	Handling of the machine.	5 %
2	Calculation of force.	10 %
3	Measurement of angle.	10 %
4	Proper Reading	10 %
5	Calculation of parameters concerned.	10 %
6	Drawing force polygon	10%
7	Working in team.	5 %
Product related: 10 Marks		40 %
1	Error estimation.	5 %
2	Interpretation of result and graph.	10 %
3	Conclusion and Recommendation.	10 %
4	Answer to the practical related questions.	10 %
5	Submission of report in time.	5 %
Total: 25 Marks		100 %

List of Student team members.

1.
2.
3.
4.

Marks Obtained			Dated sign of Teacher	
Process Related(15)	Product Related(10)	Total(25)		



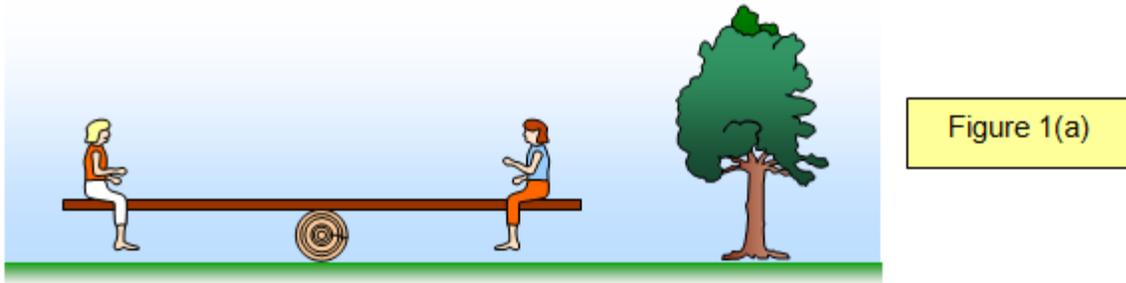


Practical No.12: Verify law of moment of forces using law of moment apparatus for given forces.

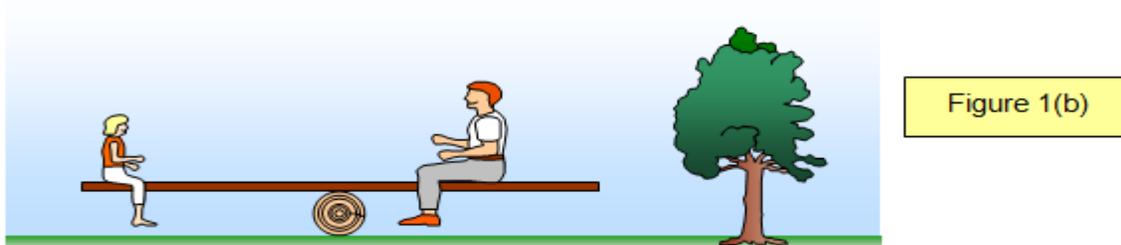
I. Practical significance

The Principle of Moments states that when a body is balanced, the total clockwise moment about a point equals the total anticlockwise moment about the same point. The real examples on moment of force in real life are the opening and closing of a door along a fixed hinge, a seesaw, and unscrewing a nut with a spanner.

When an object is balanced on a pivot the turning effect of the forces on one side of the pivot must balance the turning effect of the forces on the other side of the pivot - if they didn't it would not balance. In the picture (Figure 1(a)) two girls are sitting on a see saw. They have moved until it is balanced. They are the same weight and so to balance the see saw they must sit the same distance from the pivot.



In the picture (Figure 1(b)) one of the girls gets off and a man sits on instead. They move until the see saw is balanced. The girl is much lighter than the man and so she has to sit further away from the pivot than he does so that she can balance his extra weight.



You should remember that the turning effect of a force is called the moment of the force and is found by multiplying the force by its distance from the pivot. When the see saw is balanced we say that the anticlockwise moments (those trying to turn the object anticlockwise) equal the clockwise moments (those trying to turn the object clockwise). In our example the man's weight tries to turn the see saw clockwise and the girl's weight tries to turn it anticlockwise.

II. Industry / Employer Expected Outcome(s)

Moment of force has numerous applications in various fields of science and engineering, including in automobiles (torque is used to measure the power output of an engine), in robotics, torque is

used to control the movement of robot arms and joints. Industrial machinery, torque is used to measure the effectiveness of machines. Moment of force is used in sports such as gymnastics, diving, and ice skating to perform complex rotational movements. Moment of force is used in biology to understand the mechanics of biological systems, such as the motion of joints in the human body.

III. Course Level Learning Outcome(s)

CO2-Analyze the given force system to calculate resultant force.

IV. Laboratory Learning Outcome(s)

Analyse the resultant force of given force system.

V. Relevant Affective Domain related Outcome(s)

- Follow safety practices
- Demonstrate working as a leader/a team member.
- Maintain tools and equipment.

VI. Relevant Theoretical Background (with diagrams if required)

The Principle of Moments states that when a body is balanced, the total clockwise moment about a point equals the total anticlockwise moment about the same point. Clockwise and Anticlockwise moment example as shown below.

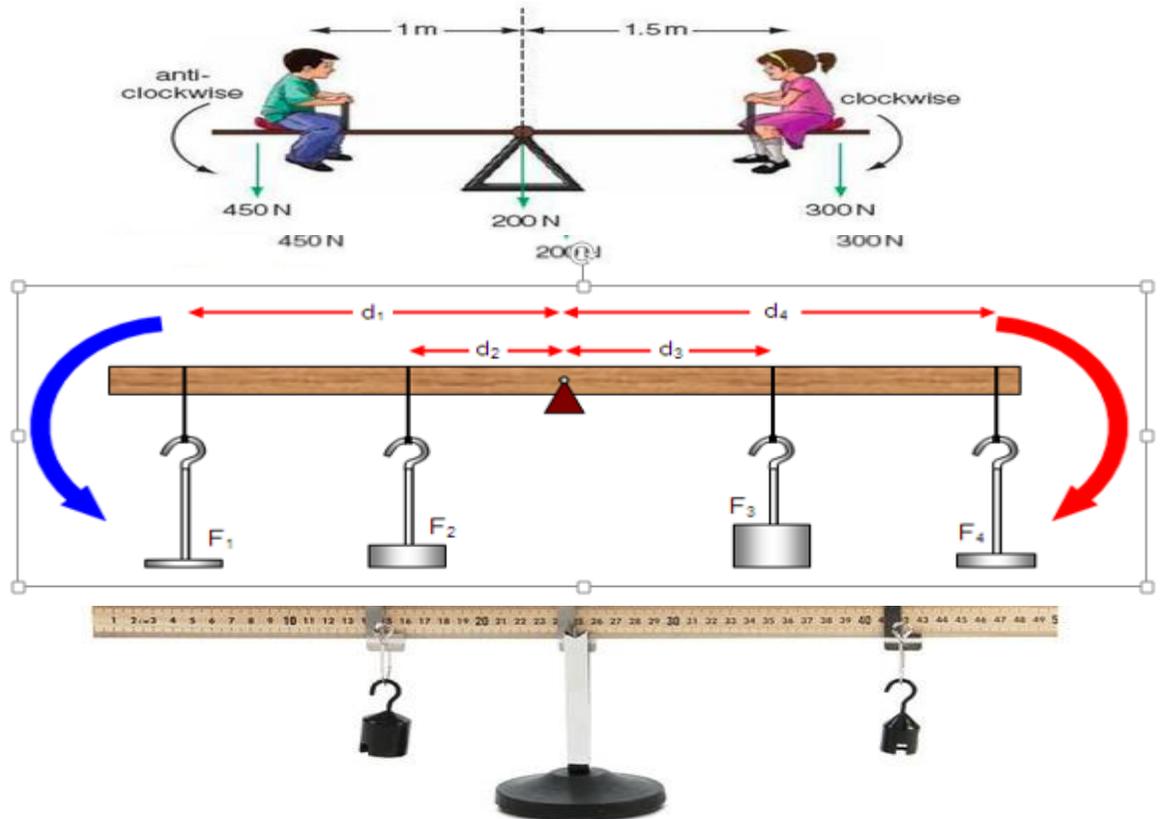


Fig. Law of moment Apparatus

The Above diagram (Figure 3) shows the effect of having more than one force on each side of the pivot. The Law of Moment is given by $F_1d_1+F_2d_2= F_3d_3+F_4d_4$

VII. Required Resources/apparatus/equipment with specifications.

Sr.No	Particulars	Specification	Quantity	Remark
1	Meter rule	With small hole drilled at 50cm mark.	01 for Group of 4 to 5 students	
2	Smooth optical pin	At least 5cm Long	01	
3	Slotted weights	50gms and 100gms	Three sets of 5 weight each	
4	Split cork		01	

VIII. Precautions to be followed.

1. Meter rule should be perfectly horizontal.
2. Pivot should be at the center.
3. Weight should be place properly at required distance.

IX. Procedure.

1. Place unequal weights on each side of the pivot.
2. Move the weight until the meter rule balances.
3. When this occurs take note of the anti-clockwise and clockwise moments.
4. Repeat several times by changing distance on each side. And take more sets of observations.

X. Observation table

Sr.No	Force $F_1(N)$	Force $F_2(N)$	Distance $d_1(cm)$	Distance $d_2(cm)$	Anti-clockwise Moment $F_1 d_1(N-cm)$	Clockwise Moment $F_2 d_2 (N-cm)$
1						
2						
3						
4						
5						

XI. Results

1. Anticlockwise moment and Clockwise moment are.....
(Equal/Nearly eual/Not equal).
2. The difference in anticlockwise moment and Clockwise moment is because of (Error of manipulation/Instrument error/observation error).

Sr.No	Link	Discription
1	https://www.schoolphysics.co.uk/age11-14/Mechanics/Statics/text/Balancing_/index.html	See saw example of law of moment

XVII. Suggested Assessment Scheme

Performance Indicators		Weightage (%)
Process related: 15 Marks		60 %
1	Handling of the machine.	5 %
2	Application of different weights at different locations.	15 %
3	Observation of weights and distances.	10 %
4	Measuring of weights and distances.	10 %
5	Calculation of clockwise and anticlockwise moments.	15 %
6	Working in team.	5 %
Product related: 10 Marks		40 %
1	Error estimation.	5 %
2	Interpretation of result and graph.	10 %
3	Conclusion and Recommendation.	10 %
4	Answer to the practical related questions.	10 %
5	Submission of report in time.	5 %
Total: 25 Marks		100 %

List of Student team members.

1.
2.
3.
4.

Marks Obtained			Dated sign of Teacher
Process Related(15)	Product Related(10)	Total(25)	

Practical No.13: Verify Varignon's theorem of moments of force using law of moment apparatus for given forces.

I. Practical significance

Varignon's theorem has various applications in field of engineering. In Civil Varignon's theorem is used in analyzing the forces and moments in structures such as dams, bridges, buildings, structural elements beams, trusses, and frames. By replacing the distributed forces with an equivalent resultant force, it helps to determine the overall moment and its effect on the structure.

In mechanical engineering, Varignon's theorem helps to analyze the forces and moments acting on mechanical systems, such as linkages, levers, and pulleys. By using the Varignon's theorem, we can determine the resultant forces and moments at specific points, helping in the calculation of required torques, balancing systems, and optimizing mechanical designs.

II. Industry / Employer Expected Outcome(s)

Apply the principles of engineering mechanics to find resultant of Parallel forces which are acting on structure.

III. Course Level Learning Outcome(s)

CO2-Analyze the given force system to calculate resultant force.

IV. Laboratory Learning Outcome(s)

Analyse the resultant force of given force system.

V. Relevant Affective Domain related Outcome(s)

- Follow safety practices
- Demonstrate working as a leader/a team member.
- Maintain tools and equipment.

VI. Relevant Theoretical Background (with diagrams if required)

It states "If a number of coplanar forces are acting simultaneously on a body, the algebraic sum of the moments of all the forces about any point is equal to the moment of their resultant force about the same point."

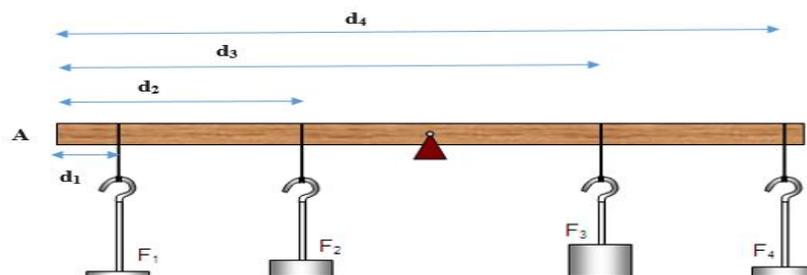


Fig.Law of moment Apparatus

VII. Required Resources/apparatus/equipment with specifications.

Sr.No	Particulars	Specification	Quantity	Remark
1	Meter rule	With small hole drilled at 50cm mark.	01 for Group of 4 to 5 students	
2	Smooth optical pin	At least 5cm Long	01	
3	Weights	50g,100g masses	5 No each	
4	Split cork		01	

VIII. Precautions to be followed.

1. Meter rule should be perfectly horizontal.
2. Pivot should be at the centre.
3. Weight should be place properly at required distance.

IX. Procedure.

1. Place four unequal weights on meter rule.
2. Move the weight until the meter rule balances.
3. When this occurs note down values for forces in observation table.
4. Mark distance from starting point of meter rule to the first force as (d_1) and mark same for all other remaining forces.
5. Repeat same process several times by changing distance and no of weights on meter rule. And take more sets of observations.

X. Observation table

Sr.No	Force(N)				Resultant $R(\sum FY)=$	Distance (cm)				Moment @A= $(F_1 d_1 + F_2 d_2 + F_3 d_3 + F_4 d_4)$	Distance $R_x = \text{Moment}$ $x = \text{Moment}/R$	
	F_1	F_2	F_3	F_4		d_1	d_2	d_3	d_4			
1												
2												
3												
4												
5												

XV. References/Suggestions for further reading: include websites/links

Sr.No	Title of Book	Author	Publication
1	Engineering Mechanics	R. S. Khurmi,N.Khurmi	S.Chand&Co.NewDelhi2018ISBN:978-9352833962
2	Engineering Mechanics	S.Ramamrutham	DhanpatRaiPublishingCo.2016ISBN-13:978-9352164271
3	Engineering Mechanics	S. S. Bhavikatti	New Age International Private Limited ISBN: 978-9388818698
4	Engineering Mechanics	D. S. Bedi, M. P.Poonia	Khanna Publishing ISBN-13:978-9386173263

XVI. Suggested Assessment Scheme

Performance Indicators		Weightage (%)
Process related: 15 Marks		60 %
1	Handling of the machine.	5 %
2	Application of different weights at different locations.	15 %
3	Observation of weights and distances.	15 %
4	Measuring of weights and distances.	20 %
5	Working in team.	05 %
Product related: 10 Marks		40 %
1	Error estimation.	5 %
2	Interpretation of result and graph.	10 %
3	Conclusion and Recommendation.	10 %
4	Answer to the practical related questions.	10 %
5	Submission of report in time.	5 %
Total: 25 Marks		100 %

List of Student team members.

1.
2.
3.
4.

Marks Obtained			Dated sign of Teacher
Process Related(15)	Product Related(10)	Total(25)	

Practical No.14: Determine graphically the resultant force of given concurrent force system.**I. Practical significance**

The graphical method is a method of solving equations involving more than one variable using the Cartesian coordinate system. In engineering, the use of the graphical method is limited to the problems involving two variables. The graphical method has a great impact in solving the questions regarding engineering mechanics. In engineering mechanics, graphical methods can be used in the following topics: Triangle and Polygon Laws of Forces, Representation of Space diagram, Vector diagram, and Bow's notation, Resultant of Forces, Equilibrium of Coplanar Forces. This method is use when force system is complicated.

II. Industry / Employer Expected Outcome(s)

Apply the principles of engineering mechanics to find resultant of concurrent forces acting on structure (analytically and graphically).

III. Course Level Learning Outcome(s)

CO2 - Analyze the given force system to calculate resultant force.

IV. Laboratory Learning Outcome(s)

Analyse the resultant force of given force system.

V. Relevant Affective Domain related Outcome(s)

- a. Follow safety practices
- b Demonstrate working as a leader/a team member.
- c. Maintain drawing tools.

VI. Relevant Theoretical Background

The force can be represented using the graphical method. To represent the force in graphs, a straight line is used and an arrowhead is used to represent the direction of the force. The diagram that shows the forces in space is known as the space diagram. In the space diagram, all the forces acting in space are represented with the help of straight lines, and arrowheads are used to represent their directions. A vector diagram is a diagram drawn in the X-Y plane of a Cartesian coordinate system using a suitable scale to represent the forces in terms of both magnitude and directions.

Bow's notation: Bow's notations. According to this notation a force is designated by two capital letters which are written on either side of the line of action of the force. A force with letters L and M on either side of the line of section is shown.

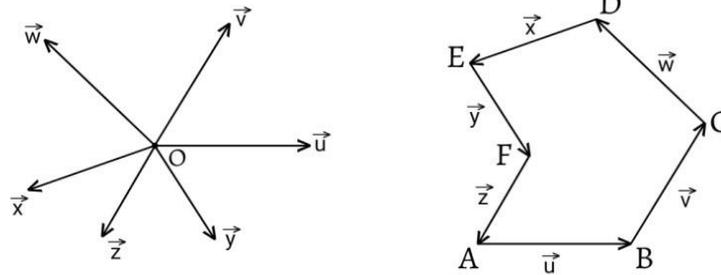


Fig. Space and Vector diagram

VII. Required Resources/apparatus/equipment with specifications

Sr.No	Particulars	Specification	Quantity	Remrk
01	Drawing Sheet with drawing instruments	Pencil, Eraser, straight Edge, Sets Square, Mini Drafter.	1 set for each student	

VIII. Precautions to be followed

While drawing the diagram accuracy should be maintained.

IX. Procedure

1. Draw space Diagram of given force system by choosing suitable scale. Give Bow's notation.
2. Construct Vector diagram by selecting suitable scale for forces by drawing lines parallel to line of action of Space Diagram in sequence.
3. If the vector diagram is closed figure then resultant of the force system is zero, if not follow next step.
4. Determine the resultant force in magnitude, which is represented by closing side of vector diagram.
5. Show the direction of resultant force, which is from beginning of first vector force to the end of last vector force in vector diagram.
6. Show the position of resultant force in space diagram by drawing line parallel to the closing side of vector diagram and passing through common point of application of all the forces.
7. Measure the angle (θ) made by the resultant force with horizontal in the space diagram.

X. Observation (Use blank sheet provided if space not sufficient)

Resultant force = (Length of closing side) \times (Scale multiplying factor)

XI. Result(s)

1. Magnitude of Resultant force =.....
2. Direction of the Resultant force with Horizontal =.....
3. Position of Resultant force=.....

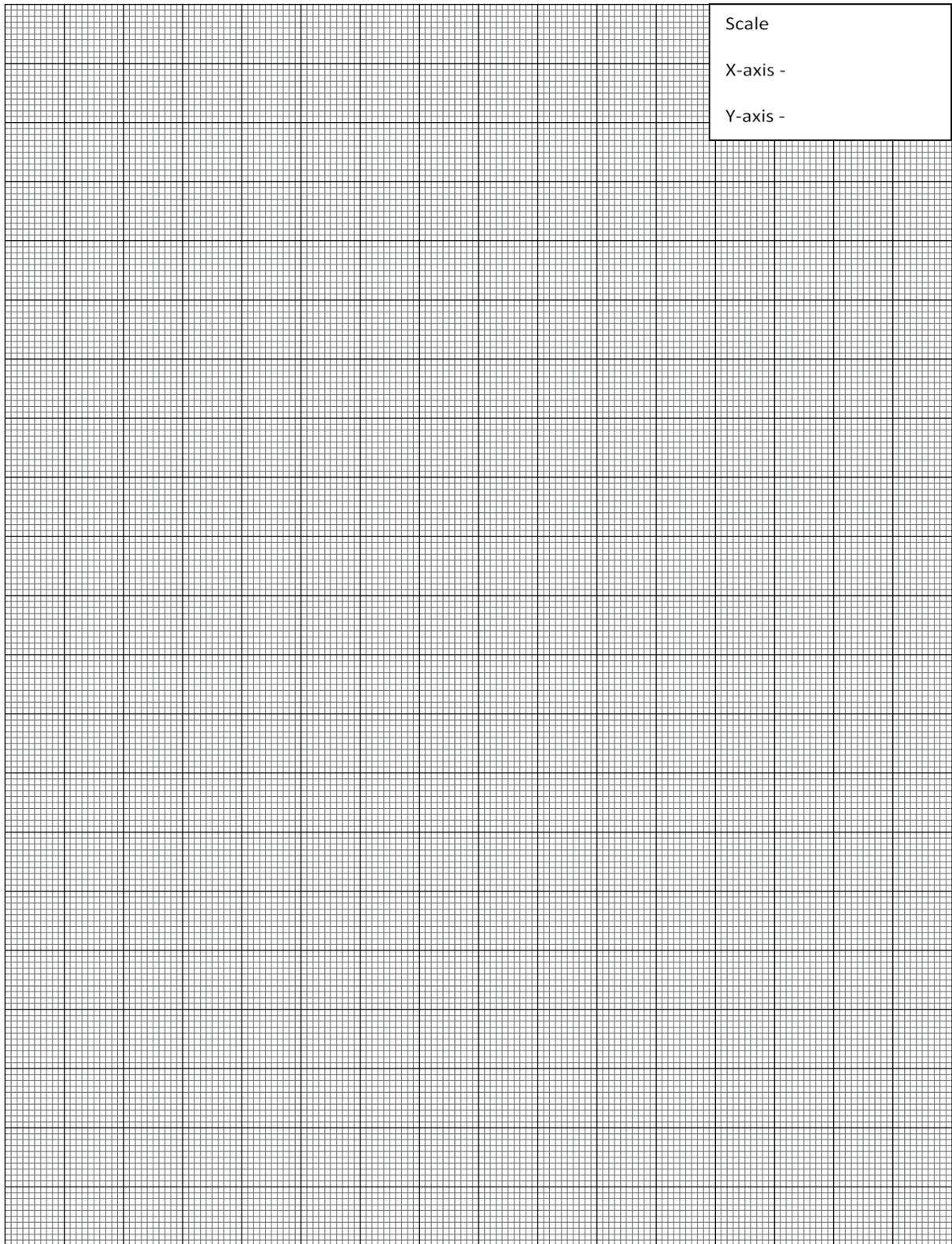
XVI. Suggested Assessment Scheme

Performance Indicators		Weightage (%)
Process related: 15 Marks		60 %
1	Proper use of drawing instrument	5 %
2	Calculation of force.	10 %
3	Measurement of angle.	10 %
4	Proper reading.	10 %
5	Calculation of parameter concerned.	10 %
6	Drawing of force polygon.	10 %
7.	Working in team.	5 %
Product related: 10 Marks		40 %
1	Error estimation.	5 %
2	Interpretation of result and graph.	10 %
3	Conclusion and Recommendation.	10 %
4	Answer to the practical related questions.	10 %
5	Submission of report in time.	5 %
Total: 25 Marks		100 %

List of Student team members.

1.
2.
3.
4.

Marks Obtained			Dated sign of Teacher
Process Related(15)	Product Related(10)	Total(25)	



Practical No.15: Determine graphically the resultant force of given parallel force system.**I. Practical significance**

The graphical method is a method of solving equations involving more than one variable using the Cartesian coordinate system. In engineering, the use of the graphical method is limited to the problems involving two variables. The graphical method has a great impact in solving the questions regarding engineering mechanics. In engineering mechanics, graphical methods can be used in the following topics: Triangle and Polygon Laws of Forces, Representation of Space diagram, Vector diagram, and Bow's notation, Resultant of Forces, Equilibrium of Coplanar Forces. Graphical method is use when force system is complicated.

II. Industry / Employer Expected Outcome(s)

Apply the principles of engineering mechanics to find resultant of parallel forces acting on structure (analytically and graphically).

III. Course Level Learning Outcome(s)

CO2-Analyze the given force system to calculate resultant force.

IV. Laboratory Learning Outcome(s)

Analyse the resultant force of given force system.

V. Relevant Affective Domain related Outcome(s)

- a. Follow safety practices
- b. Demonstrate working as a leader/a team member.
- c. Maintain drawing tools.

VI. Relevant Theoretical Background (with diagrams if required)

The force can be represented using the graphical method. To represent the force in graphs, a straight line is used and an arrowhead is used to represent the direction of the force. The diagram that shows the forces in space is known as the space diagram. In the space diagram, all the forces acting in space are represented with the help of straight lines, and arrowheads are used to represent their directions.

Vector Diagram:

It is a diagram drawn in the X-Y plane of a Cartesian coordinate system using a suitable scale to represent the forces in terms of both magnitude and directions.

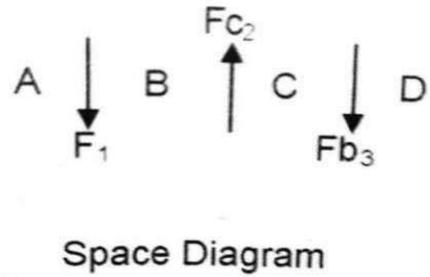
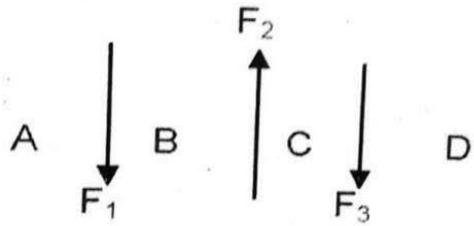
Polar Diagram:

It is the diagram obtained by joining beginning an end of all forces of vector diagram to any arbitrary point 'O' called pole.

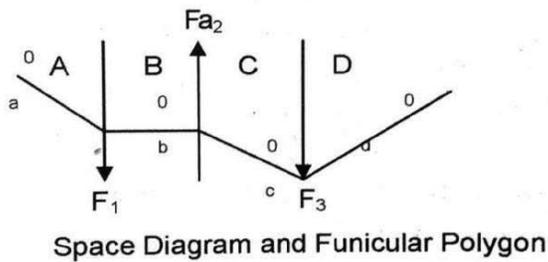
Funicular Polygon: It is figure obtained by drawing lines parallel to rays oa,ob,od etc. of polar diagram in respective space A,B,C,D etc. in space diagram.

Bow's notation

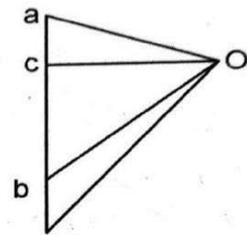
According to this notation a force is designated by two capital letters which are written on either side of the line of action of the force.



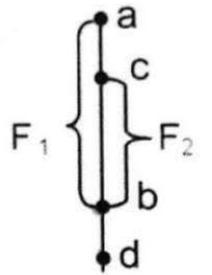
Space Diagram



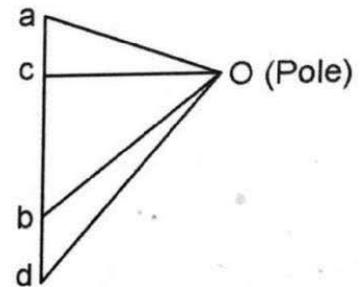
Space Diagram and Funicular Polygon



Vector Diagram and Polar Diagram



Vector Diagram



Vector Diagram and Polar Diagram

VII. Required Resources/apparatus/equipment with specifications

Sr.No	Particulars	Specification		Quantity	Remrk
01	Drawing Sheet with drawing instruments	Pencil, Eraser, straight Edge, Sets Square, Mini Drafter.		1 set for each student	

VIII. Precautions to be followed

While drawing the diagram accuracy should be maintained.

IX. Procedure

1. Draw space diagram of given force system by choosing suitable scale for distance. Also give Bow's notation.
2. Construct Vector diagram by selecting suitable scale for forces by drawing lines parallel to line of action of Space Diagram in sequence.
3. If the vector diagram is closed figure then resultant of the force system is zero, if not follow next step.
4. Determine the resultant force in magnitude, which is represented by closing side of vector diagram use following equation.
5. Show the direction of resultant force, which is from beginning of first vector force to the end point of last vector force in vector diagram.
6. Select any arbitrary point called pole in vector diagram and join beginning and end point of all forces to the pole to obtain polar diagram.
7. Draw lines parallel to rays of polar diagram in their respective spaces (i.e. ray oa in space A, ray ob in space B, and so on) and in continuation with each other. This diagram obtained is called Funicular polygon.
8. Extend first and last rays down in funicular polygon to meet at single point. This is the point through which lines of action of resultant force will pass.
9. Locate resultant force in space diagram by drawing line parallel to closing side (resultant) of vector diagram passing through the point as obtained in step 4.
10. Measure the angle made by resultant with horizontal.
11. Measure the perpendicular of resultant force from any known point in space diagram.

X. Observation (Use blank sheet provided if space not sufficient)

Resultant force=(Length of closing side) ×(Scale multiplying factor)

XI. Result(s)

1. Magnitude of Resultant force =.....
2. Direction of the Resultant force with Horizontal =.....
3. Position of Resultant force=.....

XII. Interpretation of results

Compare the above result analytically.

.....
.....

XIII. Conclusions and recommendation

.....
.....

XIV. Practical related questions

Note: Below given are few sample questions for reference. Teachers must design more such questions so as to ensure the achievement of identified CO. Write answers of minimum three questions.

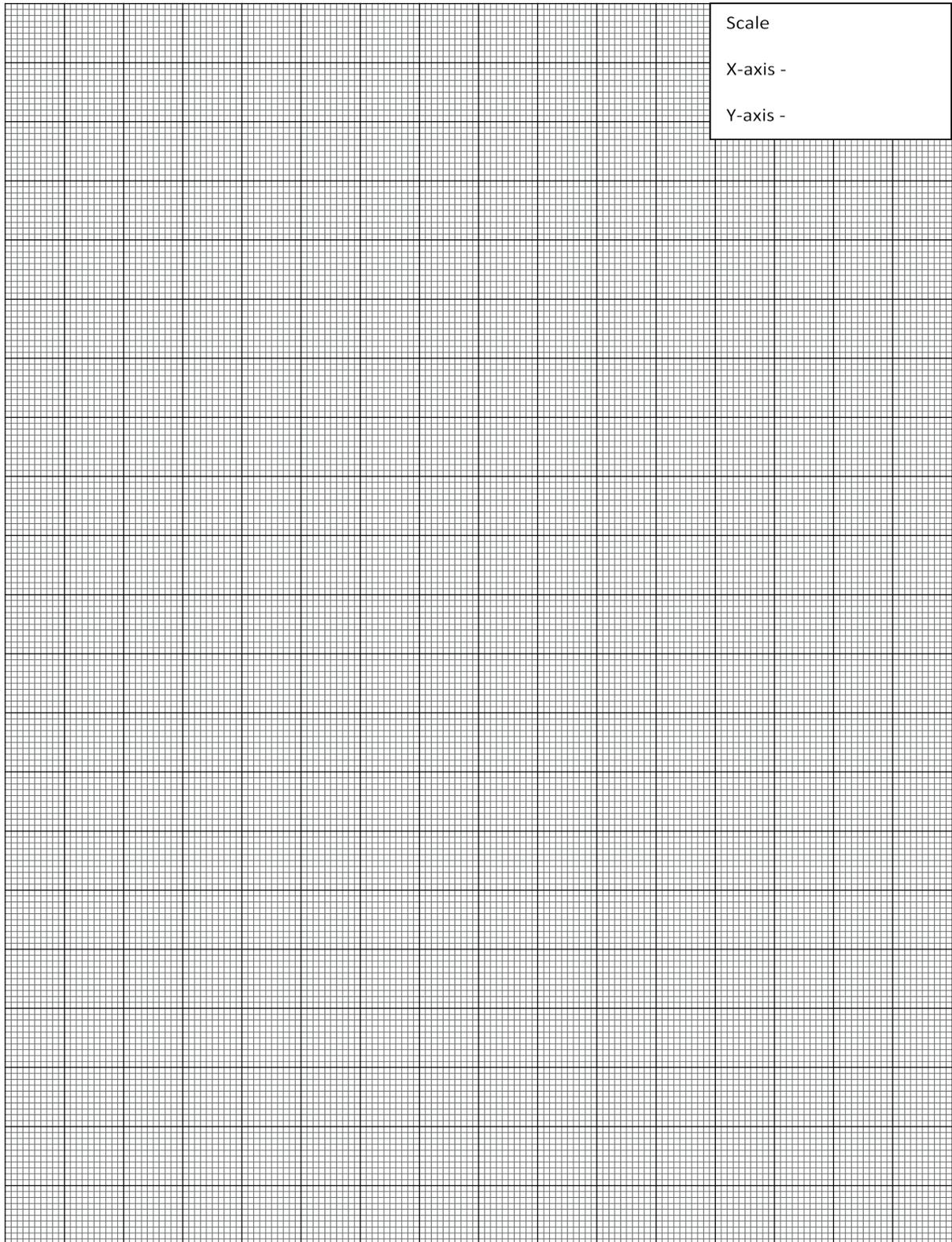
XVI. Suggested Assessment Scheme

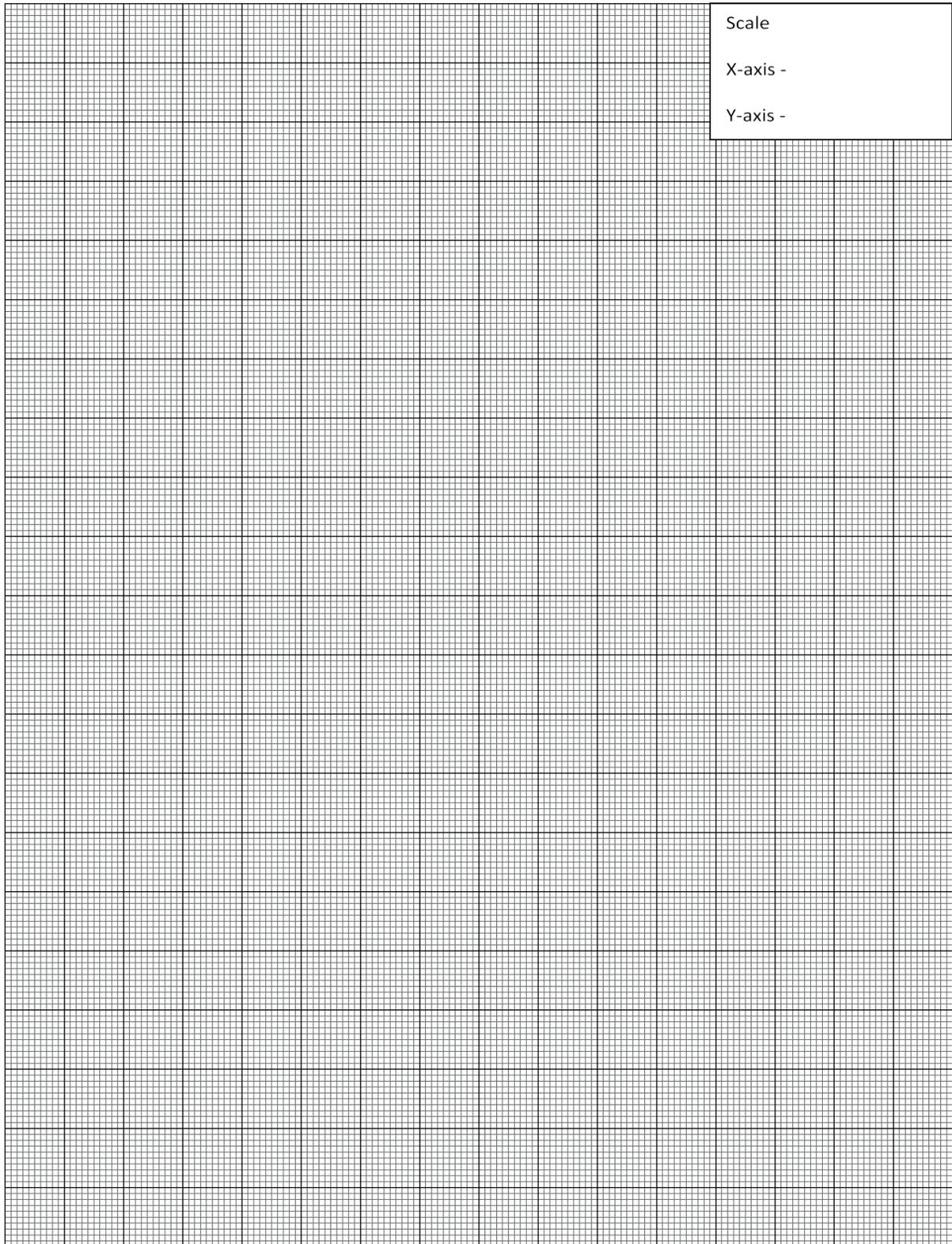
Performance Indicators		Weightage (%)
Process related: 15 Marks		60 %
1	Proper use of drawing instrument	5 %
2	Giving Bow's notation and drawing Space diagram	10 %
3	Drawing Vector diagram.	10 %
4	Drawing Funicular polygon.	10 %
5	Calculation of magnitude and direction of resultant force.	10 %
6	Location position of Resultant force.	10 %
7.	Working in team.	5 %
Product related: 10 Marks		40 %
1	Error estimation.	5 %
2	Interpretation of result and graph.	10 %
3	Conclusion and Recommendation.	10 %
4	Answer to the practical related questions.	10 %
5	Submission of report in time.	5 %
Total: 25 Marks		100 %

List of Student team members.

1.
2.
3.
4.

Marks Obtained			Dated sign of Teacher
Process Related(15)	Product Related(10)	Total(25)	





Practical No.16: Verify the Lami's theorem using Universal force table apparatus for given forces.

I. Practical significance

Lami's theorem relates the magnitudes of coplanar, concurrent and non-collinear forces that maintain an object in static equilibrium. The theorem is very useful in analyzing most of the mechanical as well as structural systems.

Lami's theorem has been obtained from the Sine Rule for triangles. By representing the forces as lines as in a free-body diagram and translating them in such a way that one head touches the tail of another, then it will be noticed that when there are three forces, if they are supposed to cancel each other, they resultantly form a triangle. If they are not supposed to cancel each other, they form an open curve. The Sine Rule is only applicable for triangles only and hence Lami's Theorem is only applicable to three forces, but not for the 'n' number of forces.

II. Industry / Employer Expected Outcome(s)

After Studying this Practical Students will be able to find tension in string in three coplanar, concurrent forces.

III. Course Level Learning Outcome(s)

CO3 - Determine unknown force(s) of given load combinations in the given situation.

IV. Laboratory Learning Outcome(s)

Analyse the resultant force of given force system.

V. Relevant Affective Domain related Outcome(s)

- a. Follow safety practices.
- b. Demonstrate working as a leader/a team member.
- c. Maintain tools and equipment.

VI. Relevant Theoretical Background (with diagrams if required)

If three coplanar forces acting at a point are in equilibrium then each force is directly proportional to the Sin of the angle included between the other two forces. By using simple weights, pulleys & strings placed around a circular table, several forces can be applied to an object located in the centre of the table in such a way that the forces exactly cancel each other, leaving the objects in equilibrium (the object will appear to be at rest). Force table and Newton's First Law is used to study the components at the force vector.

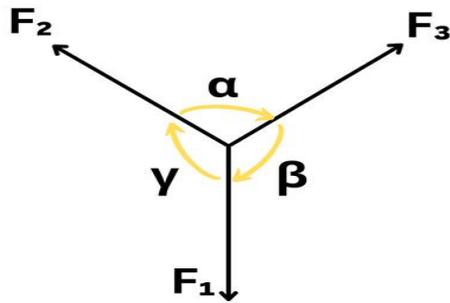


Fig. Universal force table

VII. Required Resources/apparatus/equipment with specifications

Sr.No	Particulars	Specification	Quantity	Remark
1	Universal Force table	Circular graduated disc supported on rd and the assembly supported on three adjustable screws	01 for Group of 4to5 students	
2	Circular ring of metal tied to the three strings.		One ring Three strings.	
3	Load Hanger	50gms and 100gms	3Nos each	
4	Slotted weights	50gms and 100gms	Three sets of 5 weight each	
5	Spirit level	10cm Long	One	

VIII. Precautions to be followed

1. Hangers should sit in pulleys properly.
2. All the pulleys should be free from friction.
3. Force table should be perfectly horizontal.
4. Pivot and ring must be concentric with each other.

IX. Procedure

1. Place the Universal Force Table on firm platform.
2. Make the circular disc in horizontal position with the help of boots crews.
3. Check the horizontal position of circular disc by spirit level
4. Clamp the three detachable pulleys to the circular disc at three different positions.
5. Keep the ring at the centre of disc and pass the other ends of each string over the three pulleys.
6. Hang three hangers to these ends of strings passing over the pulleys.

7. Put slotted weights to each hanger so as to make pivot and ring concentric with each other.
8. Note the sum of slotted weights in each hanger and weight of hanger as three forces F1, F2,F3.
9. Measure the angles included between the two adjacent pulleys andnote them as $\theta_1, \theta_2, \theta_3$.
10. Record these observations in table.
11. Repeat step (7) by changing one or two pulleys position and take two sets ofobservation.

X. Observation table

Sr.No	Force(N)			Angle(Degree)			Ratio		
	P	Q	R	α	B	γ	$P/\sin \alpha$	$Q/\sin \beta$	$R/\sin \gamma$
1									
2									
3									
4									
5									

XI. Result(s)

Ratios $P/\sin \alpha, Q/\sin \beta, R/\sin \gamma$ are(Equal/Nearly equal/Not equal).

XII. Interpretation of results

If the ratio of force to the sin of opposite angle remains constant then the third observed equilibrant force is correct.

XIII. Conclusions and recommendation

.....

XIV. Practical related questions

Note: Below given are few sample questions for reference. Teachers must design more such questions so as to ensure the achievement of identified CO.

1. Define Lamis theorem.
2. Give the Practical Example where Lamis theorem is used.
3. State limitations of Lamis theorem.

SPACE TO WRITE ANSWERS

.....

Sr. No.	Link	Description
1.	https://youtu.be/qYhhWHIIkLY?si=OvTv02X9NYIV1xOd	Application of Lamis theorem

XVI. Suggested Assessment Scheme

Performance Indicators		Weightage (%)
Process related: 15 Marks		60 %
1	Handling of force table.	5 %
2	Application of different weight at different location.	15 %
3	Observation of weight in hanger and included angles.	5 %
4	Measuring of weights in hangers and included angles.	15 %
5	Calculation of third equilibrant force	15 %
6.	Working in team.	5 %
Product related: 10 Marks		40 %
1	Error estimation.	5 %
2	Interpretation of result and graph.	10 %
3	Conclusion and Recommendation.	10 %
4	Answer to the practical related questions.	10 %
5	Submission of report in time.	5 %
Total: 25 Marks		100 %

List of Student team members.

1.
2.
3.
4.

Marks Obtained			Dated sign of Teacher
Process Related(15)	Product Related(10)	Total(25)	

Practical No.17: Determine support reactions of simply supported beam using parallel forces of beam reaction apparatus for given vertical forces**I. Practical significance**

A simply supported beam is one whose ends are resting freely on two supports that provide only vertical reaction. Typical practical applications of simply supported beams with point loadings include bridges, beams and beds of machine tools.

II. Industry / Employer Expected Outcome(s)

After Studying this Practical Students will be able to find support reactions of beam which further use for analysis of beam.

III. Course Level Learning Outcome(s)

CO3 - Determine unknown force(s) of given load combinations in the given situation.

IV. Laboratory Learning Outcome(s)

Analyse the given force system acting on structural element.

V. Relevant Affective Domain related Outcome(s)

- a. Follow safety practices.
- b. Demonstrate working as a leader/a team member.
- c. Maintain tools and equipment

VI. Relevant Theoretical Background (with diagrams if required)

The beam is said to be simply supported beam when only vertical reaction, at supports exist. In this experiment this condition is achieved by applying only vertical forces.

The test is based on the ‘**Principle of Moments.**’ It states that if a system of coplanar forces acts on a rigid body, and the body remains in equilibrium despite the forces being acted upon, the summation of all the vertical forces acting on the body is zero, the summation of all the horizontal forces is zero and the algebraic sum of their moments at any point inside the plane is also zero. Mathematically, Mathematically: The body will be in equilibrium, if

$\Sigma H = 0$ i.e. the algebraic sum of all horizontal forces is zero.

$\Sigma V = 0$ i.e. the algebraic sum of all Vertical forces is zero.

$\Sigma M = 0$ i.e. the algebraic sum of all moments about a point is zero.

Parallel force apparatus to find support reaction of a simply supported beam meter scale, weights etc. The apparatus consists of a graduated wooden beam supported at its ends on spring balance OR Dial type balance. The balance facilitates to read the reaction due to applied loads directly. The detachable hangers hold the desired load resting in the grooves.

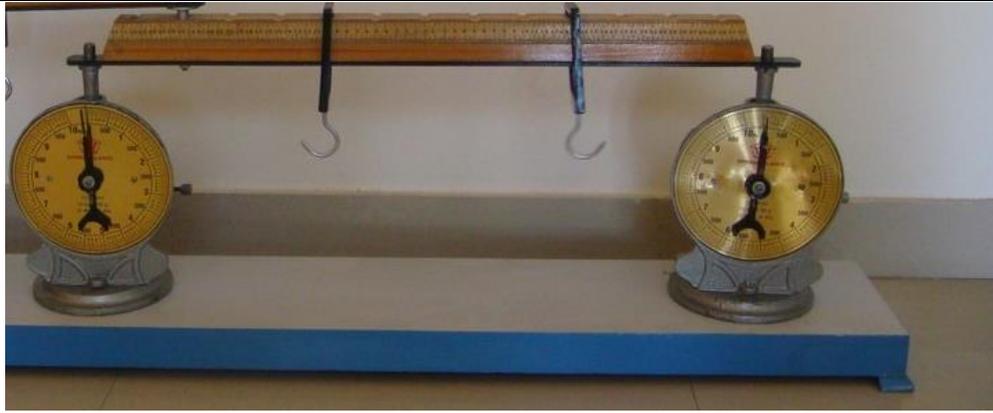


Fig. Beam apparatus

VII. Required Resources/apparatus/equipment with specifications

Sr.No	Particulars	Specification	Quantity	Remark
1	Beam apparatus	1000mm long beam with Scale fitted along length.	01 for Group of 4 to5 student	
2	Force measuring Dials	Laest count:100gm Max:10kg	2Nos	
3	Measuring weights	500gms	3Nos. 3Nos	
4	Load Hangers	1000gms	3Nos.	

VIII. Precautions to be followed

1. Dials to be set to zero before loading the beam.
2. Measure the Distance accurately.
3. Hangers should be sit in the grooves properly.

IX. Procedure.

1. Keep the Beam Reaction Apparatus on the table.
2. Note down the initial reading of parallel force apparatus both left &right.
3. For one point load put one weight hanger and attach some weight to the weight hanger.
4. Note down the weight attach and its distance from left support and reading of compression balance both left and right.
5. For two point load attach two weight hanger at any point and note down the weight its distance from left support and reading of compression balance both left and right.
6. For three point load attach three weight hanger at any point and note down the weight its distance from left support and reading of compression balance both left and right.
7. Find the experimental value of reaction of the support by subtracting the initial reading of compression balance from the final reading.

8. Also find reaction by applying condition of equilibrium. Summation of $F_y=0$, summation of $M=0$
9. Compare the experimental and theoretical value of support reaction

X. Observation table

Sr.No	Load W1(N)	Load W2(N)	Distance X1(mm)	Distance X2(mm)	Observed Reactions		Analytical Reactions	
					R _A (N)	R _B (N)	R _A (N)	R _B (N)
1								
2								
3								
4								
5								

XI. Result(s)

1. Observed Reaction R_A and Analytical Reaction R_A
(Equal/Nearly equal/Not equal)
2. Observed Reaction R_B and Analytical Reaction R_B
(Equal/Nearly equal/Not equal)

XII. Interpretation of results

.....

XIII. Conclusions and recommendation

.....

XIV. Practical related questions.

Note: Below given are few sample questions for reference. Teachers must design more such questions so as to ensure the achievement of identified CO. Write answers of minimum three questions.

1. State different types of supports.
2. Explain types of beam with diagram.
3. Define the term Support reaction.
4. State the two situations in field where simply supported beams are used.

Sr. No.	Link	Description
1.	https://www.youtube.com/watch?v=tM5hsUiNpGA	Calculation of beam reactions for various types of beams

XVII. Suggested Assessment Scheme

Performance Indicators		Weightage (%)
Process related: 15 Marks		60 %
1	Handling of force table.	5 %
2	Application of different weight at different location.	15 %
3	Observation of weight in hanger and included angles.	5 %
4	Measuring of weights in hangers and included angles.	15 %
5	Calculation of third equilibrant force	15 %
6.	Working in team.	5 %
Product related: 10 Marks		40 %
1	Error estimation.	5 %
2	Interpretation of result and graph.	10 %
3	Conclusion and Recommendation.	10 %
4	Answer to the practical related questions.	10 %
5	Submission of report in time.	5 %
Total: 25 Marks		100 %

List of Student team members.

1.
2.
3.
4.

Marks Obtained			Dated sign of Teacher
Process Related(15)	Product Related(10)	Total(25)	

Practical No.18: Determine coefficient of friction using friction apparatus for given block on horizontal plane

I. Practical significance

Friction is defined as resistive force offered by the surfaces that are in contact. When we kick a football it rolls for some distance and after that it stops after rolling for some time. This is because of the friction force between the ground and the ball. In this case force that is acting opposite to the motion of the ball and stops the ball is called the friction. Due to friction human can easily walk on surface without slipping. When a body is dragged along the rough plane friction force is more as compare to smooth surface because there is less interlocking between smooth surfaces Friction is very helpful in our daily activities like walking, running. Hence life would be very difficult without friction.

II. Industry / Employer Expected Outcome(s)

Student will be able to apply the knowledge of frictional forces in automobile industries (braking system brings the vehicle to a stop). In construction industries (While making roads, runways and highways) etc.

III. Course Level Learning Outcome(s)

CO4-Apply the laws of friction in the given situation.

IV. Laboratory Learning Outcome(s)

Verify laws of forces related to forces.

V. Relevant Affective Domain related Outcome(s)

- a. Follow safety practices.
- b. Demonstrate working as a leader/a team member.
- c. Maintain tools and equipment.

VI. Relevant Theoretical Background (with diagrams if required)

When there is a motion or tendency of motion between two surfaces in contact the Friction exists. The frictional force is opposite to the motion. In some practical situations the friction is required to reduce using lubrication. When the force causes the motion increases, the frictional force is also increased proportionately. Hence when the both are at the point of motion the frictional force is Maximum. This friction is known as Limiting Friction.

Normal Reaction(R): The reaction which is right angle to the plane of motion is called as normal reaction.

Coefficient of friction (μ): Is defined as ratio of limiting friction to normal reaction.

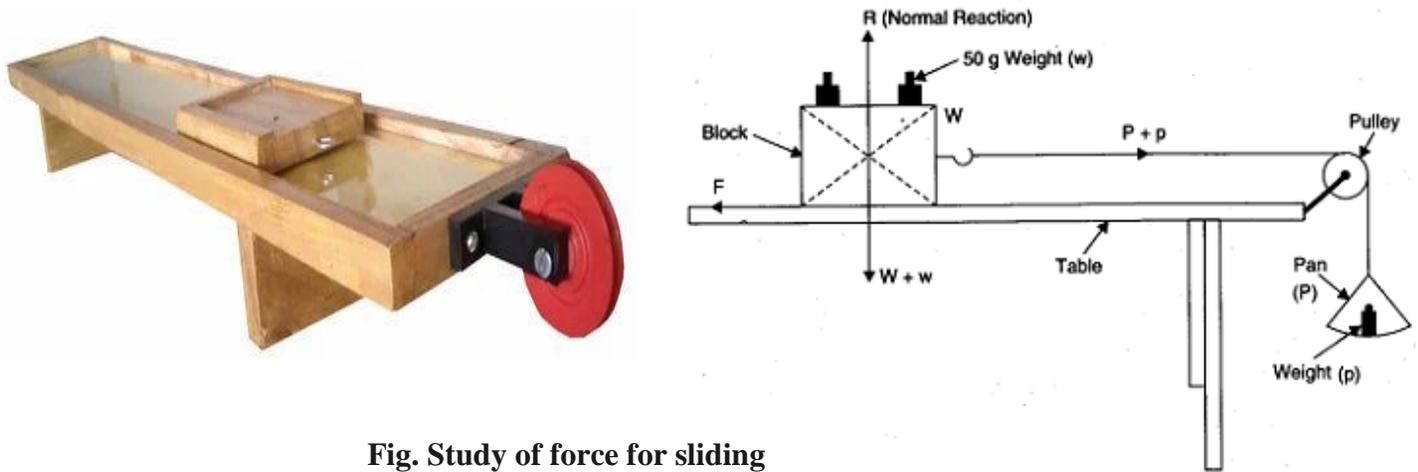


Fig. Study of force for sliding

VII. Required Resources/apparatus/equipment with specifications

Sr.No	Particulars	Specification	Quantity	Remark
1	Adjustable inclined plane	Wooden make with protractor fitted to it for measurement of angle of inclination. A frictionless pulley fitted at its free end	One for Group of 4to5 students	
2	Block	Hollow wooden block with bottom fitted with different material sheets such aaluminum,brass,copper,plywoodetc	One each	
3	Standard weight	Measuring 100,500and 1000gms a fractional weight box	Two each	
4	Inextensible string with pan	1m long tied to the block at one end and pan at the other	One for each block	

VIII. Precautions to be followed

1. The plane should be clean and smooth
2. The load and effort should move slowly.
3. The thread should be free from knots.
4. Pulley should be frictionless.
5. Efforts must be applied gradually
6. String should be knot free.

IX. Procedure.

1. Keeps the plane horizontal using sprit level.

2. Weight the box place the box on the surface of the frictional apparatus.
3. Attach a piece of string to the box and pass it over the pulley. At the other end of the string attach a pan.
4. Put some weight in the pan gently till the box is just at the point of motion. Note down the total weight in the pan.
5. Total hanging mass and its weight (P) and total mass of block with weight (w)
7. Add some weight in the box and repeat the above steps.
8. Take at least 6 readings of weight in box and the weights in pan.
9. Repeat the process with different set of surface in contact.

X. Observation table

Sr.No	Surface in contact	Load W (N)	Effort P (N)	Force of Friction F=P(N)	Normal Reaction R=W(N)	Coefficient of Friction $\mu=F/R$	Average μ
1							
2							
3							
4							
5							
6							

XI. Result(s)

1. The average value of coefficient of static friction for surface in contact.
 - a)and.....(μ)=.....

XII. Interpretation of results

Coefficient of friction for a pair of surfaces in contact..... and is more/less than that for.....and.....

XIII. Conclusions and recommendation

.....

.....

XIV. Practical related questions

Note: Below given are few sample questions for reference. Teachers must design more such questions so as to ensure the achievement of identified CO. Write answers of minimum three questions.

XVIII. Suggested Assessment Scheme

Performance Indicators		Weightage (%)
Process related: 15 Marks		60 %
1	Handling of force table.	5 %
2	Proper determination and applying of effort.	15 %
3	Observation of motion.	10 %
4	Calculation of parameters concerned.	10 %
5	Determination of coefficient of friction.	15 %
6.	Working in team.	5 %
Product related: 10 Marks		40 %
1	Error estimation.	5 %
2	Interpretation of result and graph.	10 %
3	Conclusion and Recommendation.	10 %
4	Answer to the practical related questions.	10 %
5	Submission of report in time.	5 %
Total: 25 Marks		100 %

List of Student team members.

1.
2.
3.
4.

Marks Obtained			Dated sign of Teacher
Process Related(15)	Product Related(10)	Total(25)	

Practical No.19: Determine coefficient of friction using friction apparatus for given block on inclined plane.**I. Practical significance**

Friction is defined as resistive force offered by the surfaces that are in contact. When we kick a football it rolls for some distance and after that it stops after rolling for some time. This is because of the friction force between the ground and the ball. In this case force that is acting opposite to the motion of the ball and stops the ball is called the friction. Due to friction human can easily walk on surface without slipping. When a body is dragged along the rough plane friction force is more as compare to smooth surface because there is less interlocking between smooth surfaces Friction is very helpful in our daily activities like walking, running. Hence life would be very difficult without friction.

II. Industry / Employer Expected Outcome(s)

Student will be able to apply the knowledge of frictional forces in automobile industries (braking system brings the vehicle to a stop). In construction industries (While making roads, runways and highways) etc.

III. Course Level Learning Outcome(s)

CO4-Apply the laws of friction in the given situation

IV. Laboratory Learning Outcome(s)

Verify laws of forces related to forces.

V. Relevant Affective Domain related Outcome(s)

- a. Follow safety practices.
- b. Demonstrate working as a leader/a team member.
- c. Maintain tools and equipment.

VI. Relevant Theoretical Background (with diagrams if required)

When there is a motion or tendency of motion between two surfaces in contact the Friction exists. The frictional force is opposite to the motion. In some practical situations the friction is required to reduce using lubrication. When the force causes the motion increases, the frictional force is also increased proportionately. Hence when the both are at the point of motion the frictional force is Maximum. This friction is known as Limiting Friction. Normal Reaction(R): The reaction which is right angle to the plane of motion is called as normal reaction. Coefficient of friction (μ): Is defined as ratio of limiting friction to normal reaction. The frictional force also depends on the type of relative motion between the two surfaces in contact. The motion can be either sliding or rolling. On the basis of motion, the friction is referred as either a sliding or rolling friction.



Fig. Motion on Inclined Plane

VII. Required Resources/apparatus/equipment with specifications

Sr.No	Particulars	Specification	Quantity	Remark
1	Adjustable inclined plane	Wooden make with protractor fitted to it for measurement of angle of inclination. A frictionless pulley fitted at its free end	One for Group of 4to5 students	
2	Block	Hollow wooden block with bottom fitted with different material sheets such aaluminum,brass,copper,plywoodetc	One each	
3	Standard weight	Measuring 100,500and 1000gms a fractional weight box	Two each	
4	Inextensible string with pan	1m long tied to the block at one end and pan at the other	One for each block	

VIII. Precautions to be followed

1. The plane should be clean and smooth.
2. The load and effort should move slowly.
3. The thread should be free from knots.
4. Pulley should be frictionless.
5. Efforts must be applied gradually.
6. String should be knot free.

IX. Procedure.

1. Place the Apparatus on table and make sure that base of the inclined plane is at horizontal surface.
2. Bring the inclined plane to the horizontal position so that the angle of inclination is zero. After that Set the apparatus at desired angle.

3. Put a block on surface whose co-efficient of friction is required to be found, at the lower end of inclined plane connect the block with a string which will pass over the frictionless pulley connect the pan to it.

4. Put a limiting value of weight which will cause a uniform upward sliding of the surface block. Record angle, weight of pan as (P) weight of box and weight in box (W).

5. Increase the inclination angle, fixed value of weight pan and vary the weight in box place on surface so that the minimum value of weight in the box may cause uniform motion of the box down the plane Record angle, Total weight of pan as (P) weight of box and weight in box (W).

6. Repeat the above steps for box with different surface.

X. Observation table

Sr.No	Surface in contact	Inclination of plane	Load W (N)	Effort P (N)	Sin θ	Cos θ	Coefficient of Friction μ	Average μ
1								
2								
3								
4								
5								
6								

Draw FBD

a) Body just sliding down the inclined plane.

b) Body just sliding up the inclined plane.

Sample Calculation.

a) Body just sliding down the inclined plane.

$$\mu = \frac{W \sin\theta - P}{W \cos\theta}$$

Sr. No.	Link	Description
1.	https://www.youtube.com/watch?v=RGT1g_lu440	Calculation of coefficient of friction for horizontal and inclined plane

XIX. Suggested Assessment Scheme

Performance Indicators		Weightage (%)
Process related: 15 Marks		60 %
1	Handling of force table.	5 %
2	Proper determination and applying of effort.	15 %
3	Observation of motion.	10 %
4	Calculation of parameters concerned.	10 %
5	Determination of coefficient of friction.	15 %
6.	Working in team.	5 %
Product related: 10 Marks		40 %
1	Error estimation.	5 %
2	Interpretation of result and graph.	10 %
3	Conclusion and Recommendation.	10 %
4	Answer to the practical related questions.	10 %
5	Submission of report in time.	5 %
Total: 25 Marks		100 %

List of Student team members.

1.
2.
3.
4.

Marks Obtained			Dated sign of Teacher
Process Related(15)	Product Related(10)	Total(25)	

Practical No.20: Verify centroid of plane figure of given dimensions by making simple paper model

I. Practical significance

We use various types of shapes, lamina, composite bars/wires in the constructions, in machines and mechanisms for different purposes. Specific shape is chosen for cross section of a beam, column and other structural member. One of the most important geometric property of the shapes is center of gravity or centroid. The plane figure like circle triangle square has only area, but no mass. The centre of area of plane figure is known as centroid.

II. Industry / Employer Expected Outcome(s)

Apply the principles of engineering mechanics to find out centroid of different structural cross-section such as Beam, Column, Dam and Retaining wall etc.

III. Course Level Learning Outcome(s)

Determine the centroid/centre of gravity of the structural elements of having specific shape and size.

IV. Laboratory Learning Outcome(s)

Apply the concept of centroid for given objects.

V. Relevant Affective Domain related Outcome(s)

- Follow safety practices.
- Demonstrate working as a leader/a team member.
- Maintain tools and equipment.

VI. Relevant Theoretical Background (with diagrams if required)

Centre of gravity: The centre of gravity of a body is that point through which the resultant of the system of parallel forces formed by the weights of all the particles of the body passes. for all positions of the body.

Centre of Mass: The point at which the whole mass of a body is supposed to be concentrated is known as centre of mass.

Centroid: Is is the point at which whole area of the body is supposed to be concentrated.

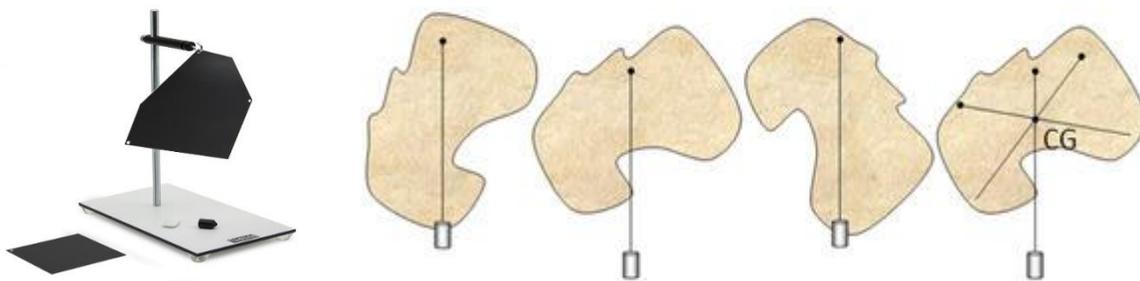


Fig. Step wise location of centroid with the help of centre of mass

VII. Required Resources/apparatus/equipment with specifications

Sr.No	Particulars	Specification	Quantity	Remark
1	Sheet of paper / Hardboard		01 for each shape	
2	Scissor/cutter		01 for batch of 3 to4 students	
3	Plumb bob with string		01 for batch of 3 to4 students	
4	Marker pen		01 for batch of 3 to4 students	

VIII. Precautions to be followed

1. Line should be connected to each other accurately.
2. Drawing errors should be reduced to minimum so as to get correct results.

IX. Procedure.

1. Draw any shape on sheet of hard board. And mark holes on a Shape.
2. Hang that shape on a peg through the desire hole.
3. Hang a plumb bob and mark plumb line with marker.
4. Repeat same procedure for other holes.
5. Mark the point of intersection of these lines this point gives the centroid of that lamina by experimentally.
6. Also calculate the center of gravity of that plane lamina by analytically.

X. Observation table

Sr.no	Shape	Dimensions (mm)			X- Coordinate(mm)	Y- Coordinate(mm)
1	Square					
2	Rectangle					
3	Triangle					
4	Circle					
5	Semicircle					
6	Trapezium					

XVI. Suggested Assessment Scheme

Performance Indicators		Weightage (%)
Process related: 15 Marks		60 %
1	Handling of force table.	5 %
2	Keeping the plumb line vertical.	10%
3	Marking of line on plane lamina.	10 %
4	Determination of centroid of geometrical shapes.	10 %
5	Analytical calculation of centroid.	20 %
6.	Working in team.	5 %
Product related: 10 Marks		40 %
1	Error estimation.	5 %
2	Interpretation of result and graph.	10 %
3	Conclusion and Recommendation.	10 %
4	Answer to the practical related questions.	10 %
5	Submission of report in time.	5 %
Total: 25 Marks		100 %

List of Student team members.

1.
2.
3.
4.

Marks Obtained			Dated sign of Teacher
Process Related(15)	Product Related(10)	Total(25)	